

1           **Thermal fatigue as a driving mechanism for activity on asteroid Bennu**

2 **J. L. Molaro<sup>1</sup>, C. W. Hergenrother<sup>2</sup>, S. R. Chesley<sup>3</sup>, K. J. Walsh<sup>4</sup>, R. D. Hanna<sup>5</sup>, C. W.**  
3 **Haberle<sup>6</sup>, S. R. Schwartz<sup>2</sup>, R.-L. Ballouz<sup>2</sup>, W. F. Bottke<sup>4</sup>, H. J. Campins<sup>7</sup>, and D. S.**  
4 **Lauretta<sup>2</sup>**

5 <sup>1</sup>Planetary Science Institute, Tucson, AZ, USA. <sup>2</sup>Lunar and Planetary Laboratory, University of  
6 Arizona, Tucson, AZ, USA. <sup>3</sup>Jet Propulsion Laboratory, Caltech Institute of Technology.  
7 <sup>4</sup>Southwest Research Institute, Boulder, CO, USA. <sup>5</sup>Jackson School of Geosciences, University of  
8 Texas, Austin, TX, USA. <sup>6</sup>School of Earth and Space Exploration, Arizona State University.  
9 <sup>7</sup>University of Central Florida, Orlando, FL, USA.

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11 **Key Points:**

- 12       • We simulated stress fields in boulders to assess the nature and efficacy of thermal  
13       breakdown on Bennu, including by exfoliation.
- 14       • Our model predicts that exfoliation is capable of ejecting centimeter-scale particles from  
15       the asteroid at speeds of meters per second.
- 16       • This mechanism is consistent with observations of particle ejection at Bennu and is a  
17       viable explanation for Bennu's activity.

## 1 **Abstract**

2 Many boulders on (101955) Bennu, a near-Earth rubble pile asteroid, show signs of *in situ*  
3 disaggregation and exfoliation, indicating that thermal fatigue plays an important role in its  
4 landscape evolution. Observations of particle ejections from its surface also show it to be an active  
5 asteroid, though the driving mechanism of these events is yet to be determined. Exfoliation has  
6 been shown to mobilize disaggregated particles in terrestrial environments, suggesting that it may  
7 be capable of ejecting material from Bennu's surface. We investigate the nature of thermal fatigue  
8 on the asteroid, and the efficacy of fatigue-driven exfoliation as a mechanism for generating  
9 asteroid activity, by performing finite element modeling of stress fields induced in boulders from  
10 diurnal cycling. We develop a model to predict the spacing of exfoliation fractures, and the number  
11 and speed of particles that may be ejected during exfoliation events. We find that crack spacing  
12 ranges from ~1 mm to 10 cm and disaggregated particles have ejection speeds up to ~2 m/s.  
13 Exfoliation events are most likely to occur in the late afternoon. These predictions are consistent  
14 with observed ejection events at Bennu and indicate that thermal fatigue is a viable mechanism for  
15 driving asteroid activity. Crack propagation rates and ejection speeds are greatest at perihelion  
16 when the diurnal temperature variation is largest, suggesting that events should be more energetic  
17 and more frequent when closer to the Sun. Annual thermal stresses that arise in large boulders may  
18 influence the spacing of exfoliation cracks or frequency of ejection events.

## 20 **Plain Language Summary**

21 Soon after its rendezvous with the asteroid Bennu, the OSIRIS-REx spacecraft observed the  
22 asteroid to be ejecting tiny particles of material. Bennu is a rubble-pile asteroid covered in boulders  
23 of varying size. Many of these boulders show evidence of exfoliation, a process where thin layers  
24 of material are shed from their surfaces. Exfoliation is one consequence of thermal fatigue, which  
25 is the slow and progressive lengthening of cracks caused by the daily variation in boulder  
26 temperature from exposure to the Sun. Here we explore how thermal fatigue may cause the  
27 degradation and fracturing of boulders on Bennu and how the specific process of exfoliation could  
28 lead to the ejection of particles from the asteroid surface. We develop a model to predict the timing,  
29 number, and speeds of particles that may be ejected during exfoliation events, and compare our  
30 results to the spacecraft observations of the ejection events from Bennu's surface. Our results  
31 suggest that particles ejected from boulder surfaces during exfoliation can have speeds up to ~2  
32 m/s and are most likely occur when Bennu is closest to the Sun and during the late afternoon,  
33 consistent with spacecraft observations.

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## 1 **1 Introduction**

2 Observations of 101955 Bennu by the Origins, Spectral Interpretation, Resource Identification,  
3 and Security–Regolith Explorer (OSIRIS-REx) spacecraft have revealed a rough surface  
4 dominated by boulders with diverse morphologies and textures [*DellaGiustina and Emery et al.*,  
5 2019; *Walsh et al.*, 2019; *Lauretta and DellaGiustina et al.*, 2019]. Signs of *in situ* bulk  
6 degradation, mass movement, craters, and visible fractures hint that its surface is influenced by a  
7 variety of weathering, impact, and other processes [*Barnouin et al.*, 2019; *DellaGiustina and*  
8 *Emery et al.*, 2019; *Walsh et al.*, 2019]. Although dedicated searches for asteroid activity during  
9 the spacecraft’s approach detected none [*Hergenrother et al.*, 2019], navigational images taken  
10 from orbit have also unexpectedly revealed that Bennu has an active surface [*Lauretta and*  
11 *Hergenrother et al.*, 2019]. Multiple particle ejection events were observed starting in January  
12 2019, shortly after the OSIRIS-REx spacecraft entered orbit, characterized as bursts of centimeter-  
13 scale and smaller particles leaving the asteroid surface. The two largest events occurred near  
14 asteroid perihelion, with numerous smaller events observed in the months following [*Lauretta and*  
15 *Hergenrother*, 2019; *Hergenrother et al.*, *in review this collection*; *Leonard et al.*, *in press*; *Pelgrift*  
16 *et al.*, 2020]. Several mechanisms have been suggested to drive these ejection events, including  
17 electrostatic lofting of particles [*Hartzell*, *in review this collection*], meteoroid impacts [*Bottke*, *in*  
18 *review this collection*], phyllosilicate dehydration, and thermal fracturing [*Lauretta and*  
19 *Hergenrother*, 2019]. This work focuses on the lattermost mechanism, exploring its efficacy on  
20 Bennu’s surface and possible contribution to ejection events.

21 Many of Bennu’s boulders show signs of exfoliation, the flaking and disaggregation of thin  
22 layers of surface material. Recent work by Molaro et al. [2020] has demonstrated that these  
23 features on Bennu result from thermal fatigue, a subcritical crack growth process driven by diurnal  
24 thermal cycling [e.g., *Holzhausen*, 1989]. Previously, we lacked morphological evidence that  
25 fatigue could operate on airless body surfaces, though numerous studies had hypothesized that it  
26 may play an important role [e.g., *Dombard et al.*, 2010; *Jewitt and Li*, 2010; *Delbo et al.*, 2014].  
27 Although models [*Molaro et al.*, 2015; *Hazeli et al.*, 2018; *El Mir et al.*, 2019] and laboratory  
28 investigations [*Thirumalai and Demou*, 1970; *Levi*, 1973; *Delbo et al.*, 2014] have provided  
29 valuable insight into its nature, the opportunity to study fatigue *in situ* on Bennu’s surface provides  
30 new pathways for understanding how it drives landscape evolution and interacts with other surface  
31 processes such as micrometeoroid impacts. In terrestrial environments, fatigue often works in  
32 synergy with various chemical and biogenic weathering processes to drive boulder breakdown  
33 [*Waragai*, 1998; *McFadden et al.*, 2005; *Fletcher et al.*, 2006; *Eppes et al.*, 2010; *Eppes and*  
34 *Keanini*, 2017; *Lamp et al.*, 2017]. At very large scales, exfoliation of terrestrial rock domes is  
35 attributed to weakening of the rock via thermal fatigue, followed by critical failure due to  
36 compressive stresses from regional and/or seasonal thermal sources [*Martel*, 2011; *Collins and*  
37 *Stock*, 2016; *Martel*, 2017; *Collins et al.*, 2018; 2019]. These spontaneous bursts of crack growth  
38 are observed to cause the release of audible acoustic waves and mobilization of particles off the  
39 dome surface [*Collins et al.*, 2018; 2019]. Although the large scale of the stresses in these events  
40 are thought to add significant energy, this leads to the question of whether fatigue-driven, boulder-  
41 scale exfoliation may be capable of ejecting material from an asteroid surface, where less energy  
42 would be needed due to the microgravity environment. If so, this has important implications for  
43 our understanding of asteroid geology and the active asteroid population.

44 Here we investigate the nature of thermal fatigue on Bennu’s surface and the efficacy of  
45 fatigue-driven exfoliation as a mechanism for generating asteroid activity. Following the  
46 description of the finite element model (Section 2), the paper has two primary focuses: (i)

1 describing boulder breakdown on Bennu and (ii) assessing its potential to cause asteroid activity  
2 (particle ejection). In Section 3, we perform modeling of stress fields induced in Bennu’s boulders  
3 from diurnal thermal cycling to explore how thermal fatigue may drive the development of  
4 fractures and boulder morphologies observed on the asteroid surface. We compare our results to  
5 similar analyses done for terrestrial [Eppes *et al.*, 2016; Lamp *et al.*, 2017] and lunar [Molaro *et*  
6 *al.*, 2017] boulders, and studies that quantify scaling laws for estimating stress magnitudes and  
7 resurfacing rates on arbitrary asteroid surfaces [El Mir *et al.*, 2019; Graves *et al.*, 2019; Ravaji *et*  
8 *al.*, 2019], providing new insight into the efficacy of fatigue on carbonaceous chondrite materials  
9 and its expression on lunar versus asteroid surfaces. Section 3.2 describes the specific process of  
10 fatigue-driven exfoliation, which is then expanded upon in Sections 4 and 5 to explore how it may  
11 contribute to asteroid activity. In Section 4, we develop a model to predict the spacing of  
12 exfoliation fractures and the size and speed of particles that may be ejected from Bennu’s surface  
13 during an exfoliation event, and in Section 5 we compare our results to observational constraints  
14 from Bennu’s particle ejection events to assess the likelihood that thermal fatigue is their driving  
15 mechanism. All references to exfoliation in this text refer to exfoliation fully or partially driven by  
16 thermal fatigue, unless explicitly stated.  
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## 18 **2 Finite Element Model**

19 Following Molaro *et al.* [2020], we used COMSOL Multiphysics to perform finite element  
20 modeling of stress fields in three-dimensional spherical boulders on the surface of Bennu, with  
21 diameters ranging from 0.2 to 6 m. In each case, the boulder was embedded in unconsolidated  
22 regolith such that its lower half was buried. The regolith volume had sides which were fixed with  
23 respect to displacement and periodic with respect to temperature. The lower boundary had a net  
24 heat flux of zero and was fixed. The shared boundary between the regolith and boulder had a heat  
25 flux determined by the effective thermal conductivity of the two materials. This shared boundary,  
26 as well as the unburied boulder and regolith surfaces, were free to move in response to thermal  
27 forcing. Incident solar radiation was applied to unburied surfaces by adjusting the time-dependent  
28 solar position and distance computed using the NAIF (Navigation and Ancillary Information  
29 Facility) SPICE (spacecraft, planet, instrument, constants, and events) Toolkit. The coordinates  
30 were computed at an equatorial location over one solar day at Bennu’s perihelion. The model takes  
31 into account the local surface slope and orientation of individual mesh elements, scattered and  
32 exchanged radiation from surrounding elements, and the size of the solar disc during a local sunrise  
33 or sunset.

34 The boulders were assumed to have the bulk properties of terrestrial serpentinite (Table 1),  
35 as the closest spectral matches to Bennu’s surface are aqueously altered CM carbonaceous  
36 chondrites [Hamilton *et al.*, 2019], which are composed primarily of serpentine-group  
37 phyllosilicates [Howard *et al.*, 2009]. We simulated both “dense” and “porous” boulders, with  
38 properties representing each end of serpentinite’s range of porosities (10 to 35%, respectively).  
39 This porosity range may represent compositional or structural differences in the rock due to its  
40 formation, or due to subsequent accumulation of damage. The properties associated with the  
41 porous boulders are comparable to measurements of the thermophysical properties of CM  
42 chondrites and other possible Bennu analogs [Opeil *et al.*, 2010; Macke *et al.*, 2011; Horai, 2012].  
43 The difference in stress magnitude observed between dense and porous simulations is due  
44 primarily to the change in Young’s modulus as a result of increased porosity, as the thermophysical  
45 properties have only a weak (up to a few percent) influence on the results [Molaro *et al.*, 2017].

1 The thermophysical properties of the regolith were determined by ensuring that the effective  
 2 thermal inertia of the combined regolith and boulder surfaces matches that of Bennu ( $350 \text{ J/m}^2 \text{ K}$   
 3  $\text{s}^{1/2}$ ) [DellaGiustina and Emery et al., 2019], and therefore that it realistically approximates the  
 4 asteroid's thermal environment. The regolith was assumed to have mechanical properties  
 5 comparable to lunar regolith such that it did not impose any confining pressure on the boulders.

