

1 **Spatial variability of turbulent mixing from an**
2 **underwater glider in a large, deep stratified lake**

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14 **Key Points:**

- 15 • Underwater gliders are reliable platforms for scanning spatial heterogeneity and esti-
16 mating turbulent dissipation in large lakes.
- 17 • Glider-based temperature microstructure turbulence estimates reveal inhibited mixing
18 in the interior hypolimnion under stratified conditions.
- 19 • Centrifugal instabilities are a plausible explanation for augmented turbulent dissipa-
20 tion measured on a gradual coastal slope.

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21 **Abstract**

22 Spatial variability of physical properties induced by circulation and stirring remains
23 unaccounted for in the energy pathway of inland waters. Recent efforts in microstructure
24 turbulence measurements have unraveled the overall energy budget in lakes. Yet, a paucity
25 of lake-wide turbulence measurements hinders our ability to assess how representative such
26 budgets are at the basin scale. Using an autonomous underwater glider equipped with a
27 microstructure payload, we explored the spatial variability of turbulence in Lake Geneva.
28 Microstructure analyses allowed turbulent dissipation rates and thermal variances estima-
29 tions by fitting temperature gradient fluctuations spectra to the Batchelor spectrum. In
30 open waters, results indicate mild turbulent dissipation rates in the surface and thermocline
31 ($\sim 10^{-8}$ W kg $^{-1}$), which weaken towards the deep hypolimnion ($\sim 10^{-11}$ – 10^{-10} W kg $^{-1}$).
32 The strong thermal stratification inhibited interior mixing in the thermocline. In contrast,
33 measurements along the coastal slope reveal a notorious enhancement of turbulent dissipa-
34 tion ($\sim 5 \times 10^{-8}$ W kg $^{-1}$) above the sloping topography way above the known extent of the
35 bottom boundary layer. These distinct turbulence patterns result from differing large-scale
36 dynamics in the interior and coastal environments. Current measurements in open waters
37 show dominant internal Poincaré waves. On the coast, three-dimensional numerical results
38 from `meteoLakes.ch` suggest that enhanced bottom dissipations arise from the development
39 of centrifugal instabilities. A process driven by coastal cyclonic circulation interacting with
40 the sloping bottom reported for the ocean but so far overlooked in large lakes. The spatially-
41 distributed turbulence measurements we report here highlight the potential of underwater
42 glider deployments for further lake exploration.

43 **Plain Language Summary**

44 Estimating kinetic energy distribution in lakes remains challenging due to a lack of
45 lake-wide turbulence measurements. We show that underwater gliders can address this gap
46 by providing reliable maps of turbulent mixing estimates covering broad areas. Results
47 reveal clear differences in turbulence intensity and mixing between the interior and coastal
48 zones of deep Lake Geneva (Switzerland/France). In the interior, measurements show that
49 (i) turbulence variation happens mainly vertically, and (ii) strong thermal stratification
50 inhibits turbulent mixing much more than expected for such a large windy lake. Glider
51 measurements along the coastal slope, by contrast, mostly show horizontal turbulent vari-
52 ation. Also, the thickness of the bottom frictional zone at the slope, where most energy
53 dissipates, exceeds known values. We propose that centrifugal instabilities are responsible
54 for these intense turbulent dissipation measurements based on numerical simulations. Such
55 interactions between rotating currents and the bottom are known for the ocean but so far
56 overlooked in large lakes. Our findings disclose the distinct turbulence characteristic of the
57 interior and coastal regions and highlight gliders' capability for lake exploration.

58 **1 Introduction**

59 Climate change is modifying the thermal structure of lakes – rising surface water tem-
 60 peratures and strengthening background stratification (Adrian et al., 2009; Sahoo et al.,
 61 2016; Schwefel et al., 2016). In a resulting future scenario of diminished vertical transport,
 62 ecologically-relevant exchanges such as oxygen and nutrients renewal will rely primarily on
 63 three-dimensional (3D) hydrodynamic processes. Yet, the spatial variability of physical
 64 properties induced by more complex lake hydrodynamics and in particular its link to energy
 65 distribution remains poorly studied. A better understanding of lake-wide turbulent mixing
 66 can help connect these interactions and ultimately foster our ability to assess the effects of
 67 climate change on lake ecosystems.

68 The pathway of energy transference across scales, or energy cascade, is a key concept to
 69 assess the impacts of atmospheric forcing on the spatial variability of standing water bodies.
 70 External forcing transfers energy to large-scale motions providing turbulent kinetic energy
 71 (TKE) and inducing spatial variability. Then, TKE cascades to smaller scales until it dis-
 72 sipates by friction, mainly at the boundaries (Imberger, 1998). Turbulence microstructure
 73 measurements have unraveled the contributions of the interior and boundary regions for the
 74 overall kinetic energy budget in the hypolimnion of lakes (Fernández Castro, Bouffard, et
 75 al., 2021; Wüest et al., 2000). However, it is still unknown how representative these budgets
 76 are at the spatial extent, particularly for large lakes that exhibit substantial turbulence
 77 characteristics differences within a few km distances (e.g., Bouffard et al., 2012; Lemckert et
 78 al., 2004). The aim of this work is to provide insight into the spatial distribution of turbu-
 79 lent quantities in lakes’ interior and coastal regions using underwater glider measurements
 80 (Figure 1).

81 In medium-to-large lakes, wind and Earth rotation’s combined effect are a significant
 82 source of spatial variability (Csanady, 1975). Complex basin-scale processes such as coastal
 83 upwelling (Reiss et al., 2020; Roberts et al., 2021; Schladow et al., 2004), gyres (Ishikawa et
 84 al., 2002; Laval et al., 2005; Shimizu et al., 2007), and rotational internal waves (Antenucci
 85 et al., 2000; Appt et al., 2004; Bouffard et al., 2012), drive transport and stirring at a wide
 86 range of scales. Consequently, these processes will redistribute energy through the generation
 87 of turbulence and mixing. Characterizing the spatial variability ranging from basin-scale
 88 processes to small-scale turbulence, in situ, is essential to assess lake-wide energy budgets.

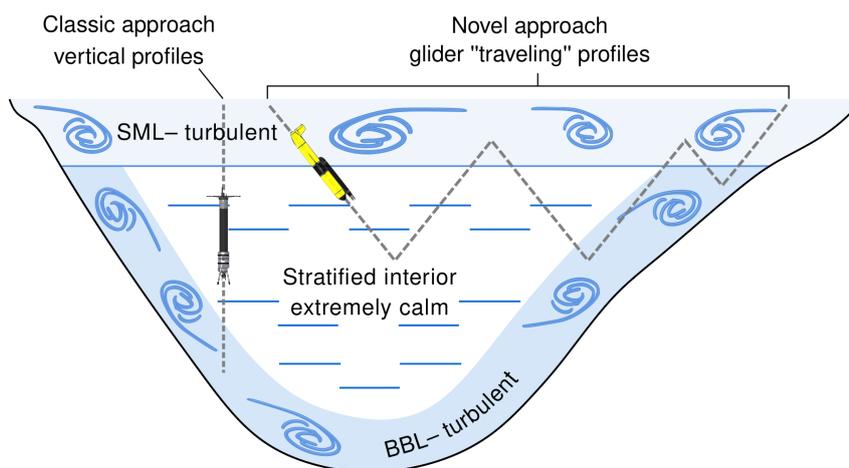


Figure 1. Schematics of turbulence intensity in a stratified lake. The sketch depicts turbulence microstructure measurements from a free-falling profiler and an underwater glider transect.

89 Spatially distributed measurements are required to characterize the spatial heterogene-
90 ity of physical and biogeochemical processes. Manual observations of spatial variability
91 such as Conductivity-Temperature-Depth (CTD) transects (Alexander & Imberger, 2013;
92 MacIntyre et al., 2002, 2014) and piloted submarine-based measurements (Fer et al., 2002;
93 Gargett et al., 1984; Osborn & Lueck, 1985; Thorpe et al., 1999) have successfully been
94 applied. However, these applications are logistically and financially prohibitive. Novel
95 autonomous measuring platforms such as self-propelled Autonomous Underwater Vehicles
96 (AUVs; Forrest et al., 2008; Laval et al., 2000) and underwater gliders (Rudnick, 2016;
97 Webb et al., 2001) enable the coupled scanning of vertical and horizontal gradients of water
98 properties with fewer restrictions. The variety of sensors integrated into underwater vehi-
99 cles, including CTDs and water quality sensors, makes them a suitable platform for studying
100 spatial variability.

101 Buoyancy-controlled autonomous underwater vehicles (aka gliders) provide sawtooth
102 transects through the water column with low levels of vibration and mechanical noise (Davis
103 et al., 2002). This feature makes them a suitable platform for turbulence measurements,
104 which require extremely low vibrations. Microstructure-based turbulence estimates using
105 gliders have been tested in deep oceanic environments featuring energetic (Fer et al., 2014;
106 Peterson & Fer, 2014) and weak (Scheifele et al., 2018) regimes as well as in the upper ocean
107 (Lucas et al., 2019) and shallow shelf seas (Schultze et al., 2017). Although the potential for
108 underwater glider deployments in lakes has been previously identified (Austin, 2013), their
109 practical application remains reduced (Austin, 2012, 2019; McInerney et al., 2019) and we
110 still lack clear assessment of the potential of glider-based turbulence observations in lakes.

111 In the present study, we sought to shed light on the turbulence characteristics of dis-
112 tinct lake regions using an underwater glider. To this end, we first validated temperature
113 microstructure turbulence estimates from a moving platform in a weakly energetic system.
114 With this technical barrier solved, we present a large and novel dataset of glider-based
115 turbulent mixing in the interior and coastal regions of a large, deep stratified lake. We
116 carry out two analyses of turbulent mixing. First, we use the lake interior results (five [5]
117 missions) to evaluate turbulent mixing parameterizations in this region and discuss par-
118 ticular aspects of strongly stratified and weakly energetic systems. Second, we focus on
119 the interior-coast transition region, where our measurements revealed a striking turbulent
120 dissipation enhancement (one [1] mission). Based upon the results of an operational 3D
121 lake forecast model (meteolakes.ch; Baracchini et al., 2020), we present a discussion of a
122 possible hydrodynamic process driving this enhanced dissipation in a specific coastal region
123 of Lake Geneva.

124 **2 Study site**

125 This study was conducted on Lake Geneva (*Lac Léman*; Figure 2), a deep (309 m
126 max. depth) and large (582 km² surface area) perialpine lake located between Switzerland
127 and France. Lake Geneva is the largest natural freshwater body in Western Europe and is
128 classified as a warm-monomictic lake where complete deep winter mixing seldomly occurs
129 (Schwefel et al., 2016). During the seasonal stratification, the thermocline is located at ~5
130 to ~10 m depth in May and gradually deepens during summer and autumn before deep
131 winter convective mixing sets in. The wind is the driving force for horizontal water mass
132 movements (Bohle-Carbonell, 1986), exhibiting two dominant winds: North-East (*La Bise*)
133 and South-West (*Le Vent*; Lemmin & D’Adamo, 1996). Previous studies highlighted the
134 role of Coriolis in the dynamics of Lake Geneva (Bauer et al., 1981; Lemmin et al., 2005;
135 Reiss et al., 2020). Particularly during summer stratified conditions, when the maximum
136 width of the lake (~14 km) is more than three times larger than the internal Rossby radius
137 (~4 km; Bouffard & Lemmin, 2013a), this rotational effect modifies the circulation and
138 stirring in the lake. Past studies of turbulence in Lake Geneva have mainly focused on the
139 near-shore region. Cooling-driven gravity currents (Fer et al., 2002) and internal Kelvin

140 wave-induced shear (Bouffard & Lemmin, 2013b; Thorpe et al., 1999) cause localized and
 141 intermittent enhancements of turbulent dissipation. In the lake interior, Michalski and
 142 Lemmin (1995) used bulk methods (e.g., Jassby & Powell, 1975) to estimate diffusivity from
 143 monthly temperature profiles, finding well above molecular levels (i.e., turbulent mixing) in
 144 the upper hypolimnion (down to ~ 90 m depth). Instantaneous microstructure turbulence
 145 measurements in this zone, up to date, have not been reported.

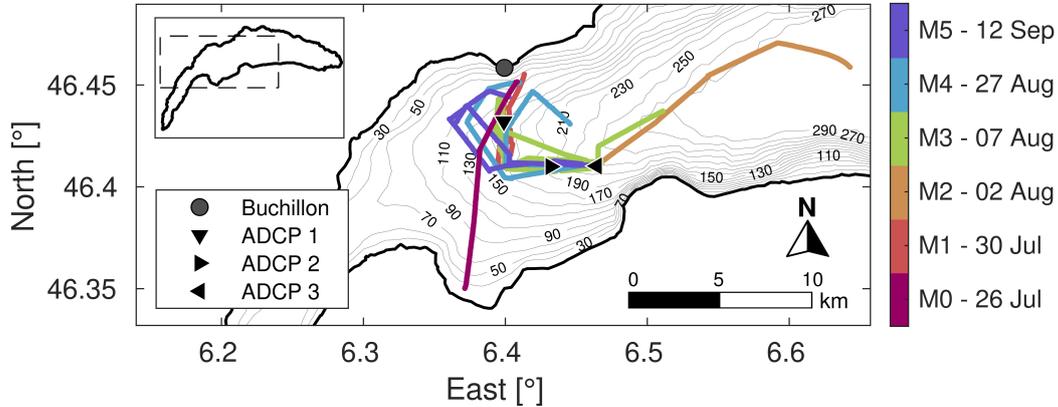


Figure 2. Study site location. Bathymetry of Lake Geneva with the location of the Buchillon station and the three moorings (ADCP 1 to 3). Color-coded lines depict glider missions M0 to M5, respectively. Dates correspond to the year 2018.

146 3 Materials and methods

147 3.1 Slocum glider and turbulence package

148 We performed spatially distributed measurements in Lake Geneva using the UC Davis
 149 glider *Storm Petrel*, a G2 Slocum underwater glider (1000 m depth; Teledyne Webb Re-
 150 search). During our sampling campaigns, the glider payload included a Sea-Bird pumped
 151 CTD, Sea-Bird ECO Puck measuring Chlorophyll-a fluorescence and an Aanderaa Op-
 152 tode dissolved oxygen (DO) sensor. Additionally, a MicroRider-1000 turbulence package
 153 (Rockland Scientific Canada) mounted on top of the glider (Fer et al., 2014) recorded mi-
 154 crostructure turbulent fluctuations. This customized instrument included two shear and
 155 two temperature microstructure channels, an inclinometer, and an accurate pressure sensor
 156 sampling at 512 Hz. The glider with the mounted MicroRider was ballasted in a freshwater
 157 pool with water density comparable to lake water.

158 3.2 Measurements

159 3.2.1 Glider transects

160 *Interior* – Our glider missions were carried out in the western part of the main basin
 161 to minimize safety hazards with summer boat activity offshore of Lausanne. The sampling
 162 strategy consisted mainly of repeated L-shaped trajectories keeping the glider away from
 163 the steep Northern-shore bathymetry (Figure 2). The glider was programmed to perform
 164 continuous dives and climbs (downcast and upcast profiles, respectively) between 3 and
 165 100 m depth, reaching the surface every 4 h for communication and GPS position update.
 166 The profiling was programmed to reach 100 m depth for navigation safety and data quality
 167 purposes. Although a deep glider (1000 m depth) is slow at turns, the adopted sampling

168 strategy enables a smooth passage through a significant portion of the water column repre-
169 senting a great range of variability and ensures that inflexions of the glider occur far away
170 from the thermocline. We programmed the glider to perform flights with a fixed pitch angle,
171 which allows for battery position adjustments throughout the missions. Still, the battery
172 position remained almost constant during each dive and climb, therefore not interfering with
173 the flight behavior. For this mission design, the glider traveled a distance of ~ 410 -450 m
174 between two dives and performed 9 to 10 yoyos (dive and climb) during the 4 h immersion
175 period.

176 *Coastal transition* – An opportunistic mission from Buchillon towards the Southern
177 shore of the lake (M0; Figure 2) allowed us to traverse a gentle slope into the coastal region.
178 The vehicle’s flight parameters were the same as for the interior missions. In particular, the
179 bottom detection system (underwater altimeter) was set with a tolerance of 10 m to the
180 bottom, allowing the glider to adjust maximal dive depth when approaching zones shallower
181 than 100 m.

182 **3.2.2 Microstructure measurements**

183 We collected temperature and shear microstructure measurements during our sampling.
184 The focus in this study is on the foremost for two reason: firstly, turbulence estimates based
185 on the temperature microstructure technique have shown better performance than shear to
186 characterize weak turbulence, as typically encountered in the stratified hypolimnion of lakes
187 (Kocsis et al., 1999) and occasionally in strongly stratified zones of the ocean (Scheifele
188 et al., 2018); secondly, shear microstructure measurements were not always available due
189 to probes damage during vehicle encounters with fishing nets. Still, the online dataset
190 includes all microstructure measurements for reproducibility and open science purposes (see
191 Data Availability Statement). A substantial amount of turbulence research in lakes (e.g.,
192 Bouffard & Boegman, 2013; Imberger & Ivey, 1991; Saggio & Imberger, 2001; Wüest et al.,
193 2000) sustains our choice to proceed with temperature microstructure only.

194 **3.2.3 Wind and current measurements**

195 A hydro-meteorological station located at Buchillon (Figure 2) provided wind speed and
196 direction measurements from a 05103 Wind Monitor anemometer (Young, USA) installed
197 at 10 m above the water level, and sampling means and gust values every 10 mins. We
198 performed current velocity profiles measurements using Acoustic Doppler Current Profilers
199 (ADCPs) to complement the glider observations with background hydrodynamic informa-
200 tion. The deployment comprised three suspended upward-looking ADCPs installed in the
201 open water region (Figure 2), in addition to a long-term deployment of a bottom-moored
202 upward-looking ADCP at Buchillon station. Installation of ADCP moorings 1 to 3 con-
203 sisted of lines equipped with subsurface floaters at their uppermost end (~ 50 m depth).
204 Each ADCP was installed within a frame assembled to the line, 5 m below the floater (as-
205 suring no signal interference). An acoustic releaser system was also installed at the bottom
206 to retrieve the instruments. This setup allowed scanning the upper part of the water column
207 with a reasonable resolution given the local restriction due to professional fishing in the top
208 50 m. Table 1 lists ADCPs information and deployment depths.

209 **3.3 Flight model**

210 Glider along-path speeds (U) are required to perform accurate turbulence estimations.
211 These are used to treat the microstructure data with the Taylor frozen-flow hypothesis
212 (section 3.4). Nevertheless, the vehicle’s speed through water cannot directly be obtained
213 from instrumentation commonly mounted on gliders and *Storm Petrel* is no exception. To
214 address this lack of data, we implemented an underwater glider flight model (Frajka-Williams
215 et al., 2011; Merckelbach et al., 2010). Specifically, we used the dynamic flight model of

Table 1. Details of instruments deployed on each station (Figure 2). Each station was equipped with a Teledyne RD Workhorse Sentinel of the specified frequency. ADCPs 1 to 3 were installed from 25 July to 10 October 2018.

Station	Frequency [kHz]	Ensemble interval [min.]	Installation depth [m]	Bin size [m]
Buchillon	600	15	38	0.75
ADCP 1	600	10	50	1.0
ADCP 2	600	10	42	1.0
ADCP 3	300	5	46	1.0

216 Merckelbach et al. (2019). Details of the implementation are presented in the Supporting
217 Information (SI; Text S1 and Figure S1).