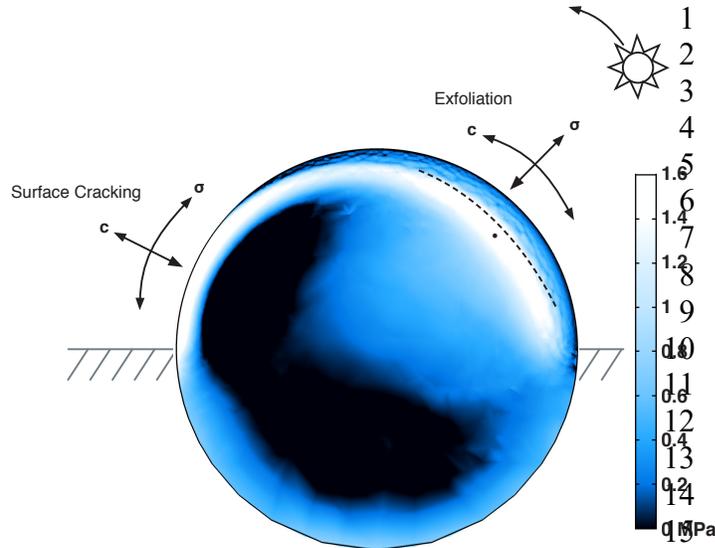
6 We then calculated the heat equation for heat transfer in solids in order to calculate the  
 7 temperature and stress fields within the boulders over time. A full description of the equations  
 8 solved by COMSOL for this calculation, as well as an expanded discussion of the model details,  
 9 justification for the material properties in Table 1, and information on model uncertainties can be  
 10 found in Molaro et al. [2020] and in Supporting Information Text–1. A discussion of the influence  
 11 of boulder shape and surface roughness on our results is included in Section 3.4 and Appendix A.  
 12

13 **Table 1.** Thermal and mechanical properties of simulated materials.

Property	Units	Dense <sup>a</sup> Boulders	Porous <sup>b</sup> Boulders	Regolith <sup>c</sup>	References
Density ( $\rho$ )	$\text{kg/m}^3$	2510	1812	1190	<sup>a</sup> [Christensen, 1966], <sup>c</sup> [Vasavada et al., 2012]
Thermal Conductivity ( $k$ )	$\text{W/m K}$	2.5	0.5	<sup>a</sup> 0.076, <sup>b</sup> 0.125	<sup>a,b</sup> [Horai, 2012], <sup>b</sup> [Opeil et al., 2010], <sup>c</sup> [Vasavada et al., 2012]
Heat Capacity ( $c_p$ )	$\text{J/ kg K}$	$c_p(T)$	$c_p(T)$	$c_p(T)$	[Ledlow et al., 1992]
Albedo ( $A$ )		0.044	0.044	0.044	[DellaGiustina and Emery et al., 2019]
Young's Modulus ( $E$ )	GPa	35	15	$8 \times 10^{-3}$	<sup>a</sup> [Christensen, 1966], <sup>b</sup> [Burk, 1964], <sup>c</sup> [Colwell et al., 2007]
Poisson's Ratio ( $\nu$ )		0.34	0.05	0.4	<sup>a</sup> [Christensen, 1966], <sup>b</sup> [Burk, 1964], <sup>c</sup> [Colwell et al., 2007]
Coefficient of Expansion ( $\alpha$ )	$1/\text{K}$	$8 \times 10^{-6}$	$8 \times 10^{-6}$	$2.4 \times 10^{-4}$	<sup>a, b</sup> [McKinstry, 1965], <sup>c</sup> [Agar et al., 2006]

### 15 3 Model Results and Discussion

16 Before we can assess the contribution that thermal breakdown makes to asteroid activity, we use  
 17 our simulations to examine its general nature on Bennu's surface. The magnitude of stress fields  
 18 experienced by the boulders can be used to determine whether the threshold for crack propagation  
 19 is met. The model does not simulate crack propagation itself, but the orientation of the stress fields  
 20 informs where and when microcrack propagation tends to occur. The stress fields induced in  
 21 boulders undergoing thermal cycling are spatially and temporally complex. Tensile stresses arise  
 22 in different parts of the boulders at different times of day, and their orientation leads to crack  
 23 propagation in different directions. Although all of these stresses are part of the boulder's  
 24 continuous mechanical response to heating, it is helpful to think about certain effects as separate  
 25 stress fields that each contribute differently to the overall morphological evolution of boulder  
 26 shapes and sizes over time. Molaro et al. [2017] illustrated the three primary stress fields (Figure  
 27 1) induced by diurnal cycling in lunar boulders: deep interior stresses that drive through-going  
 28 fractures, near-surface stresses that drive surface-parallel fractures ("exfoliation"), and surface



**Figure 1.** Stress field in a cross section of a 2 m boulder at mid-morning, showing developing exfoliation stresses on the boulder’s east face and surface cracking stresses on its west face. Lines show the direction of stress ( $\sigma$ ) and cracking ( $c$ ). The dashed line shows the approximate exfoliation depth, and the dot is the approximate location maximum of the exfoliation stress field. The Sun moves from right to left in the plane of the image. Regions that are black have negative (compressional) stress.

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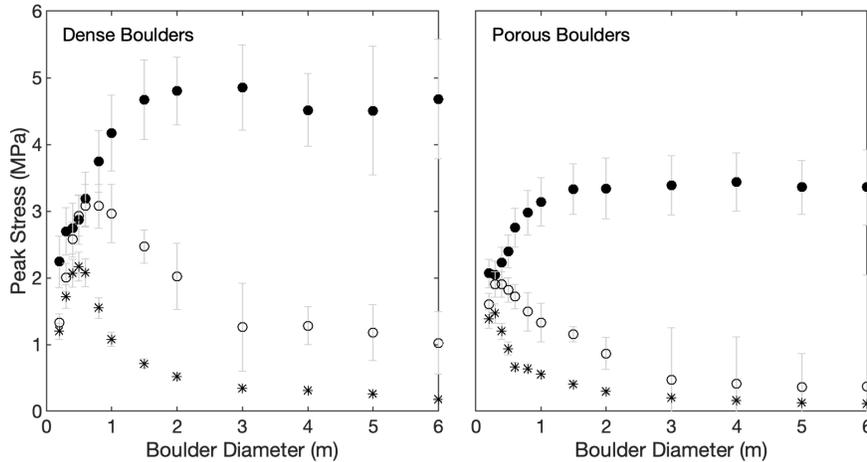
stresses that drive shallow surface-perpendicular fractures (“surface cracking”). We discuss each of these effects in the context of observations of Bennu’s boulders. Parameters from the simulations will also feed into the crack spacing and particle ejection model discussed in Section 4, which we relate to the observed particle ejection events at Bennu [Lauretta and Hergenrother *et al.*, 2019; Leonard *et al.*, *in press*]. We examine only boulder-scale effects in this work, but stresses induced at the mineral grain scale could also play a role in the distribution of microcracks that develop into larger-scale features [e.g., Molaro *et al.*, 2015; Hazeli *et al.*, 2018].

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### 26 3.1 Stress Magnitudes

27 To determine whether thermal fracturing may occur, we can quantify the magnitude of thermally  
28 induced stress in boulders, which is controlled by the amplitude of temperature variation they  
29 experience and their thermophysical and mechanical properties. Stresses are highest in dense,  
30 brittle materials that do not easily deform in response to thermal forcing, and each stress field  
31 varies differently with boulder size (Figure 2). Stresses in boulders that are more porous are weaker  
32 in magnitude, though their orientations remain unchanged. Surface stresses range from  $\sim 2$  to 5  
33 MPa, increasing with boulder diameter as a result of decreased surface curvature. Exfoliation and  
34 deep interior stresses are controlled by the size of the boulder with respect to the diurnal skin depth.  
35 They peak at a diameter of  $\sim 5\times$  the skin depth and decrease in larger boulders, ranging from  $\sim 0.4$   
36 to 3 MPa and  $\sim 0.2$  to 2 MPa for exfoliation and interior stresses, respectively. These are  
37 comparable to the tensile strengths of our terrestrial serpentinite analog (0.5 to 5 MPa) [Burk, 1964;  
38 Altindag *et al.*, 2010] and similar soft, anisotropic materials such as limestone and shale (1 to 12  
39 MPa) [Sanio, 1985; Chen *et al.*, 1998]. Even the weakest stresses are comparable to the estimated  
40 tensile strength of boulders on (162173) Ryugu (0.2 MPa) [Grott *et al.*, 2019], which is also a  
41 carbonaceous asteroid. Such conditions make it plausible for thermal fracture processes to be  
42 active at Bennu.

43 The most likely thermal fracture process to occur is fatigue, which, as a subcritical crack  
44 growth process, requires a stress lower than the material’s ultimate tensile strength in order to



**Figure 2.** Peak surface (solid circle), exfoliating (open circle), and deep interior (asterisks) stresses in dense (left) and porous (right) boulders of varying diameter. The error bars represent uncertainty due to mesh size and location of peak stress (see Supporting Information Text–1 and Molaro et al. [2020] for full details).

propagate cracks. Crack propagation models typically describe stress fields in terms of the stress intensity factor, a term that relates the stress around the tip of a crack to the macroscopic stress field [Lawn, 1993]. In terrestrial environments, the threshold to drive sub-critical crack growth requires a stress intensity factor that is  $\sim 10$  to 20% of the material’s fracture toughness [Atkinson, 1984]. To first order, surface-parallel microcracks can be approximated as cracks in an infinite medium, where the material’s fracture toughness is linearly proportional to its tensile strength [Emmerich, 2007]. Our results (Figure 2) show we have sufficient stress to overcome a threshold of 20% of the tensile strength, indicating that fatigue is likely to be active at Bennu. Observations of boulder morphologies on the surface are consistent with fatigue-driven exfoliation [Molaro et al., 2020]. On Earth, however, fatigue is typically aided by stress corrosion and other synergistic chemical weathering mechanisms [Fletcher et al., 2006; Aldred et al., 2016; Eppes and Keanini, 2017; Lamp et al. 2017], and studies have shown that crack propagation in vacuum can be harder to achieve [Krokosky and Husak, 1968; Thirumalai and Demou, 1970; Kranz, 1979]. This makes it unclear what threshold is needed to drive fatigue in asteroid environments, though better constraints on material strengths and fatigue thresholds will be enabled by analysis of the samples that OSIRIS-REx will return to Earth.

If Bennu’s materials are sufficiently weak, it is plausible that thermal shock processes [Walsh and Lomov, 2013; Browning et al., 2016; Thirumalai and Demou, 1970; Richter and Simmons, 1974], which occur when an object’s tensile strength is exceeded, could also drive crack propagation on Bennu. Such processes could have occurred during Bennu’s migration to near-Earth space as its surface materials normalized to a warmer thermal environment. However, the prevalence of boulders on the asteroid surface and the relative lack of finer material [DellaGiustina and Emery et al., 2019; Lauretta and DellaGiustina et al. 2019; Walsh et al., 2019] are not consistent with the rapid erosion rates associated with shock processes [Kendrick et al., 2016; Wang et al., 2016; Atkinson, 1984], which would break down boulders quickly over Bennu’s shortest predicted migration period [100 Myr; Walsh et al., 2019]. Any shock processes that occur today are likely limited to freshly exposed boulders faces, e.g., by mass movement or

1 impacts [Walsh et al., 2019]. Thus, we focus the remainder of our discussion on thermal fatigue,  
2 which we interpret to be a much more likely driver of rock breakdown on Bennu. The way in  
3 which subcritical growth via fatigue can lead to critical failure and energetic particle ejection is  
4 discussed in Sections 3.2 and 4.

5 The magnitude of diurnal stresses decreases with increasing solar distance (for a body with  
6 a given rotation rate) due to the reduction in insolation. Because fatigue crack propagation rates  
7 have a nonlinear relationship to stress [e.g., Lawn, 1993], this will cause variation in fatigue  
8 efficacy throughout the orbit, which adds complexity to estimating fracture development  
9 timescales using models [e.g., El Mir et al., 2019]. For a 1-m boulder on Bennu, the variation in  
10 stress with solar distance ( $s$ ) is approximately proportional to  $s^{-1.2}$ , which is consistent with  
11 previous models and scaling laws [Ravaji et al, 2019; Molaro et al., 2017]. For flat ground, a  
12 similar decrease in stress magnitude would occur with increasing latitude. However, due to its  
13 large-scale surface roughness, high (relative) diurnal temperature amplitudes occur at all latitudes  
14 on Bennu [Rozitis et al., 2020]. This suggests that fatigue does not necessarily occur more slowly  
15 at high latitudes, though it likely affects a smaller part of the boulder population. An overall  
16 decrease in fatigue efficacy with latitude would be more likely on an asteroid whose boulders are  
17 smaller in scale relative to the body's surface curvature. Compared to the equatorial boulders, the  
18 orientation of stress fields in boulders at non-equatorial latitudes is rotated relative to the direction  
19 of the Sun's path (Section 3.4 and Appendix A).