218 3.4 Turbulence estimations and mixing quantities

219 3.4.1 Turbulent dissipation from temperature microstructure

220 The possibility to estimate turbulence from temperature microstructure sensors (fast
221 thermistors) mounted on gliders has already been successfully demonstrated (Peterson &
222 Fer, 2014; Scheifele et al., 2018). Measurements carried out with these sensors can be used
223 to estimate rates of turbulent kinetic energy dissipation ε (W kg^{-1}) by fitting the measured
224 temperature gradient spectra (S_{obs}) to a theoretical spectral shape $S = S(k_C, \chi_\theta)$, as a
225 function of a cutoff wavenumber (k_C) and the smoothing rate of temperature variance, χ_θ
226 ($^\circ\text{C}^2 \text{ s}^{-1}$).

227 Here, we adjust S_{obs} to the Batchelor (1959) spectrum, S_B , to extract turbulence
228 information from the microstructure data. Performing such spectral fitting allows us
229 to infer ε estimates because the Batchelor cutoff wavenumber, k_B (cpm), is defined as a
230 function of ε by:

$$k_B = \frac{1}{2\pi} \left(\frac{\varepsilon}{\nu D_T^2} \right)^{\frac{1}{4}} \quad (1)$$

231 where $\nu \approx 1.5 \times 10^{-6} \text{ m}^2 \text{ s}^{-1}$ is the kinematic viscosity and $D_T = 1.4 \times 10^{-7} \text{ m}^2 \text{ s}^{-1}$ is the
232 molecular thermal diffusion coefficient at hypolimnion temperatures. This data processing
233 employs the maximum likelihood spectral fitting method (Ruddick et al., 2000) to estimate
234 ε , coupled with the Steinbuck et al. (2009) approach to calculate χ_θ .

235 The first step of the procedure is to obtain S_{obs} . To do so, the fast thermistors data are
236 first treated with a frequency response correction following Sommer et al. (2013). Afterward,
237 the data processing is similar to the methodology of Scheifele et al. (2018). However, we
238 use half-overlapping microstructure temperature segments of 10 s to calculate frequency
239 spectra instead of 40 s. This data treatment allows us to maximize the amount of S_{obs} for
240 turbulence analysis without compromising data quality (see section 4.2).

241 Then, the procedure requires obtaining χ_θ . Here we take advantage of the Steinbuck et
242 al. (2009) correction to filter fine-scale fluctuations (Gregg, 1977) and possible low-frequency
243 vehicle-induced contamination by modifying some commonly used parameters (namely k_l
244 and k_u in Eq. 2). The calculation of χ_θ is performed with the following integral:

$$\chi_\theta = \chi_l + \chi_{obs} + \chi_u = 6D_T \left(\int_o^{k_l} S_B dk + \int_{k_l}^{k_u} (S_{obs} - S_n) dk + \int_{k_u}^\infty S_B dk \right) \quad (2)$$

245 with the factor 6 for assuming isotropy. The lower wavenumber end of the measured spectra
 246 (k_l) is obtained by considering $k_l = \max\{\text{first } k_{obs} > 0; 3k_*\}$, where $k_* = 0.04k_B(D_T/\nu)^{1/2}$
 247 is the so-called transitional wavenumber separating the inertial and viscous-convective sub-
 248 ranges (Dillon & Caldwell, 1980). Whereas the upper wavenumber end (k_u) is the intersec-
 249 tion of S_{obs} with the noise spectra S_n . Outside the range defined by k_l and k_u , given the
 250 lack of reliability of S_{obs} , Steinbuck et al. (2009) propose to use the theoretical expression
 251 of S_B to obtain the fringe contributions of χ_l and χ_u .

252 By coupling the estimation of χ_θ and S_B and solving iteratively for k_B , we can finally
 253 obtain ε . Turbulence analyses exclude data collected 5 m within turning points as these
 254 present diminished data quality from vibrations and may not satisfy the Taylor frozen-
 255 flow hypothesis (Fer et al., 2014). Dissipation estimates obtained from poorly resolved
 256 spectra, which do not comply with the Bachelor fitting, are discarded following the likelihood
 257 and mean absolute deviation criteria Ruddick et al. (2000) proposed. For temperature
 258 microstructure, the detection floor of ε is in the range of 10^{-12} to 10^{-11} W kg $^{-1}$ (Luketina
 259 & Imberger, 2001; Steinbuck et al., 2009).

260 Turbulent quantities often exhibit lognormal character. Statistical analyses, therefore,
 261 used the maximum likelihood estimator (mle) for lognormal distributions (Baker & Gibson,
 262 1987). This approach reduces the influence of extreme values and provides ad-hoc estimates
 263 of statistical variability through the intermittency factor $\langle \sigma_{mle}^2 \rangle$, which is denoted by pointy
 264 brackets, $\langle \cdot \rangle$, throughout the article.

265 **3.4.2 Turbulent mixing characteristics**

266 Mixing is quantified using χ_θ by following the Osborn and Cox (1972) diapycnal diffu-
 267 sivity model, defined as:

$$K_T = \frac{\chi_\theta}{2 \left(\frac{\partial \bar{T}}{\partial z} \right)^2} \quad (3)$$

268 where $\partial \bar{T} / \partial z$ is the background temperature gradient, obtained by calculating the slope of
 269 T in the vertical segment of interest through linear regression.

270 We use the isotropic version of the Cox number to quantify the turbulent to molecular
 271 vertical mixing ratio, defined as (Thorpe, 2007):

$$C_x = 3 \frac{\left(\frac{\partial T'}{\partial z} \right)^2}{\left(\frac{\partial \bar{T}}{\partial z} \right)^2} = \frac{K_T}{D_T} \quad (4)$$

272 where $\partial T' / \partial z$ is the temperature fluctuation gradient. This also accounts for the strength of
 273 turbulent fluctuations compared to the background temperature gradient. We use directly
 274 K_T obtained from Eq. (3) to compute Cox numbers.

275 To account for mixing efficiency, we use the flux Richardson number (Ri_f ; Monismith
 276 et al., 2018). Assuming steady and homogeneous turbulence, the local shear production (P)
 277 balances with the sum of buoyancy flux and dissipation (i.e. $P = B + \varepsilon$; Ivey & Imberger,
 278 1991). Hence, we can define Ri_f as:

$$Ri_f = \frac{B}{B + \varepsilon} \quad (5)$$

279 where $B = K_T N^2$ is the buoyancy flux and $N^2 = g \rho_o^{-1} \partial \rho / \partial z$ is the water column stability,
 280 $g = 9.81$ m s $^{-2}$ and z is the depth coordinate (positive downwards). Freshwater density, ρ ,
 281 is calculated from CTD data using methods ad-hoc with TEOS 2010 (McDougall & Barker,
 282 2011) and $\rho_o = 1000$ kg m $^{-3}$ is the freshwater reference density. The density gradient,
 283 $\partial \rho / \partial z$, is obtained through linear regression of ρ in the vertical segment of interest.

284 To characterize the intensity of turbulence with respect to stratification, we use the
 285 buoyancy Reynolds number (Gibson, 1980):

$$Re_b = \frac{\varepsilon}{\nu N^2} \quad (6)$$

286 which defines three energy regimes (Ivey et al., 2008): molecular ($Re_b < 7$), transitional
 287 ($7 < Re_b < 100$) and turbulent ($Re_b > 100$).

288 3.5 Horizontal kinetic energy

289 We use the ADCP current data to determine the depth-integrated horizontal kinetic
 290 energy (HKE), as follows:

$$\text{HKE} = \frac{1}{2} \int_0^{z_{\text{ADCP}}} (u^2 + v^2) dz \quad (\text{m}^3 \text{s}^{-2}) \quad (7)$$

291 where u and v are the East and North current components, respectively. The vertical
 292 integration range is considered from the surface ($z = 0$ m) to $z_{\text{ADCP}} = 40$ m depth. An
 293 approximation of the characteristic radius resulting from current-induced circulation at a
 294 specific frequency band (f^*) can then be defined as:

$$R^* = \frac{\sqrt{2\overline{\text{HKE}^*} z_{\text{ADCP}}^{-1}}}{2\pi f^*} \quad (8)$$

295 where $\overline{\text{HKE}^*}$ is the mean of the f^* -bandpass filtered HKE.

296 4 Results

297 This research explores the capabilities of underwater gliders for studying spatial vari-
 298 ability in a large lake. Glider *Storm Petrel* was deployed in Lake Geneva in the summer
 299 of 2018 to connect large-scale spatial variability to turbulence activity. Throughout the
 300 six missions considered in this study, we measured 345 yo-yo sets equivalent to 155 h of
 301 sampling, covering a lake surface distance of 158 km. Next, we present an overview of the
 302 data collected by the glider, a turbulence estimate assessment, a comparison of turbulence
 303 and mixing conditions between interior and coastal regions of the lake, and the sources of
 304 spatial variability evaluated from wind and ADCP measurements.

305 4.1 Glider measurements

306 *Interior* – We show a time-series example of data collected during mission M2 (Figures
 307 3a,b), consisting of a long transect through the middle of the lake (Figure 2). This and
 308 the other interior missions, accompanied by water quality parameters less relevant for the
 309 analysis presented herein (namely Chlorophyll-a and dissolved oxygen), are presented in the
 310 SI (Figures S2-S6). Mission-composite averaged profiles during M2 show a marked vertical
 311 structure (Figures 3c,d). Temperature data show a strong vertical stratification (Figure 3c).
 312 However, a more careful analysis of the transect reveals lateral heterogeneity in the top 50 m
 313 with varying thermocline depths (depicted by $\sim 15^\circ\text{C}$ isotherm; Figures 3a,b). The first 4 h
 314 of this mission presented colder temperatures close to the surface, suggesting a thermocline
 315 uplift in the eastern part of the main basin. Although presenting a vertically consistent
 316 decay (Figure 3d), fast temperature gradients exhibit horizontal variability with sharper
 317 gradients in the upper water column (Figure 3b). Considering $\text{abs}(T \text{ grad.}) > 0.4 \text{ }^\circ\text{C m}^{-1}$ as
 318 a proxy for the thermocline, the gradient time-series indicates two thermocline uplift regions
 319 (at the beginning of the mission and around 2 Aug 2018 – 18:00; Figure 3b). Similar yet
 320 subtle spatio-temporal variability was observed during other missions (see Figures S2-S6).

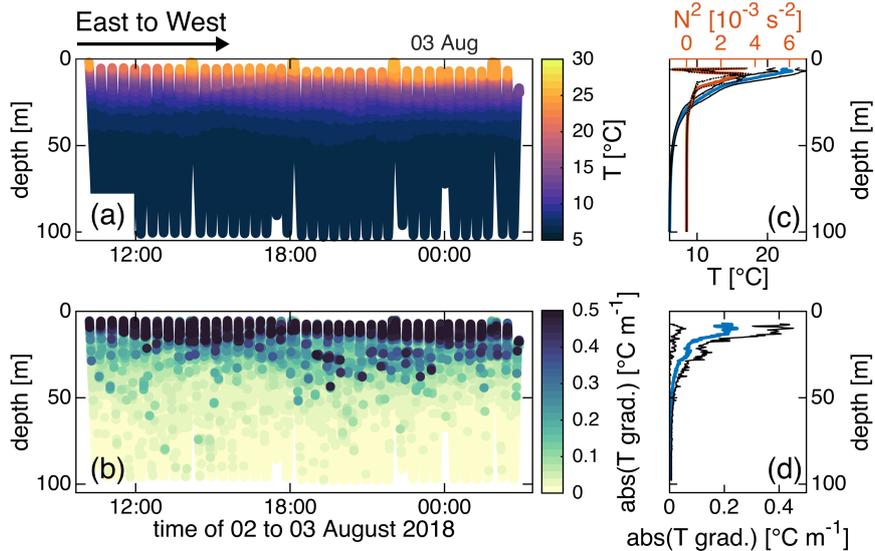


Figure 3. Example of lake-interior glider data collected on 2-3 August 2018 during mission M2. (a) Temperature (T). (b) Absolute value of the temperature gradient measured with the MicroRider, sub-sampled at 4 Hz for visualization. Time increase corresponds to E-W direction (Figure 2). (c-d) Time-averaged profiles (blue lines) of measurements presented in (a-b), accompanied by their respective standard deviations (black line envelopes). Additionally, (c) shows the depth-averaged stability (N^2) profile for mission M2 (red line) with its standard deviation (black dotted envelope).

321 *Coastal transition* – The time series of the cross-shore mission M0 (Figures 4a,b) shows
 322 similar temperature characteristics as M2. However, the fast temperature gradient struc-
 323 ture shows marked spatial heterogeneity with an enhancement toward the slope. Averaged
 324 profiles (Figures 4c,d) depict a similar vertical structure as the pelagic profiles with a strong
 325 vertical stratification (Figure 3c). Overall, M0 shows a stratified water column with en-
 326 hanced variability towards the shore, highlighting the different characteristics between the
 327 interior and coast. Enhanced temperature gradient fluctuations at the slope suggest a flow-
 328 bathymetry interaction. Details of the water quality parameters collected during M0 are
 329 presented in Figure S7.

330 4.2 Turbulence estimates assessment

331 To evaluate the microstructure analysis methodology for ε and χ_θ estimates, we per-
 332 formed a statistical assessment of the non-dimensional spectral shapes for temperature fluc-
 333 tuations following Dillon and Caldwell (1980). Here, we examine spectra from dives and
 334 climbs combined, while separated analyses are presented in the SI (Figures S8, S9). This
 335 analysis considers spectra calculated from each fast thermistor as separate samples (no av-
 336 eraging). Figure 5 shows ensemble averages of microstructure temperature gradient spectra
 337 treated with the procedure described in section 3.4 that meet the Ruddick et al. (2000)
 338 criteria and compare them with S_B for different Cox number (C_x) ranges. Considering
 339 measurements 5 m away from the glider’s vertical turning points, 60 % of the 91,454 spectra
 340 analyzed were non-compliant with this criterion and therefore discarded. For small C_x , i.e.,
 341 when the background temperature gradients are more prominent than those imposed by
 342 turbulent fluctuations, spectra present a shape seemingly in disagreement with the Batch-
 343 elor form in the lower wavenumber range. For wavenumbers above the spectral maximum,
 344 observed spectra show, in general, good agreement with S_B . This resemblance is evident
 345 for a wide range of C_x , namely $C_x > 0.1$ (Figure 5c-f).

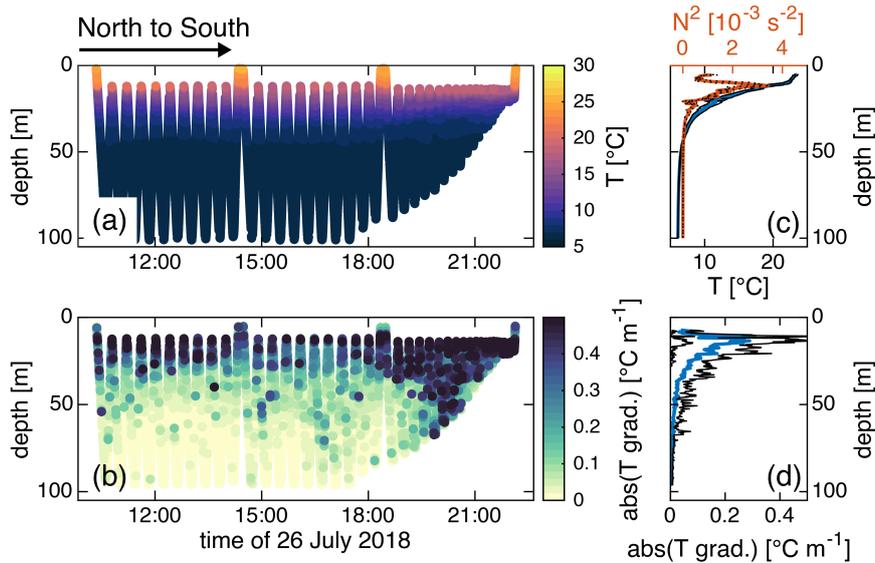


Figure 4. Cross-shore (interior-to-coast) glider data collected on 26 July 2018 during mission M0. Panels are analogous to Figure 3.

346 The specific evaluation of our procedure to calculate χ_θ (Eq. 2), requires a careful
 347 analysis of the S_{obs} ensembles at their wavenumber extremes (Figure 5). At the upper
 348 wavenumber end, the intersection of S_{obs} with S_n defines the cutoff and the maximum
 349 likelihood method (Ruddick et al., 2000) prevents an overestimation of χ_θ by avoiding the
 350 noise-dominated region. For low wavenumbers, the ensemble averages detach from the
 351 theoretical form, S_B , possibly due to vehicle-induced vibrations and or stratification fine-
 352 scale structures. This deviation becomes more evident at the lower wavenumber end of the
 353 spectra for $C_x < 10$ (Figures 5a-d). However, the variance-preserving spectra (circles in
 354 Figure 5) show that the statistical variability introduced by S_{obs} , not complying with the
 355 theoretical S_B shape, affects only wavenumbers below $3\alpha_*$ (where α_* is the non-dimensional
 356 form of k_*) for $C_x < 0.1$ and it is therefore filtered out. These results hold for separated
 357 dive and climb analyses (Figures S8, S9). Figure 5 thus shows that our Batchelor spectra
 358 fitting procedure performs overall reliably, capturing temperature gradient variance at the
 359 relevant wavenumber range, and resulting turbulence quantities can be trusted.