20 Overall, these stresses have lower absolute magnitudes than those reported by Molaro et  
21 al. [2017] for lunar boulders because the diurnal temperature variation on Bennu is smaller and the  
22 boulders have a lower Young's modulus. However, stresses in lunar boulders are an order of  
23 magnitude lower than their presumed tensile strength, and the lunar cycling rate is only 12  
24 cycles/year compared to Bennu's  $10^3$  cycles/year. Combined, these two factors suggest that  
25 thermal fatigue on the Moon happens more slowly than on Bennu. Recent works examining lunar  
26 boulder populations suggest that thermal fatigue is relevant in meter-scale boulders [Li et al.,  
27 2017], but overall is subordinate to impact processes in driving breakdown [Basilevsky et al., 2015;  
28 Ruesch et al., 2020]. There are currently no constraints on the relative rates of weathering by  
29 impacts and fatigue on Bennu. One notable difference between the two bodies is that lunar boulders  
30  $\sim 8\times$  the diurnal thermal skin depth (4 to 7 m) show a local maximum in the trend of stress with  
31 diameter [Molaro et al., 2017; their figure 10], which is distinct from where the peak exfoliation  
32 stress occurs ( $\sim 11\times$  the skin depth,  $\sim 9$  m). Boulders near this local maximum are predicted to break  
33 down most efficiently from thermal fatigue due to the strong heat flux emitted from their surfaces  
34 near sunset, in concert with the boulder size relative to the thermal skin depth. This effect is not  
35 present on Bennu because of its smaller temperature range, and instead stresses are dominated by  
36 boulder size and temperature gradients. Bennu's peak exfoliation stress also happens at a smaller  
37 relative boulder size ( $\sim 5\times$  its skin depth) than on the Moon. These factors highlight that the boulder  
38 population will evolve differently on different bodies as a result of thermal effects.

### 41 3.2 Exfoliation

42 Near-surface stresses lead to boulder exfoliation, which is observed widely at Bennu and likely to  
43 be driven by thermal fatigue [Molaro et al., 2020]. It is relevant to review how fatigue-driven  
44 exfoliation operates here because it is this mechanism which we propose leads to the observed

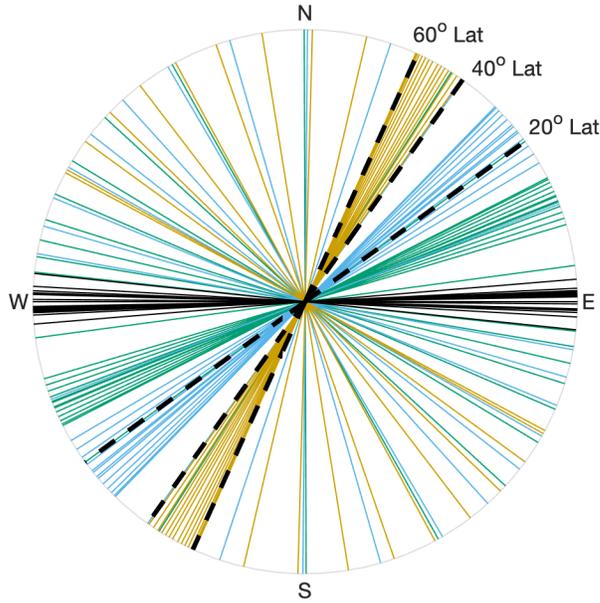
1 ejection of particles from Bennu’s surface. This discussion directly informs the crack spacing and  
2 particle ejection calculations performed in Section 4.

3 Exfoliation is driven by thermally induced stresses that arise in boulder near-surfaces  
4 during daytime heating [e.g., *Holzhausen, 1989; Martel, 2011; Molaro et al., 2017*], as illustrated  
5 in Figure 1, which shows the stress field on a cross section through a boulder at mid-morning. The  
6 boulder surface moves into a state of compression as it heats, causing a region of tension to develop  
7 in the near-surface associated with the spatial temperature gradient. As the Sun moves overhead,  
8 this tensile region expands westward and the location of its local maximum follows along a plane  
9 parallel to the boulder’s surface. These “exfoliation stresses” have a surface-normal orientation,  
10 pointing approximately in the Sun’s direction and driving microcrack propagation along surface-  
11 parallel planes. Over time, larger-scale fractures can develop as microcracks coalesce [*Jansen et*  
12 *al., 1993*], leading to the development of an exfoliation flake that separates from the boulder  
13 surface. Once it has begun to disaggregate, expansion and contraction of the flake itself can aid in  
14 lengthening the underlying crack [*Collins and Stock, 2016; Lamp et al., 2017*]. The rate at which  
15 crack propagation occurs increases as its length grows relative to the boulder size, and when it  
16 nears a boundary (e.g., boulder edge or material discontinuity) will transition abruptly from sub-  
17 critical to critical failure [e.g., *Janssen et al., 2002*]. This instantaneous, catastrophic disruption at  
18 the end of a fatigue crack’s life can cause disaggregation of all or part of the flake, and in terrestrial  
19 environments has been observed to result in rockfalls and mobilization of particles off the surface  
20 [*Collins and Stock, 2016; Collins et al., 2018; 2019*]. It is this mechanism which we hypothesize  
21 to cause ejection of particles from Bennu’s surface. In Section 4, we will quantify the available  
22 energy in these events that can go towards ejecting particles such events and estimate the particular  
23 sizes and speeds.

24 Terrestrial observations show that one or more surface-parallel fractures may develop  
25 within the exfoliation region [e.g., *Martel, 2017*], the spacing of which controls the thickness of  
26 layers that disaggregate from the surface. In three dimensions, the exfoliation stress field is shaped  
27 somewhat like a spherical cap, and as a result the depth to which the stress orientation is surface-  
28 normal (the “exfoliation depth”) is shallower than the depth of the local stress maximum at the  
29 center (Figure 1). The exfoliation depth varies over time and is not symmetrical with respect to the  
30 local subsolar point at the boulder surface. It typically falls between ~1 and 3 diurnal thermal skin  
31 depths, and may reach deeper in some parts of the boulder due to interaction with other stress  
32 fields. This variation makes it difficult to quantify the exfoliation stress consistently across boulder  
33 sizes and at different times of day, so it is useful to use the stress magnitude at the local maximum  
34 as an upper limit. This magnitude, which is controlled by both the boulder size and the diurnal  
35 thermal skin depth, is reported as the maximum exfoliation stress in Figure 2. The magnitude of  
36 stress at the exfoliation depth is typically 50–80% of that at the local maximum and decreases  
37 towards the boulder surface until entering the compressive regime (negative stress). Surface  
38 parallel fractures may develop at any point shallower than the exfoliation depth where the stress  
39 and energy requirements to drive crack propagation are met (Section 4).

### 41 3.3 Other Expressions of Fatigue

42 While exfoliation is the most relevant process pertaining to asteroid activity (Section 4), stress  
43 fields elsewhere in boulders may produce other breakdown behaviors on Bennu. The highest  
44 thermal stresses that occur in boulders undergoing thermal cycling are at their surfaces during  
45 surface cooling at night. These are limited in depth to the upper thermal skin depth and drive



**Figure 3.** Orientation of stress at the center of a 1 m boulder at the equator (black), 20 degrees latitude (green), 40 degrees latitude (blue), and 60 degrees latitude (orange) on Bennu at solar hour intervals. The black dashed lines show the orientation at the time of peak stress for each boulder above the equator.

18

19 surface-normal crack propagation (“surface cracking”) that is expected to contribute to shallow  
 20 effects such as surface disaggregation or granular disintegration. Many boulders on Bennu appear  
 21 to be breaking down in ways consistent with surface cracking, featuring loose particles seemingly  
 22 disaggregated from their surfaces, surrounded by unresolved material, or containing cracks that  
 23 follow apparent clast boundaries [DellaGiustina and Emery *et al.*, 2019; Walsh *et al.*, 2019;  
 24 Molaro *et al.*, 2020]. Surface cracks are likely to be the dominant mechanism serving to break up  
 25 exfoliation flakes into smaller particles as they disaggregate. Even if they do not cause  
 26 disaggregation directly, any damage accumulated in the form of microcracks at the boulder surface  
 27 can weaken flakes, enabling pieces to break off during exfoliation events, or making them more  
 28 susceptible to breakup from impacts. Damage accumulation in the upper few thermal skin depths  
 29 may also increase the porosity of boulder surfaces relative to their less damaged interiors. This  
 30 will make it more challenging to constrain the thermal and mechanical properties of Bennu’s bulk  
 31 materials from both spacecraft data and returned samples, which has important implications for  
 32 impact modeling and other research focused on understanding the formation and evolution of  
 33 rubble-pile asteroids. Different materials are more or less susceptible to different types of damage  
 34 accumulation depending on their mineral composition and fabric, and therefore studying variation  
 35 in surface thermal inertia with respect to the boulder population may provide important insight.

36 Another expression of thermal fatigue that may be visible on Bennu is the presence of  
 37 linear, through-going fractures that are inferred to result from stresses occurring in the deep interior  
 38 of boulders [Molaro *et al.*, 2017]. These stress fields produce a predominant N-S trend in fracture  
 39 orientation, which has been identified in boulder populations on Earth [McFadden *et al.*, 2005;  
 40 Eppes *et al.*, 2010], Mars [Eppes *et al.*, 2015], and the Moon [Ruesch *et al.*, 2020]. Figure 3 (black  
 41 solid lines) shows the stress orientation at solar hour intervals throughout the day at the center of  
 42 a 1-m boulder at Bennu’s equator. These remain approximately in the E-W plane, which tend to  
 43 drive crack propagation in the N-S direction at boulder interiors. Microcracks can coalesce into  
 44 large-scale features that reach the boulder edges, and may become through-going fractures that  
 45 split boulders apart. McFadden *et al.* [2005] inferred from observations that the predominant  
 46 fracture orientation should vary with latitude as the position of the boulder changes relative to the

1 Sun. This is supported by our results, which shows the stress field shift from an E-W to NE-SW  
2 orientation with increasing latitude (Figure 3 left; green, blue, orange). The orientation of the stress  
3 field at the time of peak magnitude has an aspect angle (degrees east of north) of 54, 35, and 25  
4 degrees for boulders at 20, 40, and 60 degrees latitude, respectively. This orientation never  
5 becomes truly N-S at the highest latitudes, as it will always be influenced by the position of the  
6 Sun and the E-W direction of its motion. This suggests that the trend in predominant fracture  
7 orientations should shift from N-S near the equator towards NW-SE and NE-SW at higher and  
8 lower latitudes, respectively. Statistical mapping of the orientation of through-going fractures  
9 observed on Bennu [Walsh *et al.*, 2019; Molaro *et al.*, 2020] is needed to assess whether this trend  
10 is present, though it may be influenced by mass movement [Walsh *et al.*, 2019; Barnouin *et al.*,  
11 2019; Jawin *et al.* submitted]. Such work may provide additional constraints on fatigue stress  
12 thresholds and crack propagation rates for carbonaceous chondrite materials.  
13

### 14 3.4 Influence and Evolution of Boulder Shapes

15 Expressions of thermal fatigue on Bennu may be influenced by realistic boulder shapes, as  
16 variation in the amount and timing of incident solar radiation on their surfaces may change where  
17 and how efficiently different fatigue-driven features develop due to face orientation and  
18 surface/shape roughness. Boulders that are very angular and/or have highly sloped faces may  
19 experience considerable changes in heating throughout the day, depending on their orientation  
20 with respect to the Sun. For example, a highly sloped east-facing surface heats quickly at sunrise  
21 but also becomes self-shadowed early in the day. As a result, it experiences a reduction in diurnal  
22 temperature variation relative to another face and lower surface stresses may lead to less surface  
23 cracking. An increase in local surface curvature due to surface roughness can have a similar effect.  
24 On very angular boulders, faces that are oriented away from the Sun may receive little incident  
25 radiation. Such an effect could serve to reinforce or retain the boulder's angular shape by only  
26 causing degradation of the sunward-facing surfaces. Exfoliation may smooth or reinforce a  
27 boulder's shape depending on the scale of surface or shape roughness relative to the thermal skin  
28 depth. Fractures may develop underneath small-scale bumps and cracks on boulders, leaving a  
29 smoother surface behind after a flake disaggregates. As the roughness of the shape approaches the  
30 scale of a few thermal skin depths, different portions of the boulder may begin to behave like  
31 separate or disparate segments, with exfoliation occurring independently on each. See Appendix  
32 A for additional discussion on such effects.