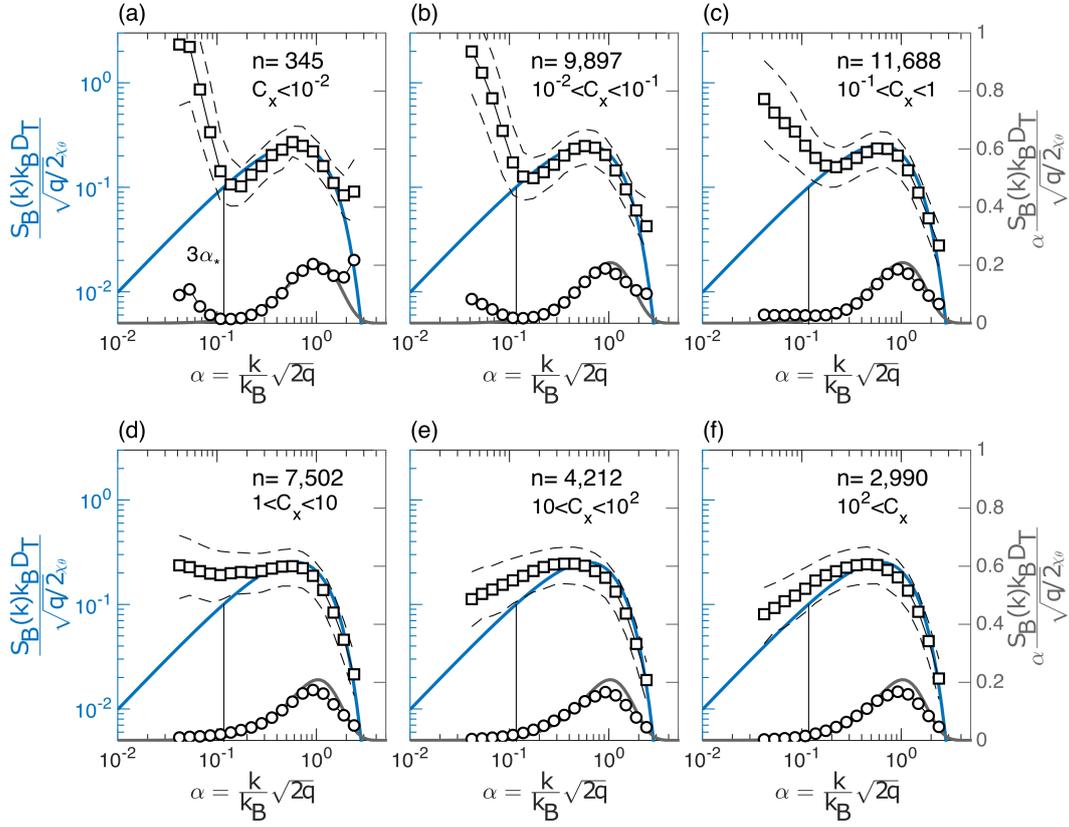


Figure 5. Spectral statistics following Dillon and Caldwell (1980). (a-f) The left y-axis corresponds to ensemble-averaged non-dimensional spectrum (squares) as a function of the non-dimensional wavenumber, α , for Cox numbers (C_x) specified in the top right corner of each panel. This analysis considers spectra meeting the Ruddick et al. (2000) criteria from all missions (including both dives and climbs), with n indicating the number of evaluated spectra. Dashed envelope represent 25th and 75th percentile confidence intervals, respectively. The blue line is the non-dimensional Batchelor spectrum $\frac{S_B(k)k_B D_T}{\sqrt{(q/2)\lambda_\theta}}$, where $q = 3.4$ is the universal spectral constant. The value $\alpha_* = 0.04\sqrt{\frac{D_T 2q}{\nu}} \approx 0.03$ (vertical black lines) corresponds to the non-dimensional form of the transitional wavenumber k_* . The right y-axis corresponds to the variance-preserving plot of ensemble-averaged non-dimensional spectrum (circles) presented in the left y-axis. Gray line is the variance-preserving non-dimensional Batchelor spectrum $\alpha \frac{S_B(k)k_B D_T}{\sqrt{(q/2)\lambda_\theta}}$.

4.3 Turbulence and mixing: Comparison between interior and coastal slope

4.3.1 Statistical and vertical distribution of turbulent quantities

Using the methods described in section 3.4.1, we obtained turbulent dissipation (ε) and temperature variance smoothing rates (χ_θ) for all glider missions (Figure 6 and Table 2). Here, the analysis considers averages of the estimates compliant with the procedure from the twin fast thermistors. We discarded 47% of (averaged) estimates and refer to those considered here as samples. Examinations presented in this section concern dives and climbs combined, while separated analyses are presented in Figure S10 (SI).

For the lake interior, distributions of turbulent quantities (22,762 samples) appear log-normal; however, their log-data kurtosis was 2.4 for ε and 3.6 for χ_θ , distant from the expected value of 3 (lognormal distribution kurtosis). The mle-mean (intermittency factor) and median for ε were $2.0 \times 10^{-8} \text{ W kg}^{-1}$ $\langle 9.8 \rangle$ and $9.8 \times 10^{-11} \text{ W kg}^{-1}$, respectively. Whereas for χ_θ the mle-mean and median were $5.7 \times 10^{-8} \text{ }^\circ\text{C}^2 \text{ s}^{-1}$ $\langle 10.7 \rangle$ and $1.8 \times 10^{-10} \text{ }^\circ\text{C}^2 \text{ s}^{-1}$, respectively. These results indicate overall weak-to-moderate turbulence. Distributions of the interior-to-coast mission (M0; Figures 6b,d) show similar characteristics, although high levels of turbulence were more frequent. Considering 2,368 samples, the log-data kurtosis of M0's turbulence estimates was 2.3 for ε and 2.6 for χ_θ . Dissipation rates for M0 were in the same range as in the interior (M1-M5), with mle-mean and median ε values of $2.6 \times 10^{-8} \text{ W kg}^{-1}$ $\langle 8.6 \rangle$ and $3.5 \times 10^{-10} \text{ W kg}^{-1}$, respectively. Temperature variance smoothing rates were, however, one order of magnitude larger for M0 than for the interior, with $2.5 \times 10^{-7} \text{ }^\circ\text{C}^2 \text{ s}^{-1}$ $\langle 10.7 \rangle$ and $1.2 \times 10^{-9} \text{ }^\circ\text{C}^2 \text{ s}^{-1}$. Probability density distribution comparisons of the subsets considered for ε and χ_θ are presented in Figures 6c and 6f.

High dissipation values appear correlated with strong stratification. The stability (N^2) color code indicates a marked concentration of samples obtained under strong stratification on the higher end of ε and χ_θ histograms (Figures 6a,b,d,e). These N^2 values correspond to the upper part of the water column (Figure 7), and considering the upper 20 m ($\sim 40 \times 10^{-5} \text{ s}^{-2}$) as a threshold, both sets present 18.8 % of samples with a strong background stratification. We also analyze the different sections of the water column, namely the epilimnion (surface layer), metalimnion (thermocline), and hypolimnion of the whole dataset to explore this dissipation response to stratification (Figures 6c,f and Table S1 second row). The metalimnion is defined here as the depth range where N^2 exceeds a value of $200 \times 10^{-5} \text{ s}^{-2}$. Epi- and metalimnion combined exhibit ε mle-means two orders of magnitude larger than in the hypolimnion, which reduces to one order of magnitude when considering the median. For χ_θ , the same comparison results in two orders of magnitude difference for both estimators. This N^2 - ε dependence is further sustained by a positive linear relation in log-log space when combining all missions samples ($\log_{10}(\varepsilon/\varepsilon_{median}) = \log_{10}(N^2/N^2_{median}) - 0.17$; $R^2 = 0.74$ and p-value ≈ 0).

Vertical distributions (Figures 7 and S11) show an overall decay of ε and χ_θ with depth. The N^2 color code reveals maximal values of ε in the zone of sharper gradients (i.e., maximal N^2). For measurements in the interior (Figure 7a), dissipation shows an increase when approaching 100 m depth. We attribute this to glider flight maneuvers close to its maximal mission depth (100 m), and measurements performed closer to the lake's Northern steep coastal region (see Figure 2), which may present enhanced turbulent dissipation due to its proximity to the bottom. This last characteristic is evident for measurements performed adjacent to the sloping topography during M0 (Figure 7b), which show more significant variability throughout the water column.

When analyzing turbulence estimates from dives and climbs separately (Figure S10 and Table S1, first row), probability distributions have a good resemblance and differ overall by a factor of 5 for ε and 2 for χ_θ regarding mle-means (1.5 for both in terms of median). Similarly, depth-averaged vertical profiles (Figures S10b,e) also show good agreement. Figure S10b indicates that for ε dives and climbs, the main discrepancies locate below the thermocline

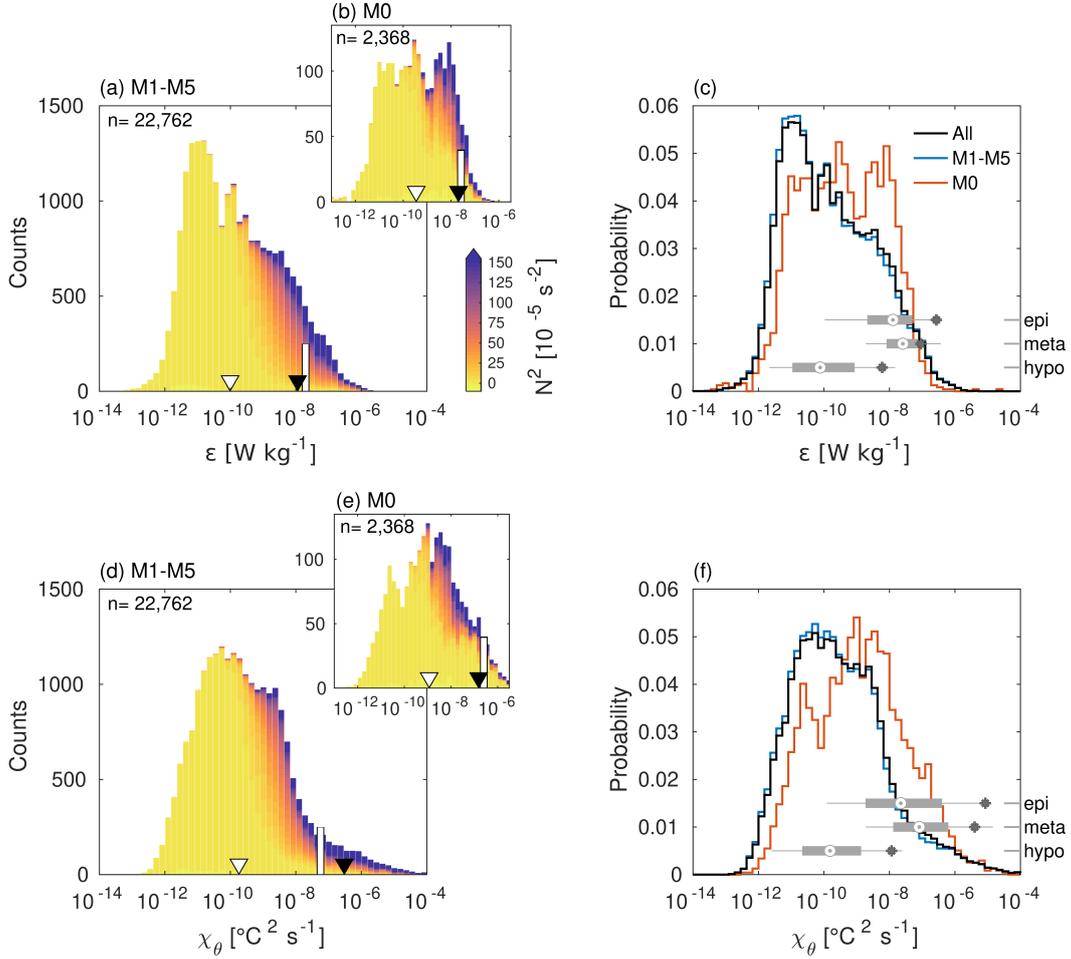


Figure 6. Statistics of measured turbulent characteristics. (a, b) Histograms of turbulent dissipation ε grouped for lake interior (M1-M5) and interior-to-coast transition (M0), respectively, and color-coded for water column stability (N^2). White vertical bars correspond to the mle-mean for a log-normal distribution (Baker & Gibson, 1987), while white and black triangles represent the median and arithmetic mean, respectively. (c) Probability distributions of ε for the whole data set (“All”) as well as for the sub-sets described in (a) and (b), accompanied by boxplots of the distinct stratified water column layers, namely: epilimnion, metalimnion (containing the thermocline), and hypolimnion. Boxplots depict median values (dotted circles) with vertical bars and lines representing the 25/75th and 5/95th percentiles, respectively. Asterisks depict mle-means. The calculations consider the metalimnion as the water column portion exceeding $N^2 = 1.5 \times 10^{-3} \text{ s}^{-2}$, with the epi- and hypolimnion the volumes above and below, respectively. (d, e, f) Analogous statistics as in (a, b, c) for the smoothing rate of temperature variance χ_θ . The analysis considers only estimations that meet the Ruddick et al. (2000) criteria. Displayed data points were obtained by averaging the two estimates from the twin fast thermistors mounted on the MicroRider. Data segments with only one sample meeting the criteria were also considered.

Table 2. Statistical summary of the measured turbulent characteristics. Results are reported threefold: (i) mle-mean for lognormal distribution following Baker and Gibson (1987) accompanied by its intermittency factor (σ_{mle}^2), (ii) median values with its respective 25th and 75th quantiles, and (iii) arithmetic mean (\bar{x}) \pm standard deviation (std).

Parameter	Estimator	M1-M5	M0	All
ε [10^{-8} W kg $^{-1}$]	mle-mean $\langle \sigma_{mle}^2 \rangle$	2.0 (9.8)	2.6 (8.6)	2.1 (9.7)
	median [25 th , 75 th]	0.010 [0.0012, 0.15]	0.035 [0.0033, 0.40]	0.011 [0.0013, 0.17]
	$\bar{x} \pm \text{std}$	1.1 \pm 7.5	2.1 \pm 58.0	1.2 \pm 19.2
χ_θ [10^{-8} °C 2 s $^{-1}$]	mle-mean $\langle \sigma_{mle}^2 \rangle$	5.7 (10.7)	25.4 (10.7)	7.2 (10.9)
	median [25 th , 75 th]	0.018 [0.0024, 0.19]	0.12 [0.011, 1.1]	0.021 [0.0026, 0.23]
	$\bar{x} \pm \text{std}$	30.1 \pm 586.6	15.3 \pm 135.8	28.7 \pm 559.8

411 and close to the maximal mission depth. This suggests that buoyancy-induced changes in
412 the vehicle’s velocity, either induced by the water column or by the vehicle navigation, affects
413 estimates reliability. Yet, Q-Q plots comparing distributions of ε and χ_θ by stratification
414 range indicate that the agreement between dives and climbs is overall acceptable (Figures
415 S10c,f). This result agrees with glider-based temperature microstructure observations in
416 strongly stratified oceanic waters by Scheifele et al. (2018), who reported no significant ε
417 estimations differences between dives and climbs.

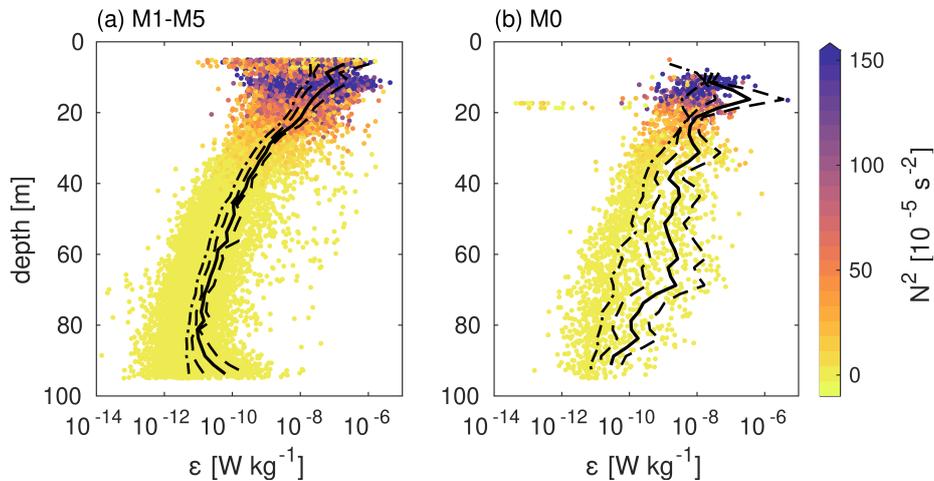


Figure 7. Vertical distribution of measured turbulent dissipation. (a) Interior (M1-M5) and (b) interior-to-coast transition (M0). Thick black line and dashed envelope correspond to the mle-mean and statistical variability given by the intermittency factor, respectively. The dot-dashed line represents the median. Data selection criteria is the same as in Figure 6.

418 4.3.2 Turbulent mixing

419 We present depth-averaged vertical profiles to analyze the mixing characteristics of the
420 water column for the two regions (Figure 8). In the interior, all three mixing parameters
421 show maximal values in the epilimnion (Figure 8a-c), a zone usually directly influenced by

422 wind forcing. Vertical profiles of C_x and Ri_f (Figures 8a,b, respectively) present minimum
 423 values around 20 m depth. The vertical profile of Re_b (Figure 8c) shows that the water
 424 column lies almost entirely within the transitional regime ($7 < Re_b < 100$). Figures 8a-
 425 c show that the strong stratification inhibits mixing ($C_x < 1$, $Ri_f < 0.1$, and $Re_b < 30$)
 426 between 10 and 40 m depth which comprises the thermocline region. This result is similar
 427 to that reported by Fernández Castro, Sepúlveda Steiner, et al. (2021) for deep Lake Zurich
 428 during stratified conditions.

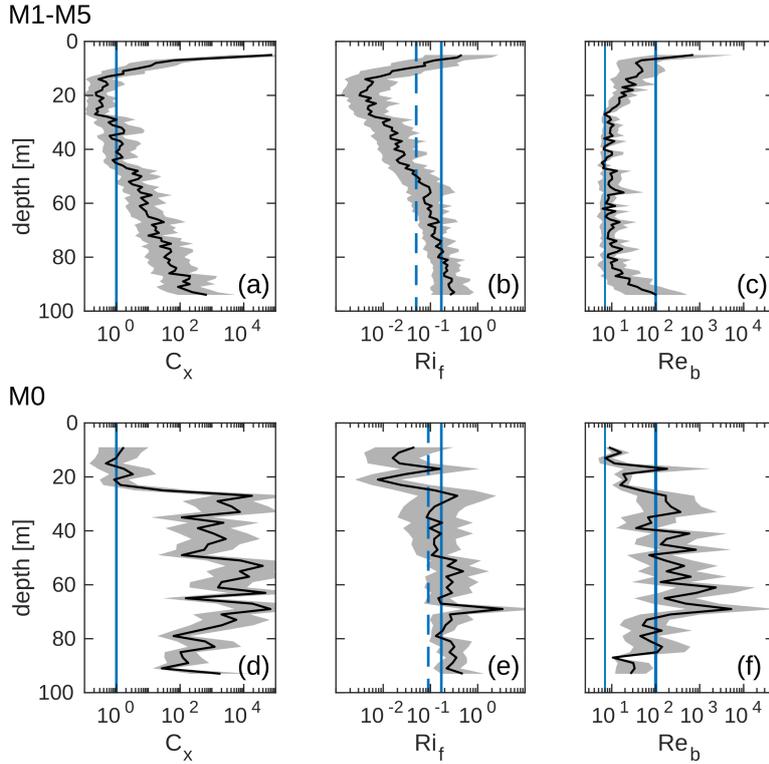


Figure 8. Average profiles of mixing quantities. (a-c) Lake interior (M1-M5) mle-mean profiles (black lines) of C_x , Ri_f and Re_b , respectively. Gray areas in (a-c) represent statistical variability given by the intermittency factor ($\langle \sigma_{mle}^2 \rangle$). The blue line in (a) is $C_x = K_T D_T^{-1} = 1$. The continuous blue line in (b) represents the canonical oceanic mixing efficiency $Ri_f = 0.17$ (Osborn, 1980). In (c), thin and thick blue lines depict the lower and upper limits of the transitional regime ($7 < Re_b < 100$; Ivey et al., 2008). (d-f) Analogous to (a-c) for the interior-to-coast transition (M5). Dashed lines in (b) and (e) show medians of Ri_f , satisfying $C_x > 1$ and $1 < Re_b < 1000$, in the interior ($Ri_f = 0.05$) and interior-to-coast transition ($Ri_f = 0.09$), respectively.

429 Conversely, for the interior-to-coast data, the Cox number profile (Figure 8d) clearly
 430 shows that in the thermocline region, temperature gradient fluctuations overcome the back-
 431 ground stratification, with higher Ri_f values (Figure 8e) and a transitional-to-turbulent
 432 energetic regime (Figure 8f). Yet, M0 depth-averaged profiles show minimal values for the
 433 three mixing parameters at depths depicting strong stratification (see also Figure 7b), which
 434 agrees with observations at the interior. The more consistent vertical structure of the in-
 435 terior profiles compared with those in the interior-to-coast mission can be attributed to (i)
 436 the large difference in the number of samples per depth considered (five versus one mission)
 437 and (ii) the boundary condition imposed by the lake bathymetry that is likely to result

438 in current-slope interactions driving enhanced turbulence and variability. Altogether the
 439 interior shows weak turbulent mixing, which increases when approaching the coast.