33 Stress fields driving different fractures also interact differently in boulders of different size.  
34 There is a synergy between interior and exfoliation stresses in boulders  $\leq 1$  m, for which the  
35 diurnal thermal skin depth is a significant fraction of their size. In these cases, exfoliation stresses  
36 on the E and W sides of the boulder are aligned and overlap with the deep interior stress field. This  
37 may result in the more efficient development of through-going fractures at the expense of  
38 exfoliation and/or in the deepening of exfoliation cracks, causing the distinction between the two  
39 features to blur. Thermal fatigue is likely to have a strong interaction with the variety of rock  
40 fabrics and textures observed on Bennu [Molaro *et al.*, 2020], and the presence of layering effects  
41 in some boulders, particularly those  $\leq 1$  m in size, may cause the deviation of exfoliation cracks  
42 from surface parallel to linear paths. As boulders become larger growing to sizes  $\geq 3$  m, their  
43 western and eastern edges become more mechanically decoupled. It takes longer for the nighttime  
44 surface stresses on their western edges to dissipate and the region to become dominated by the  
45 daytime stress field as it overtakes the eastern hemisphere. Additionally, western surface stresses

1 have much greater magnitudes than in smaller boulders. This results in large boulders retaining  
2 very strong stresses at their western surfaces and near-surfaces throughout the day that could  
3 perhaps lead to asymmetrical breakdown of boulders.  
4

### 5 3.5 Annual Stresses

6 Bennu experiences an annual thermal cycle that may also drive thermal fatigue and/or influence  
7 the rate and location of crack propagation caused by diurnal effects. This annual thermal cycle  
8 results from the asteroid's eccentric orbit, which causes its solar distance to vary between 0.89 and  
9 1.36 au throughout its 436.7 Earth-day year and resulting in an annual variation in surface heating.  
10 The annual thermal skin depth is ~5.6 and 2.9 m for dense and porous boulders, respectively,  
11 allowing annual stresses to penetrate much deeper than the diurnal effects that dominate their  
12 surfaces. Annual effects start to become important in boulders with diameters >3 m (though their  
13 effects are not included in our diurnal simulations above), in which stress fields analogous to the  
14 exfoliation and interior stresses described above arise at different times of year.

15 Annual stresses are challenging to model because spatially resolving both annual and  
16 diurnal scales in the simulation requires extremely large mesh sizes and is very computationally  
17 expensive. Using the same method described above, we simulated a 10 m equatorial boulder over  
18 an entire Bennu orbit with the highest possible mesh resolution given the restrictions on  
19 computation times. This resolution is still lower than acceptable for the diurnal simulations, and  
20 therefore there is high uncertainty in the resulting magnitude of induced stresses. The stresses at  
21 the boulder center and its near-surface, measured below the depth that diurnal surface stresses  
22 reach, are on the order of 1 MPa and peak during perihelion approach. These are likely an  
23 overestimate of actual annual stresses; however, given the order of magnitude agreement with  
24 diurnal stress magnitudes, it is likely that that annual stresses are still great enough to overcome  
25 the subcritical threshold needed to drive thermal fatigue.

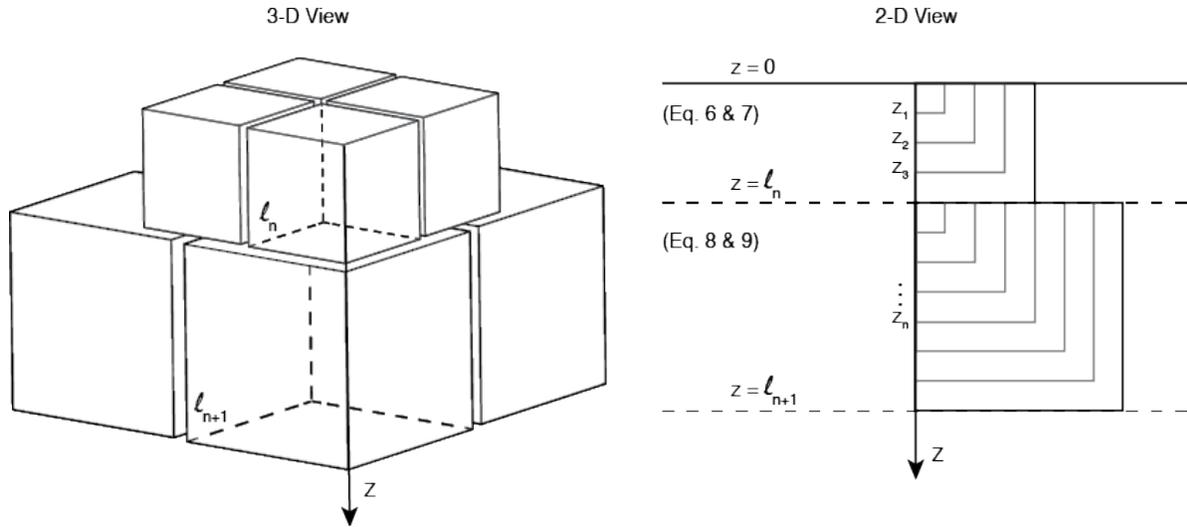
26 In spite of the uncertainty in magnitude, the orientations of annual stresses can provide  
27 insight into how they may influence rock breakdown. In the near surface, the stress orientation is  
28 surface perpendicular during perihelion approach. This is caused by net heating of the boulder as  
29 the asteroid moves closer to the sun, setting up a temperature gradient and stress field analogous  
30 to diurnal exfoliation effects. On perihelion departure, net cooling is most efficient out of the N  
31 and S faces of the boulder, which drives fractures in the E-W plane. At the boulder center, the  
32 stress orientation alternates between E-W during perihelion approach and the z direction (surface-  
33 normal) during departure, which is the same pattern as the diurnal stresses that drive N-S through-  
34 going fractures. This suggests that if annual stresses are strong enough to drive fatigue, such  
35 fractures should be seen at both spatial scales and should develop most efficiently in boulders  
36 subject to both diurnal and annual cycles, where their effects reinforce each other. A better  
37 understanding of their relative rates is needed to assess how annual stresses may disaggregate large  
38 boulders and the implications for the evolution of the boulder size-frequency distribution. In the  
39 near surface especially, it is unclear to what depth diurnal effects may operate quickly enough to  
40 dominate breakdown and whether annual fractures may be exposed by such disaggregation.  
41 Further, very large boulders are likely to have substantial preexisting damage and structural  
42 inhomogeneities that fatigue will exploit. These factors may make it difficult to identify annually  
43 driven features on Bennu's surface, though boulder size may be one distinguishing constraint.

44 The magnitude of annual stress in boulders is greatest when oriented in such a way as to  
45 drive an annual exfoliation effect in the near surface, suggesting that terrestrial sheeting joints may

1 be a relevant analog to observations. On Earth, the development of large-scale sheeting joints is  
2 commonly attributed to regional compressional stresses that result in surface-normal tensile stress  
3 in the near surface [e.g., *Martel, 2011; Martel, 2017*]. Joints occur as many surface-parallel cracks  
4 with characteristic spacing that is thin near the surface and increases with depth. They are similar  
5 to diurnal exfoliation layers but occurring at larger scales, with layers ranging from millimeters to  
6 tens of meters thick [*Martel, 2017*]. Regional tectonic stresses are not expected in a microgravity  
7 environment, but annual stresses on asteroids could play an analogous role, driving the  
8 development of surface-parallel fractures at depths below where diurnal effects operate. Further,  
9 diurnal and seasonal thermal stresses are known to contribute to sheeting joint exfoliation [*Collins*  
10 *and Stock, 2016; Collins et al., 2018; 2019*], suggesting that the superposition of annual and diurnal  
11 stress fields and/or sets of fractures in Bennu's boulders may influence the rate and/or location of  
12 diurnally driven crack propagation. These factors highlight the complexity of understanding how  
13 such features develop on asteroid surfaces and may help to explain the observation of some  
14 exfoliation layers on Bennu that are thicker than typical diurnal exfoliation depths [*Molaro et al.,*  
15 *2020*].  
16

### 17 3.6 Influence of Volatiles

18 Although volatiles from pore ice are not expected [*Rozitis et al., 2020*], Bennu's surface is  
19 dominated by hydrated phyllosilicate minerals [*Hamilton et al., 2019*], which may lead to  
20 synergies with thermal fatigue [*Lauretta and Hergenrother et al. 2019*]. CM carbonaceous  
21 chondrites are largely composed of serpentine-group phyllosilicates that contain tightly bound  
22 hydroxyl ions within octahedral sheets. Dehydroxylation can result from heating, comminution,  
23 and space weathering [*Drief and Nieto, 1999; Nakamura, 2005; Lantz et al., 2015; Thompson et*  
24 *al., 2019*], resulting in both pore space and molecular water. The former is caused by the volume  
25 change associated with the dehydration reaction and may result in cracks that weaken the bulk  
26 material and enable water migration (Tenthorey and Cox, 2003). The absorption of the water  
27 molecules onto crack walls can lower their surface energy and therefore the critical stress threshold  
28 required to drive crack growth [*Krokosky and Husak, 1968; Thirumalai and Demou, 1970; Kranz,*  
29 *1979*], which may enhance and accelerate the fatigue process. Indeed, laboratory studies have  
30 shown that hydrated carbonaceous chondrite meteorites develop cracks under thermal cycling  
31 more quickly than anhydrous ordinary chondrites [*Delbo et al., 2014*]. If present, these effects may  
32 be analogous to the environmentally assisted crack propagation (stress corrosion) that is thought  
33 to facilitate or enhance fatigue in terrestrial environments [*Aldred et al., 2016; Eppes and Keanini,*  
34 *2017; Lamp et al., 2017*]. However, the intrinsic source of water in these materials has important  
35 implications for how boulders break down relative to terrestrial observations. If thermal  
36 dehydroxylation occurs in Bennu's boulders, it cannot be physically decoupled from the  
37 mechanical stresses that are induced by thermal forcing, and therefore any effects from the process  
38 would be intrinsically captured in the material's effective strength and Young's modulus. In this  
39 context, the properties of asteroid materials not only depend on their composition, but also their  
40 temperature and age. This suggests that the efficacy of thermal fracturing processes may vary  
41 widely between asteroids and asteroid populations, as well as throughout their orbital and  
42 geomorphological histories. These effects are not directly included in our simulations but would  
43 be reflected in the range of density and Young's modulus values of the boulders, which currently  
44 are not known for Bennu.  
45



1 **Figure 4.** (left) Three-dimensional and (right) two-dimensional views of the layer geometry  
 2 assumed in our crack spacing and particle ejection calculations.  
 3

#### 4 Crack Spacing and Particle Ejection

6 We hypothesize that fatigue-driven exfoliation is the mechanism responsible for driving  
 7 the ejection of particles from Bennu's surface — specifically, at the transition from sub-critical to  
 8 critical crack growth, where the catastrophic failure of the separating flake produces mobilized  
 9 fragments of rock (Section 3.2) [*Janssen et al., 2002; Collins and Stock, 2016; Collins et al., 2018;*  
 10 *2019*]. We can test this hypothesis by comparing the characteristic spacing of exfoliation layers,  
 11 which determines the sizes of particles disaggregated from the boulder, to the observed particle  
 12 population. We can also use the predicted energy associated with these critical events to estimate  
 13 particle ejection speeds.

14 A necessary condition for crack growth to occur, whether critical or subcritical, is the  
 15 presence of enough energy to create the new crack walls. We use the thermal strain energy density  
 16 within our simulated boulders to create a model (Figure 4) to predict the spacing of surface-parallel  
 17 exfoliation cracks (Figure 5) that may develop [e.g., *Fletcher et al., 2006*]. The thermal strain  
 18 energy is potential energy stored within an object as it undergoes elastic deformation in response  
 19 to a change in temperature. If there is sufficient stress in an object to drive crack propagation, strain  
 20 energy is released as the crack grows, providing the energy that goes into producing its new crack  
 21 walls. As with our previous analysis (Section 3), we do not model actual crack growth within the  
 22 boulders, but we do quantify the characteristic spacing of exfoliation cracks by determining where  
 23 enough energy is available to create them. For boulders undergoing diurnal cycling, this energy is  
 24 generated, stored, and then dissipated in the boulder throughout each cycle, each day providing  
 25 energy for progressive crack lengthening. The strain energy is highest in the late afternoon (Figure  
 26 6) when they have undergone the most expansion due to surface heating. This is the same time at  
 27 which the exfoliation stress is highest (and therefore exfoliation events are most likely) and  
 28 represents the most amount of energy available to propagate surface-parallel cracks during the day.  
 29 As a result, exfoliation events are of the most interest with respect to producing particle ejection,  
 30 though we also consider events produced by surface cracking.  
 31