440 4.4 Enhanced dissipation towards the coastal slope

441 Unlike the more uniform interior estimates of dissipation (M1-M5; Figures 7a), M0
 442 shows a scattered distribution (Figure 7b). To better understand the differences between
 443 interior and littoral regions, we present turbulent dissipation estimates for M0 as a transect
 444 (Figure 9a). The analysis reveals a notorious spatial variability and augmented values at
 445 the sloping topography ($\varepsilon \approx 5 \times 10^{-8} \text{ W kg}^{-1}$). For the 60 to 80 m depth range, dissipation
 446 estimates between interior and slope differ by 3 to 4 orders of magnitude. The enhanced
 447 turbulence adjacent to the sloping topography consistently localizes at depths above the
 448 known extent of bottom boundary layers in Lake Geneva ($\sim 10 \text{ m}$; Bouffard & Lemmin,
 449 2013a) and, in general, for medium (e.g., Wüest et al., 2000) and large lakes (Ravens et al.,
 450 2000; Troy et al., 2016). Therefore, another hydrodynamic process may have triggered this
 451 response.

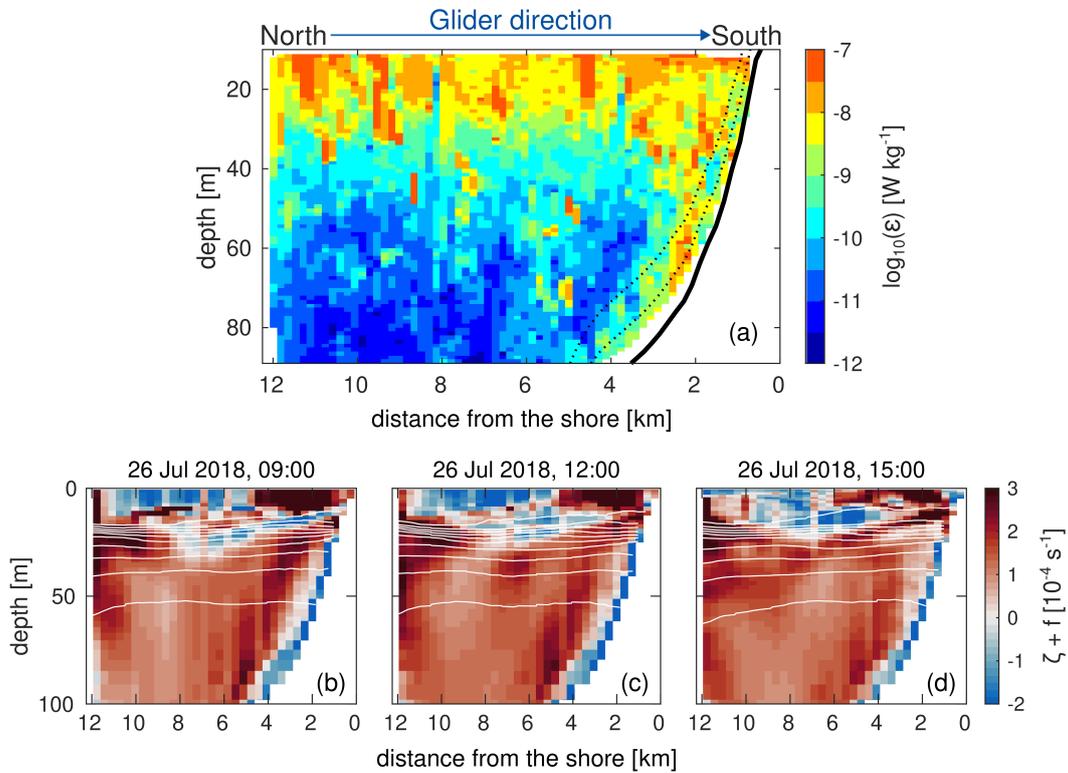


Figure 9. Cross-shore lateral variability. Data corresponding to mission M0, performed on 26 Jul 2018, starting at 10:50 am local time. (a) Glider-based turbulent dissipation (ε). The thick black line represents the lake bottom, with dotted black lines depicting the vertical displacements of the lake bed by 10 and 20 m, respectively. The collection of microstructure data was only possible due to the gentle slope of the mapped area. (b-d) Transects showing the sum of vertical relative vorticity, ζ , and the inertial frequency, f , as obtained from `meteoLakes.ch` for different times of the same day. White lines in (b-d) correspond to temperature isolines.

452 4.5 Sources of variability

453 During the field campaign, wind measurements (Figure 10a) show moderate intensity,
454 occasionally exceeding 5 m s^{-1} , and a predominant North-East direction (*La Bise*). Strong
455 winds, consistently exceeding 5 m s^{-1} , were sporadic and associated with Le Vent events
456 (South-West winds). Overall, the primary forcing was *La Bise* and exhibited a daily cycle
457 (Figure 10b).

458 We complemented our glider measurements with observations of horizontal current pro-
459 files at four different locations to obtain background information on basin-scale processes,
460 which drive spatial variability. Time series of current measurements from the four sta-
461 tions (Figure 2) are presented in Figure S12. Currents at the Buchillon coastal station
462 (shallow waters) were more energetic than those measured in the interior, with dominant
463 low-frequency periodicities (Figures 10b,c). In the lake interior, currents' rotary spectra
464 (Figures 10b,c) were remarkably similar for the three open water monitored locations (AD-
465 CPs 1 to 3). Energized frequencies near the inertial frequency (period of $\sim 16.6 \text{ h}$ for L.
466 Geneva) in the clockwise component indicate the presence of Poincaré internal waves. This
467 phenomenon has been identified to generate turbulent mixing in the lake interior (Bouffard
468 et al., 2012). However, our results (Figure 8a-c) do not support that mechanism of mixing
469 generation. At the Buchillon shore station, spectral energy levels at low frequencies exceed
470 those of the interior. These peaks occur at the expected bands of basin-scale internal Kelvin
471 waves (Bouffard & Lemmin, 2013a) and gyres.

472 Times series of band-pass filtered HKE at the near-inertial frequency (Figure 10d) were
473 markedly variable during the glider missions. The level of energy contained in the near-
474 inertial range was high during M3 but minimal during M1 and M5. Inertial currents radius
475 (Figure 10d) was 0.2 to 0.4 km during the glider missions, which given our programmed
476 flight mission ($\sim 0.5 \text{ km}$ between consecutive yo's), it is not optimal for detecting spatial
477 variability.

478 5 Discussion

479 5.1 Glider deployments and their sampling potential in lakes

480 This study reports and evaluates spatiotemporal heterogeneities of turbulence in a large
481 lake using an underwater glider. While mounting turbulence packages on gliders is now close
482 to standard for oceanic measurements (e.g., Fer et al., 2014; Scheifele et al., 2018), such ob-
483 servations remain rare in lakes. Our results indicate that glider-based missions yield reliable
484 turbulence measurements even in low turbulence and strongly stratified environments (Fig-
485 ures 5,6,7,S11) while collecting water quality parameters susceptible to turbulent transport
486 (Figures S2-S7).

487 Gliders enable scanning lateral variability of water constituents and small-scale turbu-
488 lence over long periods. Yet, the relevance of the data collected by glider missions depends
489 on the spatial scale of interest. Our flight immersion until $\sim 100 \text{ m}$ depth seriously altered
490 the possibility of investigating fine horizontal structures at the thermocline, given the ap-
491 proximate 0.5 km horizontal distance between two consecutive dives. It is tempting to infer
492 from the results that the interior's upper layer is relatively homogeneous and, therefore, a
493 1D representation would be sufficient (Figure 3). This interpretation could be a mistake
494 because the dominant basin-scale process, namely near-inertial waves (Figure 10), may in-
495 duce horizontal stirring at scales smaller than 0.5 km . From the ADCP measurements,
496 we estimated the horizontal kinetic energy and the characteristic inertial radius resulting
497 from current-induced circulation at the dominant inertial frequency band (Figure 10c). This
498 characteristic length is in the range of 0.2 to 0.4 km , suggesting that the horizontal variabil-
499 ity resulting from near-inertial waves is smaller than the scale characterized by our glider
500 missions.