1 We assume that a fracture will form where the accumulated strain energy with depth is  
 2 equal to the surface energy of the new crack walls that will be created as a result. Our simulations  
 3 are three-dimensional so the strain energy density in the boulder is not spatially uniform in any  
 4 dimension. We take a linear profile of the strain energy density from the boulder's center to its  
 5 surface at the time and (surface) location where the peak value occurs. This we use as the depth-  
 6 dependent energy density of the boulder, making the simplifying assumption that it is uniform  
 7 along the surface-parallel plane. This assumption holds true for a region approximately half a  
 8 hemisphere around the location of peak strain energy. (These energy density profiles are included  
 9 with the data available in the repository noted in the acknowledgements.) We then calculate the  
 10 depth ( $l$ ) at which a fracture will form, disaggregating the layer of material above it. We assume  
 11 that this layer fragments into many equally sized blocks with the dimension of the fracture depth  
 12 (Figure 4). The energy an individual block needs to contain for this to occur is:

$$13 \quad E_n = 6\gamma l^2 \quad (5)$$

14 where  $\gamma$  is the surface energy of the rock. Enough energy is needed to create six crack walls: four  
 15 vertical boundaries, one lower boundary, and the upper boundary of the layer below (Figure 4).  
 16 To determine the energy available ( $E_a$ ) in the boulder, we integrate the strain energy density ( $U$ )  
 17 with depth to obtain:

$$18 \quad E_z = \int_{z=0}^{z'} U(z) dz \quad (6)$$

19 and multiply it by the surface area in the other two dimensions, giving a total available energy:

$$20 \quad E_a = E_z z^2 \quad (7)$$

21 A fracture is assumed to form at the depth ( $l$ ) at which the energy available in the block is equal  
 22 to the energy required ( $E_a = E_n$ ), found using Eqs. (5) and (7). Once the depth of a given fracture  
 23 ( $l_n$ ) is determined, the value of  $E_a$  is reset to zero and can begin accumulating once more such that  
 24 for  $z > l_n$ :

$$25 \quad E_{z>l} = \int_{z=l_{n-1}}^{l_n} U(z) dz \quad (8)$$

26 and:

$$27 \quad E_a = E_z (z - l_n)^2 \quad (9)$$

28 We could instead assume that a layer disaggregates as a cohesive, disc-shaped fragment,  
 29 but subsequent investigation into possible particle ejection speeds would require invoking an  
 30 additional energy source to then fragment the disc into smaller pieces. Although portions of flakes  
 31 may disaggregate cohesively, it is reasonable to assume that factors such as surface stresses at  
 32 different times of day and other mechanisms such as micrometeoroid impacts [*Bottke et al., in*  
 33 *review this collection*] will contribute to the breakup of flakes into smaller particles as they  
 34 develop. By choosing to incorporate the energy requirement for breaking up the flake into this  
 35 calculation, this method provides a more conservative estimate of the number of surface-parallel  
 36  
 37  
 38  
 39  
 40  
 41  
 42  
 43  
 44  
 45

1 fractures that can form as a result of exfoliating stresses and an upper bound on the largest expected  
 2 layer thickness. Any particles deposited atop boulders from other processes can still be mobilized  
 3 when an exfoliation flake experiences a lengthening event, but their numbers cannot be constrained  
 4 by this model.

5 The number of particles ( $N$ ) into which each layer fragments can be calculated by taking  
 6 the volume of a spherical cap of height  $l_n$ , subtracting the layer above, and dividing it by the  
 7 volume of an individual cubic particle:

$$8 \quad N = \frac{\pi}{3(l_n - l_{n-1})^3} [l_n^2(3R - l_n) - l_{n-1}^2(3R - l_{n-1})] \quad (10)$$

10 where  $R$  is the boulder radius. This method provides a more conservative estimate than dividing  
 11 the flat area of the spherical cap by  $l_n^2$ , but it is ultimately an upper bound on the number of particles  
 12 into which flakes may fragment.

13 The previous calculation makes the assumption that a crack will form where there is  
 14 enough available strain energy. However, several factors may influence realistic crack depths and  
 15 can change the amount of available energy in a given exfoliation layer. Exfoliation layers form  
 16 progressively, and there must still be sufficient stress to drive crack growth at any given location.  
 17 Because stresses are weakest near the surface, the fatigue threshold to develop a crack may be  
 18 achieved at a greater depth than the required strain energy. At depths where the fatigue threshold  
 19 is met, thin layers may also develop more slowly due to lower stresses than layers at depth. Any  
 20 layer that disaggregates contains all available strain energy within its volume, including that which  
 21 Eqs. (5) to (9) assume goes into the development of shallower layers. Therefore, if those shallower  
 22 cracks are not propagating at the same rate as a deep crack, excess energy may be available beyond  
 23 what is needed to form the disaggregating layer. Other factors can also contribute to this. For  
 24 example, partially formed exfoliation flakes may become closer to the surface as material is  
 25 disaggregated, altering the depth where it is energetically favorable to propagate cracks and  
 26 requiring less energy to disaggregate new material. Structural weaknesses or pre-existing damage  
 27 in boulders could have similar effects. In any of these cases, excess energy may be available within  
 28 disaggregated particles that can go towards ejection.

29 If we prescribe that a single crack forms at some arbitrary depth, we can calculate the  
 30 amount of excess energy ( $E_e$ ) available within particles using the same geometrical assumptions  
 31 as in Figure 4. In this case, none of the strain energy in the boulder goes into disaggregating layers  
 32 above that depth, so we use Eqs. (5) and (9) to find:

$$34 \quad E_e = E_a - E_n \quad (11)$$

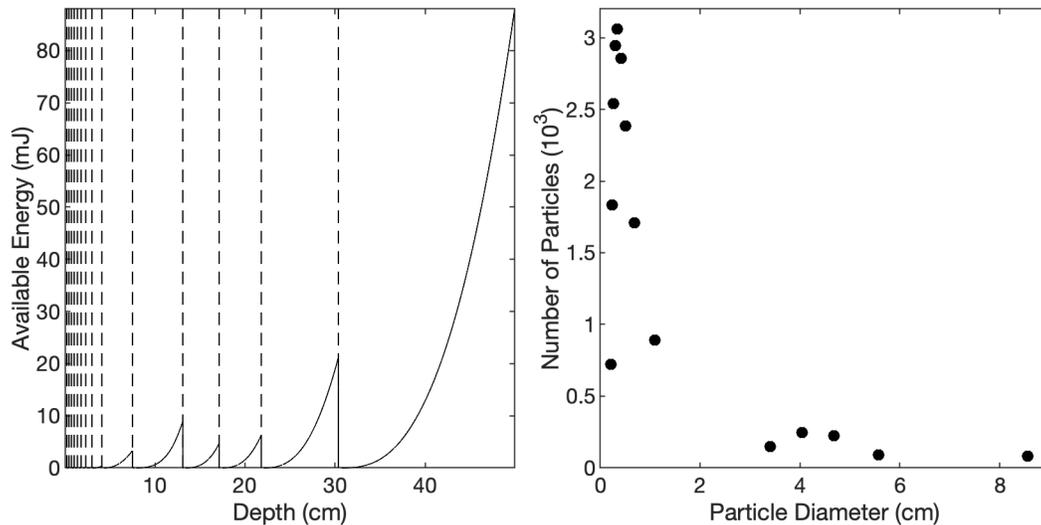
35 This is converted to kinetic energy, ignoring the effects of microgravity, giving a particle speed:  
 36

$$37 \quad v = \sqrt{\frac{2E_e}{\rho z^3}} \quad (12)$$

38 Figure 5 (left) shows an example set of cracks for a dense 1 m boulder and the resulting  
 39 number of ejected particles (right). The model predicts layer spacing ranging from  $\sim 0.1$  to 11 cm  
 40 and  $\sim 0.08$  to 13 cm within the top 30 cm of dense and porous boulders, respectively, where  
 41 exfoliation is expected to occur. This range is consistent with the thickness of exfoliation layers  
 42

1 observed on Earth that are driven or assisted by thermal fatigue [e.g., *Holzhausen, 1989; Lamp et*  
 2 *al., 2017; Martel, 2017; Collins et al., 2018*] and Bennu [*Molaro et al., 2020*]. It is also consistent  
 3 with, though slightly wider in range than, the sizes of particles ejected from Bennu, which range  
 4 from  $<1$  to  $\sim 10$  cm [*Lauretta and Hergenrother et al., 2019*]. The predicted minimum is somewhat  
 5 lower than observed, suggesting that if thermal fracturing is the driving mechanism for these events  
 6 some particles may not be resolved in spacecraft images. Layers are thinnest near the surface and  
 7 generally increase with depth, though not strictly monotonically. Larger boulders have more  
 8 volume, which leads to a higher total number of cracks. A majority of these are sub-centimeter in  
 9 size due to the boulders' higher strain energies, but the largest layers reach thicknesses of  $\geq 10$  cm.  
 10 Typically, these boulders had only one layer  $\geq 10$  cm thick within the upper 30 cm of their surfaces.  
 11 Small boulders have fewer total cracks, but more that are centimeters in size. This suggests that,  
 12 as material is disaggregated from the surface over time, large boulders may tend to show only the  
 13 one or two thick, underlying layers, whereas smaller boulders might show several layers, each a  
 14 few centimeters thick. Though, as layers disaggregate, multiple sets of cracks may become  
 15 superimposed on one another, highlighting the complexity of predicting crack spacing and particle  
 16 sizes in real boulders.

17 The predicted number of particles (Figure 5, right) produced by exfoliation of the layers  
 18 ranges from hundreds of centimeter-scale particles to thousands of sub-centimeter particles. The  
 19 number of particles grows as the diameter increases and boulders have larger cross sections of  
 20 material to disaggregate. This is higher than events observed at Bennu, which have produced of  
 21 order ones to hundreds of particles per event [*Lauretta and Hergenrother et al., 2019; Leonard et*  
 22 *al., in press*] (Table A1). However, we will neglect sub-centimeter particles for the time being  
 23 since not all of these would be resolvable in spacecraft images. This is also a reasonable  
 24 approximation considering that stresses closest to the surface are lowest in magnitude and therefore  
 25  
 26



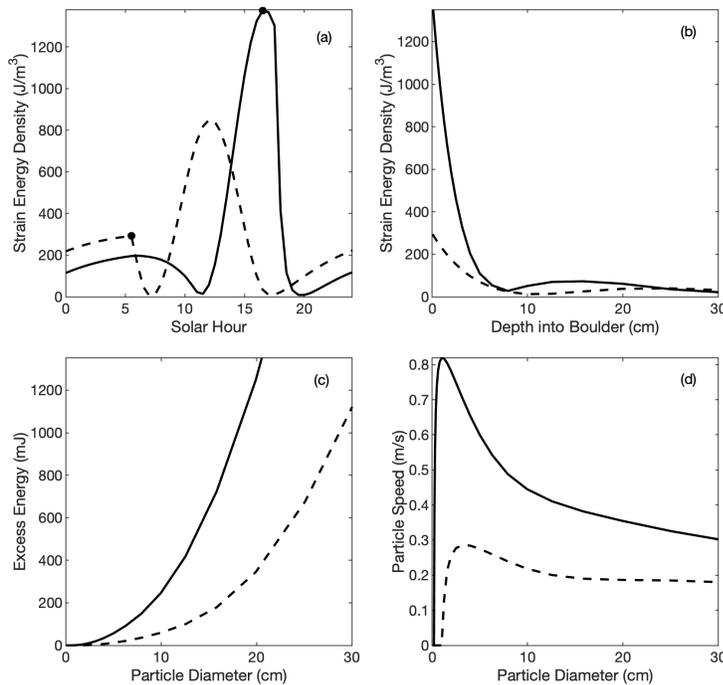
27  
 28 **Figure 5.** (left) Available energy with depth into the surface of a 1 m boulder per Eq. 9. Dashed  
 29 lines represent the locations at which cracks form, dropping the available energy to zero. The crack  
 30 spacing ranges from 0.2 to 8.5 cm. (right) The number of equally sized particles into which flakes  
 31 disaggregate (Eq. 10), with each having the dimension of the layer thicknesses shown at left.

1 the smallest exfoliation layers may not meet the required fatigue threshold to develop, and those  
 2 that do will be removed first from boulder surfaces. Considering only the centimeter-scale (and  
 3 larger) layers that remain, the number of particles ejected increases from tens in the smallest  
 4 boulders, to thousands in the largest boulders (Figure 5, right).

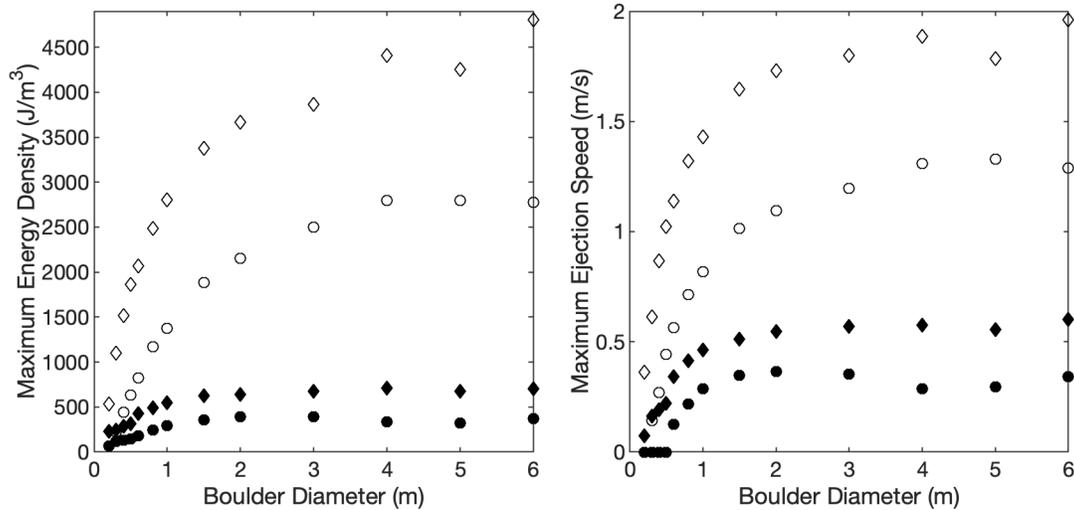
5 The prediction of tens to thousands of ejected particles per event is an upper limit, as an  
 6 entire exfoliation flake is not realistically expected to disaggregate completely at once. Rather,  
 7 flakes are expected to break apart over time, and therefore a full boulder cross section is likely to  
 8 overestimate what may be ejected in a single event. Additionally, the boulder strain energy density  
 9 is not exactly homogeneous along the radially perpendicular axes and may not possess enough  
 10 energy to eject particles over its entire cross section, particularly at greater depths and in larger  
 11 boulders. In some cases, the boulder face where exfoliation occurs may also be less than a full  
 12 cross section, such as in our ideal boulder whose buried portion of the western hemisphere would  
 13 be unaffected. Considering these factors, it is more reasonable to expect some fraction of the flake  
 14 to be ejected, which is also more consistent with observations. For example, an event that  
 15 disaggregates one quarter of exfoliation flake from a 1-m boulder produces  $\sim 225$  particles from  
 16 the 1 cm layer, or  $\sim 75$  particles from the 3 cm layer below. These are comparable to the largest  
 17 events observed to date at Bennu. In a larger boulder, the flake fraction must be smaller to produce  
 18 a similarly sized event. For example, one tenth of a 2 cm exfoliation flake disaggregated from a 5-  
 19 m boulder produces  $\sim 200$  particles. Without constraints on crack propagation rates, it is unclear  
 20 what estimate for the flake fraction is realistic. In this sense, this prediction method gives a  
 21 reasonable upper bound of tens to hundreds of centimeter-scale particles that can be produced via  
 22 fatigue for ejection, but the lower bound is not well constrained.

23 While the calculations above estimate the number of equally sized particles disaggregated  
 24 from a single layer, it is possible that multiple layers may be sourced during a given ejection event.  
 25 If the exfoliation layer driving the event is not at the boulder surface, shallower cracks may  
 26

27



**Figure 6.** (a) Thermal strain energy density over one solar day at the location of peak thermal strain energy density (solid) and peak tensile stress (dashed) in a 1 m boulder, with the dots showing the time of day at which each occurs. (b) Profiles of the thermal strain energy density with depth from the two locations in (a) to the center of the boulder. (c) Excess energy available in particles with particle size. (d) Ejected particle speed with particle size. The x-axis on panels b and c is limited to the upper 30 cm where exfoliation and surface events are most likely to be initiated.



1  
2 **Figure 7.** Maximum thermal strain energy density (left) and ejection speed (right) for exfoliation  
3 (open) and surface (solid) events in boulders of varying size. Values for dense (circle) and porous  
4 (diamonds) boulders show the range of maximum energies and ejection speeds predicted for each  
5 type of event.

6  
7 facilitate breakup of the disaggregated flake into a population of particles with a range of sizes  
8 smaller than the flake depth. In this context, or considering the cumulative material disaggregated  
9 from boulders across multiple events, the full particle size-frequency distribution (Figure 5, right)  
10 gives us a sense of the overall population of particles, and relative number of particle sizes, that  
11 we expect to be produced by exfoliation-driven particle ejection events.

12 Taking the alternate approach, we can calculate particle ejection speeds from the surface  
13 of the 1 m boulder independently of the predicted spacing of exfoliation cracks. Figure 6 (a, solid)  
14 shows the thermal strain energy density over time at the boulder surface, with peak values in the  
15 afternoon an order magnitude higher than at other times of day. At this time (b, solid), the strain  
16 energy is highest at the surface and decreases strongly within 10 cm. Taking the depth as our layer  
17 thickness, the amount of available energy (c, solid) increases to hundreds of millijoules as particles  
18 grow in size. For dense boulders, this leads to particle ejection speeds (d, solid) ranging from  $\sim 0.3$   
19 to  $0.8$  m/s, which exceed Bennu's escape speed of  $\sim 0.2$  m/s, and a minimum ejected particle size  
20 of  $0.2$  mm. We can also estimate particle speeds produced as a result of surface-perpendicular  
21 cracks (Figure 6, dashed lines) that develop during the night at boulder surfaces. These may  
22 provide a mechanism to break up exfoliation flakes, in which case their surface-perpendicular  
23 dimension would still be determined by the exfoliation layer thicknesses. The boulder has less  
24 thermal strain energy at this location and time of day, resulting in lower ejection speeds and a  
25 minimum ejected particle size of  $\sim 2.5$  cm. If surface stresses produce cracks that do not interact  
26 with exfoliation layers, they may still contribute to the disaggregation of particles, but their spacing  
27 (and thus their speeds) cannot be predicted in the same way due to the differing geometry. Overall,  
28 this suggests that thermal fatigue can drive ejection events at night on Bennu's surface, but such  
29 events may be expected to be lower in energy and with slower-moving particles than those  
30 occurring in the afternoon.

31 Figure 7 shows the maximum energy density (left) and ejection speeds (right) due to  
32 exfoliation (open) and surface cracking (solid) for dense boulders (circles) with varying diameter.  
33 The maximum ejection speeds are  $\sim 1.4$  m/s for exfoliation events in large boulders. Ejection

1 speeds due to surface cracking are much lower and do not occur in boulders <60 cm. Porous  
2 boulders have higher strain energy densities and ejection speeds than dense boulders because they  
3 have a lower elastic modulus and are less brittle. Since the magnitude of induced stresses are also  
4 lower, ejection events are less likely to occur or may occur less frequently in porous materials.  
5 The largest porous boulders are most likely to eject particles and have ejection speeds ~30 to 50%  
6 higher than the dense boulders, with a maximum of ~2 m/s. The smallest porous boulders have  
7 higher speeds by more than a factor of 4 but are the least likely to eject particles due to their low  
8 stresses. Overall, these speeds are consistent with particles ejected from Bennu, which ranged from  
9 ~0.05 to 3.3 m/s [Lauretta and Hergenrother et al., 2019; Leonard et al., in press]. The maximum  
10 predicted speed is lower (within a factor of 2) than what is observed, suggesting that although  
11 generally fatigue-driven exfoliation is a viable mechanism for particle ejection, there is limited  
12 available energy relative to other processes such as impacts [Bottke et al., in review this collection].

13 The amount of strain energy available in a given boulder varies throughout Bennu's orbit,  
14 peaking at perihelion when the diurnal temperature variation is largest. For a 1 m boulder, the  
15 change in peak strain energy with solar distance follows an approximate power law relationship  
16 with an exponent of  $-2.1$ . In contrast to Figure 6, the excess energy available to mobilize particles  
17 in a 1 m dense boulder at aphelion decreases to only a few hundred millijoules with a maximum  
18 ejection speed of 0.2 m/s. This is similar to the nighttime events, suggesting that the range of  
19 energies and ejection speeds for a given boulder size in Figure 7 are also a reasonable  
20 approximation for variation throughout the year. Since exfoliation layers are produced  
21 progressively, the number and depth of expected layers should realistically reflect some total  
22 cumulative energy throughout the entire orbit. On the other hand, stresses are nonlinear with solar  
23 distance, and so we might expect crack spacings to skew towards what is expected at perihelion.

24 The particle sizes determined by Lauretta and Hergenrother et al. [2019] are for spheres,  
25 whereas we assume cubes. It would be impractical to assume spherical particles using our  
26 methodology because of its reliance on layer spacing to determine the sizes of particles and crack  
27 walls. This will have only a minor effect on the comparison of our results to the observations. Most  
28 notably, if we approximate that the integration of energy with depth would be the same as  
29 performed above and simply split each cube into two smaller spheres, this would increase the  
30 number of particles per layer by a factor of 2. However, given the order of magnitude nature of  
31 our discussion regarding what fraction of a layer may disaggregate at once, a factor of 2 does not  
32 change our conclusion qualitatively. Since halving the volume would also halve the total energy  
33 of each particle, this would place a factor of 1/2 in both the numerator and the denominator of Eq.  
34 12. These will cancel out, and therefore the particle speeds shown in Figures 6 and 7 would remain  
35 unchanged. Lauretta and Hergenrother et al. [2019] assume a particle density of 2000 kg/m<sup>3</sup> in  
36 their calculations, which falls between our solutions for dense and porous boulders.

## 38 **5 Observational Constraints on Ejection Events**

39 To determine the likelihood of thermal fatigue as a driving mechanism for Bennu's particle  
40 ejection events, we must examine our results in the context of both observational constraints and  
41 other possible mechanisms. A summary of our results with respect to observational constraints is  
42 provided in Table 2, along with the references to which readers can refer for more details regarding  
43 the ejection event observational data. A summary the data relevant to this discussion is also  
44 included in Appendix B (Table A1). Given the limited dataset and difficulty in accounting for all  
45 possible biases, there is uncertainty in some of the possible trends that we discuss. Nevertheless,

1 the data are compelling to explore and provide an opportunity to perform an initial assessment of  
2 the feasibility of our hypothesis.

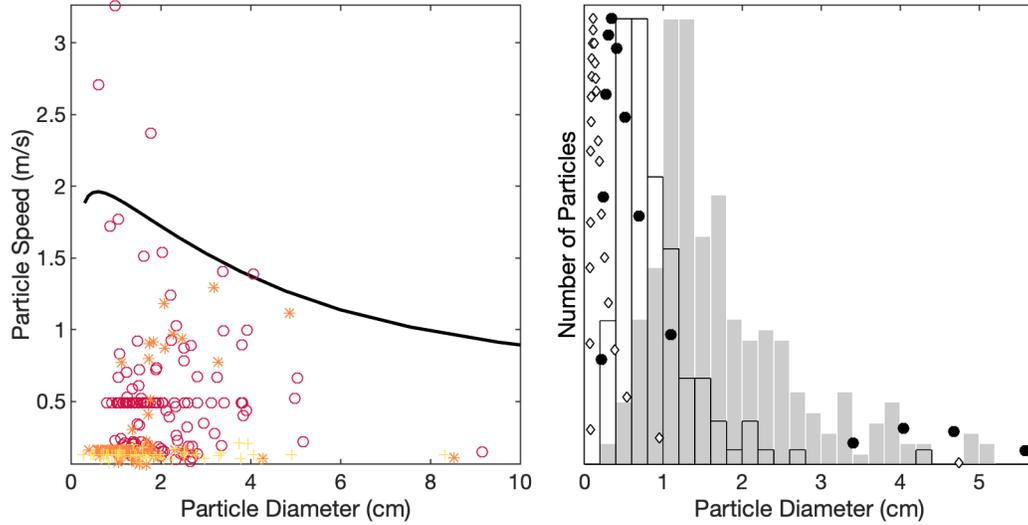
3 As described in Section 4, our model of crack spacing and particle ejection due to boulder  
4 exfoliation and surface cracking is predicted to produce (i) a range of particle sizes from 1 mm to  
5 13 cm, (ii) a maximum ejection speed of  $\sim 2$  m/s, and (iii) up to hundreds of  $\sim 1$  to 10 cm sized  
6 particles per event. All three of these results are in good agreement with observations (Table 2),  
7 though (iii) is the least well constrained. Our predicted maximum speed falls shy of the maximum  
8 observed (3.3 m/s); however, the majority of speeds from the three largest ejection events fall  
9 below our best fit profile (Figure 8, left). Since our calculations are based on available energy per  
10 particle, the lack of constraints on number of particles does not alter our predicted speeds.

11 Figure 8 (right, shaded) shows the normalized observed particle size-frequency distribution  
12 (SFD) from the three largest eject event observations [Lauretta and Hergenrother, 2019] using the  
13 upper-limit particle sizes from the observational data (Appendix B), compared to normalized  
14 predicted distributions for the 1-m dense boulder (circles) and 6-m porous boulder (diamonds)  
15 from our model. A perfect match is not expected, as the total SFD predicted by our model should  
16 realistically reflect the cumulative total from all boulders that produce particle ejections, which is  
17 not yet known. Nonetheless, the shape of the predicted size-frequency distributions provide a good  
18 qualitative match to observations, though quantitatively they skew towards more smaller particles.  
19 If Bennu's ejection events are caused by exfoliation, the relative lack of sub-centimeter sized  
20 particles could indicate that we are not observing all of the material ejected during any given event,  
21 or that the requirements to produce exfoliation layers at sub-centimeter depths is not achieved and  
22 therefore such particles should not be produced. A better match is obtained by Chesley et al. [*in*  
23 *review this issue*] who assumed the observed particles are oblate spheroids (Figure 8, unshaded)  
24 instead of spheres [Lauretta and Hergenrother et al., 2019]. They used their calculated axis ratio  
25 distribution to convert our predicted SFD to oblate particles, shifting the predicted population to  
26 larger diameters with a peak at  $\sim 0.7$  cm. Oblate or rectangular particles are consistent with the  
27 exfoliation mechanism, which may disaggregate flakes into fragments with a range of widths.  
28 Using rectangular instead of cubic particles in our model would result in a slight increase in  
29 predicted ejection speeds, as less energy would be needed to create surface-normal cracks.  
30

31 **Table 2.** A summary of our results with respect to constraints from observed particle ejection  
32 events at Bennu. Constraints and supporting data are described in detail by Lauretta and  
33 Hergenrother et al. [2019], Hergenrother et al. [*in review this collection*], Chesley et al. [*in review*  
34 *this collection*], Leonard et al. [*in press*], and Pelgrift et al. [2020] (Appendix B).

Constraints	Observations	Thermal Fatigue	Impacts*
Maximum Particle Speed (m/s)	$\sim 3.3$	$\sim 2$	$> 3.2$
Particle Diameters (cm)	$< 1$ to $\sim 10$	$\sim 0.08$ to 13	$\sim 7$ (upper limit)
Number of Particles	1s to 100s	10s to 100s (upper limit)	unconstrained
Total Mass (g)	1s to 1000s	10s to 1000s (upper limit)	350 (upper limit)
Time of Day	predominantly afternoon & night	afternoon (primary) & night (secondary)	any, afternoon preference
Frequency	days to weeks	unconstrained	biweekly near perihelion
Latitude & Longitude	various	any	any, preference equatorial

35 \*Based on calculations for a 7000-J impact event.



1 **Figure 8.** (left) Predicted maximum ejection speed with particle diameter for a 6 m, porous boulder  
 2 (black line) with particle speeds and upper limit diameters from the three largest ejection events  
 3 (symbols) as reported by Lauretta and Hergenrother et al. [2019] (Appendix B). The groups at ~0.5  
 4 and 0.16 m/s are particles with no trajectories for which the mean velocities were assumed. (right)  
 5 Particle size-frequency distribution for the same ejection events assuming the lowest albedo  
 6 particles (shaded), and the distribution assuming oblate particles from Chesley et al. [*in review this*  
 7 *issue*] (unshaded). The symbols show the predicted distribution produced from a 6 m, porous  
 8 (circles) and 1 m dense (diamonds) boulder. Each distribution is normalized to its largest bin value.  
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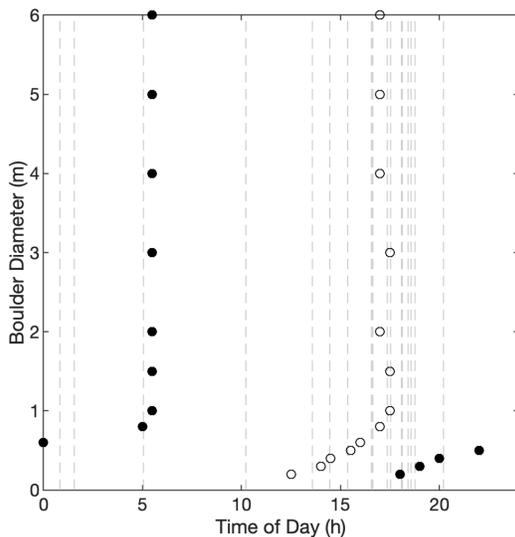
10  
 11 Additionally, the timing of observed particle ejection events is consistent with the times of  
 12 day that exfoliation and surface cracking are expected to occur (Figure 9). Strain energy and  
 13 exfoliation stress for boulders  $\geq 1$  m are highest during local solar hours 13 to 18, with a peak  
 14 value at hour 17 (Figure 6; Figure 9). The majority of observed ejection events occur during these  
 15 times (dashed lines), with four of the five largest events (those with  $>20$  particles) occurring  
 16 approximately between hours 15 and 18. The event that occurred during local night could have  
 17 been driven by surface cracking. The hours between sunrise and noon are the least likely for  
 18 fatigue-driven ejection to occur. As discussed in Section 3.4, these time predictions will vary  
 19 somewhat between individual boulders when accounting for their unique shapes.

20 The amount of strain energy available in a given boulder will peak at perihelion and  
 21 decrease with increasing solar distance. Additionally, annual exfoliation stresses peak  $\sim 30$  days  
 22 before perihelion at a solar distance of 0.92 au. It is unlikely that deformation due to annual heating  
 23 contributes any significant thermal strain energy to boulder surfaces; however, the superposition  
 24 of annual and diurnal stresses during this time may help overcome fatigue stress thresholds or  
 25 increase crack propagation rates, leading to more frequent events. Combined, these factors suggest  
 26 that if Bennu's particle ejection events are driven by thermal fatigue, we should observe more  
 27 frequent, higher energy events approaching and near perihelion, and less frequent, lower energy  
 28 events near aphelion. Higher energy events are also expected to produce more, faster moving  
 29 particles. This is generally supported by the data, which shows that the total energy of events does  
 30 decrease with increasing solar distance. Though, the five largest events are spread out over several  
 31 months with lower energy events in between. Events with speeds exceeding 1 m/s have also been

1 observed at solar distances  $\gtrsim 1.3$  au [Pelgrift *et al.*, 2020]. This is not consistent with our predicted  
 2 decrease in particle speeds near aphelion. More observations are needed to better explore this idea.

3 While the observations of particle ejection events at Bennu are consistent with what we  
 4 predict from thermal fatigue, other candidate mechanisms have not been ruled out. In particular,  
 5 electrostatic lofting and impacts have been considered as alternatives for Bennu, though other  
 6 mechanisms are also explored generally by Jewitt *et al.* [2015]. Hartzell *et al.* [*in review this*  
 7 *collection*] report that, depending on the surface cohesion, electrostatic lofting is capable of  
 8 stripping Bennu of submillimeter sized particles during the day, but cannot produce the large, fast  
 9 particles observed leaving Bennu's surface during the largest ejection events. Ultimately, they  
 10 conclude that it is unlikely to cause Bennu's daytime ejection events but cannot be ruled out as a  
 11 mechanism for smaller events that occur during the night. This leaves impacts as the most  
 12 reasonable alternative candidate to thermal fatigue (Table 2).

13 Bottke *et al.* [*in review this collection*] predicted that 7000-J meteoroid impacts at Bennu  
 14 should occur on a biweekly cadence near perihelion with a preference to strike in the late afternoon,  
 15 which is a reasonable match to the timing of the three largest ejection events observed. They found  
 16 that these impacts, on average, can produce up to 350 g of ejecta, with 80% of the mass having a  
 17 speed  $< 3.2$  m/s if they assume that the impacts strike into cohesionless (1 kPa) soil. This ejecta  
 18 mass is consistent with low to midrange values of the total masses of observed ejection events,  
 19 though it can only produce the largest observed individual particles if ejected as a single combined  
 20 mass (maximum of  $\sim 4$ -7 cm diameter). In this context, the impact hypothesis may be somewhat  
 21 mass-limited compared to the largest ejection events, but the available energy is more than enough  
 22 to produce observed ejection speeds. This is in contrast to thermal fatigue, which can potentially  
 23 produce an excess number of particles relative to observations, but with maximum speeds less than  
 24 the fastest observed particles. This being said, Bottke *et al.* [*in review this collection*] only perform  
 25 calculations for 7000-J impact events (Table 2), which does not capture the probabilistic variation  
 26 in impactor energy and size that occurs in reality. The limited number of ejection event  
 27 observations are insufficient to perform any statistical analysis that may provide a better  
 28 comparison to their results. Both hypotheses predict that impact frequency should decrease  
 29 towards aphelion.  
 30



**Figure 9.** Time of day at which peak surface (solid) and exfoliating or near-surface (open) stress occurs in boulders of varying diameter. The dashed lines show the times of nine ejection events observed at Bennu (see Appendix B).

1           One weakness in the impact hypothesis is the nature of the impactor target. The cohesive  
2 strength of rock is equal to its shear strength under zero confining pressure and typically is the  
3 same order of magnitude as its tensile strength. The impact model uses dry sand as an analog for  
4 cohesionless material, which has a cohesive strength two orders of magnitude lower than even  
5 weak and porous intact rock [e.g., *Burk, 1964; Grott et al., 2019*]. Bottke et al. [*in review this*  
6 *collection*] report that impacts occurring into cohesionless material can produce the observed mass  
7 or particle speeds from the three largest ejection events, but impacts into intact rock cannot.  
8 However, the majority of Bennu's surface is covered with intact boulders that have enough  
9 strength to sustain visible fractures and therefore cannot be considered cohesionless. Further, they  
10 report that an impact into cohesionless soil should produce a crater at least 14 cm wide, which  
11 would excavate at least 260 cm<sup>3</sup> of material and require a soil depth of 3 to 4 cm to occur (assuming  
12 its shape is a spherical shell). Both of these factors suggest that only a fraction of Bennu's surface  
13 has properties suitable to produce impact events consistent with ejection event observations, which  
14 would lead to a less frequent cadence of ejection events than they report and therefore provide a  
15 worse match to observations. On the other hand, the nature of impacts into rubble pile surfaces is  
16 not well understood, and it is unclear at what size materials transition from unconsolidated small  
17 pebbles to intact boulders that are adjacent to each other, or how these regimes are influenced by  
18 impactor energy.

19           While fatigue provides a good match to observational constraints at the present time, more  
20 observations are needed to explore long term variation in the mass, energy, and frequency of  
21 particle ejection events. Additional work studying exfoliation features on Bennu's surface will also  
22 provide better constraints on fatigue thresholds and lead to more accurate predictions of mass  
23 disaggregation rates from our model. It is also likely that fatigue works in synergy with both  
24 impacts and electrostatic lofting to produce the asteroid surface we see, and all three mechanisms  
25 may contribute to observed ejection events. For example, if stress magnitudes are sufficient for  
26 exfoliation they can produce sub-centimeter sized layers, electrostatic lofting could help sweep  
27 away the smallest disaggregated particles to leave behind the underlying centimeter scale layers  
28 we see in boulder surfaces. Such an interaction could help to explain the lack of sub-centimeter  
29 sized particles in observed ejection events relative to the particle population predicted by our  
30 model. Because exfoliation flakes develop progressively, fatigue may also provide planes of  
31 weakness that meteoroid impacts can exploit. Even if the ejection events are ultimately driven by  
32 impact processes, it is likely that the exfoliation layers play a strong role in the particle size  
33 distribution of impact ejecta both leaving and remaining on Bennu's surface. The popping up of  
34 an exfoliation layer's edge over a curved surface could also loft loose particles resting on the  
35 boulder [*Jawin et al. submitted*] from impact and/or other thermal mechanisms, even if the  
36 exfoliation flake itself does not disaggregate.

## 38 **6 Conclusions**

39           We performed finite element simulations of stress fields in serpentine-rich carbonaceous  
40 chondrite boulders undergoing diurnal thermal cycling on the surface of Bennu. We find their  
41 magnitudes to be comparable to the tensile strength of terrestrial analog materials. These stresses  
42 are sufficient to drive thermal fatigue (a subcritical crack growth process) and possibly other  
43 thermal fracturing processes (e.g., thermal shock) on the surface. The occurrence of thermal fatigue  
44 has been substantiated by the widespread observation of fatigue-driven exfoliation on Bennu  
45 [*Molaro et al., 2020*], which likely works in combination with shallow surface-normal cracking to

1 drive boulder breakdown. Large-scale through-going fractures from fatigue likely also develop,  
2 but more work is needed to map fracture orientations across the surface to assess latitudinal trends.  
3 Annual stresses arising throughout Bennu's orbit may interact with diurnal effects, influencing the  
4 rate and/or location of crack propagation in large boulders, though better constraints on the stress  
5 threshold required to drive fatigue in carbonaceous chondrite materials are needed to explore such  
6 effects. Thermal fatigue likely plays a dominant role in Bennu's landscape evolution, and future  
7 work to identify and study fatigue-driven features will provide valuable insights into the rate at  
8 which the process occurs and how it interacts with other surface processes. Analysis of returned  
9 samples will also provide better constraints on the thermal and mechanical properties of Bennu's  
10 surface materials, which have a critical bearing on induced thermal stress.

11 We posit that the process of exfoliation can lead to the energetic ejection of particles from  
12 the asteroid surface as a fatigue crack moves from sub-critical to critical failure at the end of its  
13 life. We quantified the thermal strain energy stored by boulders during the times of day at which  
14 exfoliation is expected to occur to predict the characteristic spacing of exfoliation layers. We find  
15 that layers should be thinnest near the boulder surface where the strain energy is highest and  
16 increase with depth, with predicted crack spacings of order 1 mm to 10 cm. This is consistent with  
17 observations of exfoliation layers on Bennu's boulders [*Molaro et al.*, 2020], as well as in  
18 terrestrial environments [e.g., *Holzhausen*, 1989; *Fletcher et al.*, 2006; *Martel*, 2017]. We find that  
19 exfoliation flakes can disaggregate into an upper limit of hundreds of centimeter-scale particles,  
20 although this result is less well constrained. The ejection speed of these mobilized particles is  
21 predicted to increase with decreasing diameter and to have a maximum value of  $\sim 2$  m/s for porous  
22 boulders. Dense boulders have a lower maximum speed of  $\sim 1.3$  m/s. For both porous and dense  
23 materials, ejection speeds generated during surface cracking events at night are much lower than  
24 predicted during exfoliation events.

25 These predictions are in good agreement with the sizes and speeds of particles from  
26 ejection events observed at Bennu to date by the OSIRIS-REx spacecraft [*Lauretta and*  
27 *Hergenrother et al.*, 2019; *Leonard et al.*, in press]. The shape of the size-frequency distribution  
28 of the particle population that exfoliation is predicted to produce is also consistent, though it skews  
29 toward a greater number of sub-centimeter particles than is observed. If fatigue-driven exfoliation  
30 is driving the observed ejection events, this would indicate that we are not observing all of the  
31 particles ejected, which is possible given the limitations of our detection capability [*Hergenrother*  
32 *et al.*, in review this issue]. It could also indicate that the fatigue threshold is not met near the  
33 boulder surface and therefore sub-centimeter exfoliation layers are not produced. More  
34 observations are needed to confirm whether the predicted trends of increasing event frequency  
35 and/or energy during perihelion approach occurs.

36 If thermal fatigue indeed plays a role in Bennu's activity, this has broad implications for  
37 our understanding of active asteroids and the asteroid population as a whole. Previous works have  
38 hypothesized that thermal fracture processes may generate activity on active asteroids with small  
39 perihelion distances, such as (3200) Phaethon [*Jewitt and Li*, 2010]. Our results support this  
40 hypothesis. With a diurnal temperature variation of hundreds of degrees, Phaethon's surface is  
41 likely to be subject to thermal shock processes, with fatigue operating at depth to weaken and  
42 prepare the rock for disruption. However, the fact that thermal fatigue alone may be capable of  
43 generating activity suggests that there may be many more active asteroids than are currently  
44 known, likely including many in near-Earth space. With less energetic activity, a lack of tails or  
45 comae would make such bodies hard to identify from ground-based observations, and previous  
46 missions to visit asteroids up close lacked the capability to detect ejection events like those

1 observed on Bennu. Objects with a similar rotation period and composition to Bennu should begin  
2 generating strain energies capable of ejecting particles at solar distances of  $\sim 1.5$  to 2 au. This  
3 activity “line” for different bodies will vary primarily with composition, as an object’s mechanical  
4 properties control how it responds to thermal forcing. Fatigue may also become possible on some  
5 bodies at greater distances than activity can occur, for example because the strain energy is  
6 insufficient to mobilize particles in a given gravity environment. There is much to be learned about  
7 how this process operates. For example, it is unclear what roles crack propagation distance and  
8 rate play in producing ejection events, or to what extent breakup of exfoliation flakes occurs during  
9 such an event or beforehand. A better understanding of these ideas will provide valuable insights  
10 into the distribution of active asteroids in the solar system and their mass loss rates, which has  
11 implications for asteroid survival times and the production of interplanetary debris.

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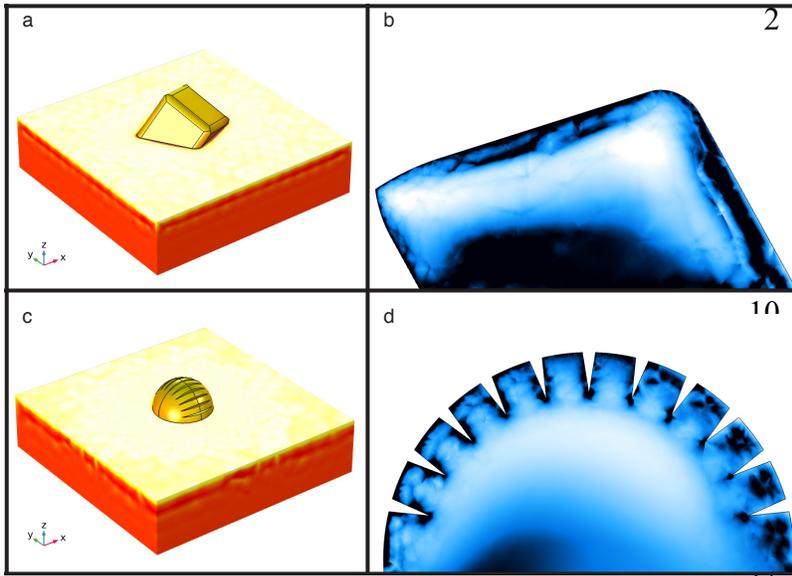
## 1 **Appendix A: Influence of Boulder Shape**

2 Although real boulders are not necessarily well approximated by spheres, our choice to use  
3 spherical boulders does not qualitatively change our results. Boulder shape can influence the nature  
4 of thermal fatigue in two primary contexts: face orientation and surface/shape roughness. In both  
5 cases, realistic shapes will cause variations in the magnitude and timing of thermally induced  
6 stresses experienced by different parts of the boulder. To explore these effects, we simulated a 1  
7 m square boulder embedded at an angle in the regolith and a 1 m spherical boulder with 10 cm  
8 deep triangular surface “cracks” spaced 10 cm apart (Figure A1). The variation in stress  
9 magnitudes in each case (described below) is smaller than  $\pm 25\%$ , which is comparable to their  
10 uncertainty values and to stress sensitivity to variation in mechanical properties [Molaro *et al.*,  
11 2017]. No color scale is included in Figure 1A because these simulations were performed at a  
12 lower resolution for computational efficiency, and so this stress variation represents an upper limit  
13 on behavior.

14 Surface stresses are primarily influenced by surface orientation. For boulders that are  
15 especially angular, the orientation of an individual face with respect to the Sun’s location and  
16 direction of motion will influence the timing and amount of incident solar radiation it receives. For  
17 example, the square boulder (Figure A1, top) has a highly sloped east face, which will heat very  
18 quickly at sunrise, but it will also become self-shadowed earlier in the day than a lower-sloped  
19 surface. This will cause it to experience a lower diurnal temperature variation and a reduction in  
20 the magnitude of surface stress. This effect may be enhanced by the fact that it has more surface  
21 area from which to emit radiation compared to a sphere. An increase in local surface curvature at  
22 a given location due to surface roughness or bumps can also lead to decreased surface stress.

23 Exfoliation stresses are influenced primarily by boulder shape, depending on the scale of  
24 surface or shape roughness. Exfoliation fractures will develop underneath small-scale surface  
25 bumps and may leave behind a smoother surface after the flake disaggregates. As the roughness  
26 of the shape approaches the scale of a few thermal skin depths, different portions of the boulder  
27 may begin to behave like separate segments, with exfoliation occurring independently on each.  
28 For example, the square boulder (Figure A1, b) has two local maximums in exfoliation stress at  
29 each corner that peak at two different times of day. The stress orientation near each corner is still  
30 surface-normal in this case, and the surface-parallel crack propagation could serve to round them  
31 over time. The stress orientation between corners is more difficult to describe with respect to the  
32 boulder’s angular shape. Below the exfoliation depth the stress orientation is determined by which  
33 boulder faces provide the most efficient pathway for cooling. In spherical boulders, this is N-S,  
34 but in this case the stress between the two corners is roughly E-W. This aligns with the surface-  
35 normal stress at the western corner and may lead the boulder to develop a flat western face. The  
36 stress magnitude is also enhanced at the western corner (relative to a spherical boulder) due to the  
37 corner orientation with respect to the time at which the boulder is hottest. In this sense, exfoliation  
38 is also influenced by surface orientation to the extent that it determines which boulder faces  
39 experience exfoliation and how they heat. In contrast, the exfoliation stress field in Figure A1 (d)  
40 remains largely unchanged from a spherical boulder, and the stress orientation in the “bumps”  
41 remains normal to the spherical shape of the surface as if the cracks did not exist. In this case  
42 exfoliation would serve to cut through or under the bumps. There is nuance in how the stress fields  
43 change and behave in irregular objects and much to still be learned about the evolution of boulder  
44 shapes from thermal fracturing.

1



**Figure A1.** (a) Temperature of a square 1 m boulder in the midafternoon being heated by the Sun as it moves within the y plane, and (b) a cross section through the boulder along the y plane. Panels (c) and (d) show the same for a spherical boulder with 10 cm surface “cracks.”

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### Appendix B: Summary of observational data

Table A1 summarizes some of the relevant data from seventeen particle ejection events observed between January 6 and September 14 of 2019. These data are compiled from Lauretta and Hergenrother et al. [2019], Hergenrother et al. [*in review this collection*], Chesley et al. [*in review this issue*], Leonard et al. [*in press*], and Pelgrift et al. [2020] for use in Figures 8 and 9, Table 2, and the text in Section 5. Table 1A reports the number of *observed* particles during each ejection event, which may differ from the number of *analyzed* particles in the aforementioned studies. The photometry techniques used to estimate particle sizes were performed using a range of assumed particle albedos. Following the methodology described by Lauretta and Hergenrother et al. [2019], we use a density of  $2000 \text{ kg/m}^3$  and an albedo of 0.033 to provide an upper-limit estimate on observed particle diameters for Figure 8. Tables 2 and A1 show values assuming an albedo of 0.044, which yields a midrange estimate of particle sizes. Note that Lauretta and Hergenrother et al. [2019] and Hergenrother et al. [*in review this collection*] make different assumptions about particle shape, and therefore these data (Table 1A) are only intended as a an approximate guide to characteristic particle sizes observed. More complete datasets are available in the aforementioned references. We also caution that the total number of observed events is limited, making it difficult to assess how statistically meaningful any specific trends may be. There may also be biases in the timing of observed events, and the number and albedo of observed particles, resulting from spacecraft location, orientation, distance from the asteroid, and other factors.

1 **Table A1.** Subset of data from the particle ejection events observed at Bennu compiled from Lauretta and  
 2 Hergenrother et al. [2019]<sup>1</sup>, Hergenrother et al. [*in review this issue*]<sup>2</sup>, Chesley et al. [*in review this*  
 3 *issue*]<sup>3</sup>, Leonard et al. [*in press*]<sup>4</sup>, and Pelgrift et al. [2020]<sup>5</sup>.

Event Date	Solar Distance (au)	Solar Hour	No. Observed Particles	Maximum Speed (m/s)	Total Energy (mJ)	Total Mass (g)	Particle Diameter (cm)			References
							Ave	Min	Max	
6 Jan	0.89	15.36	200	3.3	270	1800	1.2	0.2	5-8	1, 2
19 Jan	0.89	16.63	108	1.3	100	600	1	0.5	4-7	1, 2, 3
29 Jan	0.90	18.76	≤10	<0.5						2, 4
4 Feb	0.92	18.41	≤10	<0.5						2, 4
5 Feb	0.92	17.36	≤10	<0.5						2, 4
8 Feb	0.93	14.46	≤10	<0.5						2, 4
8 Feb	0.93	1.56	≤10	<0.5						2, 4
11 Feb	0.93	18.08	72	0.2	8	700	1.2	0.3	4-7	1, 2, 3
15 Feb	0.94	0.83	≤10	<0.5				0.3	1	2
19 Apr	1.14	16.56	22	0.9				0.7	5	2, 4, 5
18 Jun	1.29	17.53	≤10	1.6				0.3	0.6	2, 5
16 Aug	1.35	20.2	≤10	<0.5				1.2	1.4	2, 3
23 Aug	1.35	18.12	≤10	<0.5				0.9	2.6	2, 3, 5
28 Aug	1.35	18.56	≤10	<0.5				0.2	0.3	2, 3
05 Sep	1.35	13.58	≤10	<0.5				0.6	1.2	2, 3
13 Sep	1.34	10.22	30	2.3				0.5	1.9	2, 3, 5
14 Sep	1.34	5.05	≤10	<0.5				0.6	0.9	2, 3

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34 parameters needed to reproduce our simulations are described in the text. The raw numbers for all  
35 figures in the text (excluding Figures 1 and 4) and the strain energy density profiles needed to  
36 produce Figures 5 to 8 can be obtained from the Earth and Space Science Open Archive  
37 ([doi.org/10.1002/essoar.10501385.2](https://doi.org/10.1002/essoar.10501385.2)).

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**Author Contributions**

Per the CRediT (Contributor Roles Taxonomy) system:

Conceptualization: J.L.M., R.D.H., C.W.Ha., R.-L.B., S.R.S., W.F.B., K.J.W., H.J.C., D.S.L

Data Curation:

Formal analysis: J.L.M., C.W.He., S.R.C.

Funding acquisition: J.L.M., D.S.L, K.J.W.

Investigation: J.L.M., C.W.He. , S.R.C.

Methodology: J.L.M.

Resources:

Software:

Validation: J.L.M.

Visualization: J.L.M.

Writing – original draft: J.L.M.

Writing – review & editing: J.L.M., C.W.He. , S.R.C., R.D.H., C.W.Ha., R.-L.B., S.R.S.,

W.F.B., K.J.W., H.J.C., D.S.L.