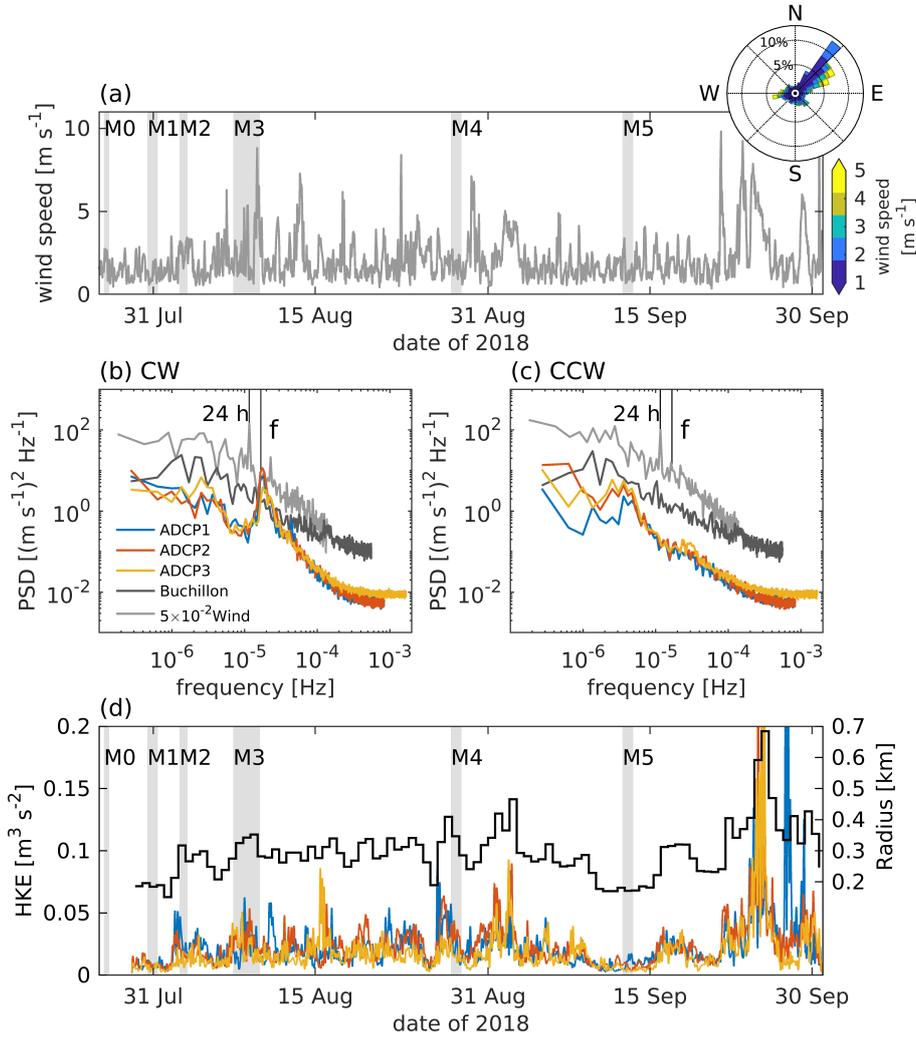


Figure 10. Wind data and current measurements analysis. (a) Wind speed time series and wind rose (direction) as measured at the Buchillon station. (b,c) Median rotary power spectral density (PSD) for clockwise (CW; anti-cyclonic in northern hemisphere) and counter-clockwise (CCW; cyclonic) current components, respectively. The analysis considers the currents time series for each sampled bin throughout the water column. For convenience, the wind rotary PSD is presented scaled by a factor of 5×10^{-2} to match the scale of currents PSDs. The inertial frequency is indicated by f and corresponds to a period of 16.6 h. (d) Left y-axis: Horizontal kinetic energy (HKE) of the inertial range of currents for ADCP1 to ADCP3. A bandpass filter around the inertial frequency of $[1, 5] \times 10^{-5}$ Hz was applied to the currents to perform the calculations. Right y-axis: Median radius of inertial currents (black line) obtained from the three HKE estimates, filtered with a 16 h window average. Gray areas in (a) and (c) denote the periods of each glider mission.

501 Prior knowledge of the characteristic length scales of the investigated process is critical
502 to evaluating whether or not gliders can provide meaningful information. Although our
503 mission design pushed the capabilities of safe glider navigation to the limit, standard CTD
504 transects can easily outcompete the spatial resolution gliders render by resigning temporal
505 coverage. As it would take longer to complete the transect for each profile added. Gliders will
506 perform at best when the enabled scanning resolves the length scales of the studied process.
507 Therefore, targeting processes that exhibit characteristic length scales of several kilometers,
508 such as gyres (Laval et al., 2005; Shimizu et al., 2007) and coastal upwelling events (Reiss
509 et al., 2020; Roberts et al., 2021), would ensure good performance. Nevertheless, equipping
510 gliders with shallow pumps to improve underwater sampling agility is a strategy that would
511 allow increasing spatial resolution in the upper layers of medium and large lakes.

512 A significant and distinct advantage of glider-based missions is the possibility to collect
513 data during traditionally challenging weather conditions (strong winds, severe sea states).
514 In lakes, under such conditions, gliders enable measurements that would be otherwise im-
515 possible to obtain through ship-based operations. This challenge is particularly relevant
516 for turbulent quantities, often requiring tethered, free-falling profilers that are likely to hit
517 the bottom when the line drop is not vertical due to wind- or current-driven boat drift.
518 Therefore, underwater gliders represent a qualitative breakthrough for data acquisition in
519 large lakes.

520 5.2 Turbulence estimates

521 Glider-based turbulence measurements have been mainly documented for energetic
522 ocean environments (Fer et al., 2014; Schultze et al., 2017). The weak-to-moderate en-
523 ergy of the strongly stratified Lake Geneva contrasts with the common use of gliders
524 for turbulence estimates in oceanic conditions. This work reports a comprehensive method
525 validation because gliders' along-path speeds ($U \approx 0.35 \text{ m s}^{-1}$; this research) are two times
526 faster than usual microstructure profiling speeds for lakes ($U \approx 0.15 \text{ m s}^{-1}$; Kocsis et al.,
527 1999). We followed the approach of Dillon and Caldwell (1980), binned temperature mi-
528 crostructure spectra in different ranges of Cox number, and calculated their ensemble average
529 (Figure 5). The analysis demonstrates that spectra meeting the Batchelor fitting conditions
530 capture the variance and roll-off characteristics of the theoretical shape. Therefore, the
531 procedure ensures reliable turbulence estimates that, as expected, were less energetic than
532 in the ocean.

533 Turbulence estimates in the interior presented a marked vertical structure with max-
534 imal values close to the surface ($\sim 10^{-7} \text{ W kg}^{-1}$) that weakened with depth ($\sim 10^{-11} \text{ W}$
535 kg^{-1}). This result is consistent with the interior vertical profile in other deep stratified
536 lakes (Fernández Castro, Sepúlveda Steiner, et al., 2021; Ravens et al., 2000). For a cross-
537 shore transect, the vertical decay of turbulent dissipation rates was more gradual and ranged
538 between $10^{-10} - 10^{-8} \text{ W kg}^{-1}$ in the deeper layers, which agrees with average summer pro-
539 files reported for Lake Geneva in a coastal location (Fernández Castro, Bouffard, et al.,
540 2021).

541 5.3 Mixing characterization

542 This work provides spatially-distributed turbulent mixing estimates from a glider in a
543 large lake. The interior thermocline region shows a combination of strong stratification and
544 moderate TKE dissipation (Figure 7a). The strong background temperature gradient leads
545 to reduced Cox numbers ($C_x < 1$), suggesting that there is no turbulent mixing, despite
546 $Re_b > 7$ (i.e., transition to turbulence) in the water column (Figure 8a,c between 10 and
547 40 m). Our analysis revealed inhibited mixing in the thermocline ($Ri_f \sim 0.01$) and mixing
548 efficiency below the canonical oceanic value in the deep interior ($Ri_f < Ri_f^{ocean} = 0.17$;
549 Osborn, 1980). The extremely low mixing efficiency in the thermocline is in line with several
550 studies using microstructure and other indirect methods (e.g., Wüest et al., 2000; Etemad-

551 Shahidi & Imberger, 2001) but differs from the strong thermocline dissipation observed by
 552 Bouffard and Boegman (2013) in the shallow and energetic Lake Erie.

553 In the coastal transition zone, mixing was active ($C_x > 1$, $Ri_f > 0.1$) below 20 m depth,
 554 even developing energetic turbulent regimes ($Re_b > 100$). This highlights the clear difference
 555 between interior and coastal slope regions in lakes and the role of boundary conditions in
 556 the generation of turbulent mixing (Gloor et al., 2000; Goudsmit et al., 1997).

557 There is a long-standing debate on whether assuming mixing efficiency as a constant
 558 ($Ri_f = 0.17$ in the ocean; Osborn, 1980) or parameterized as a function of turbulence
 559 characteristics. The constant viewpoint stems from the uncertainty level of observations,
 560 whereas several studies dealing with microstructure-based turbulent quantities propose var-
 561 ious parameterizations (e.g., Ivey et al., 2008; Bouffard & Boegman, 2013; Monismith et
 562 al., 2018). The glider-based turbulence dataset, collected in the lake interior, allows us to
 563 analyze the sensitivity of Ri_f to different turbulent parameters, such as C_x and Re_b (Figure
 564 11).

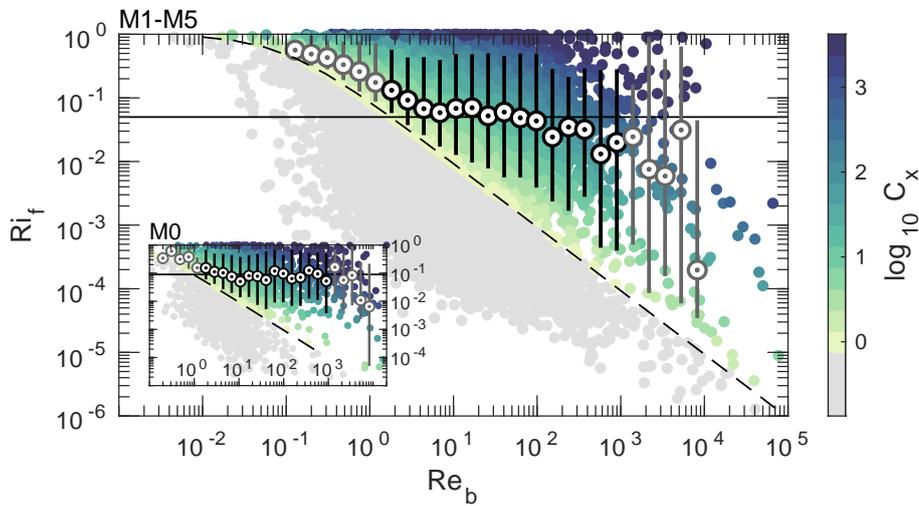


Figure 11. Mixing diagram. Richardson flux number (Ri_f) as a function of the buoyancy Reynolds number (Re_b) and color-coded for C_x numbers (C_x) for the lake interior data set (M1-M5). Dotted white circles represent the median of Ri_f in each bin for data points with $C_x > 1$. Error bars show 10th and 90th percentiles of the same subset. Black dotted-circles represent statistically well-conditioned intervals, with a reliable amount of data points, whereas those in gray are irrelevant or less reliable due to $Re \leq 1$ or few data points ($Re > 10^3$ intervals). The dashed black line is Ri_f expressed as a function of C_x and Re_b , $Ri_f(C_x, Re_b) = \frac{C_x(D_T/\nu)}{C_x(D_T/\nu) + Re_b}$ for $C_x = 1$. The horizontal black line corresponds to the median of the statistically well-conditioned interval $Ri_f = 0.05$. The inset plot in the left-inferior corner depicts the same analysis for the interior-to-coast transition data set (M0), with a median of $Ri_f = 0.09$.

565 For the interior, the comparison of Ri_f as a function of Re_b (Figure 11) shows a large
 566 scatter with values spanning more than five decades. Binning data points with $C_x > 1$ only
 567 (i.e., turbulent temperature fluctuations overcome the background gradient) and averaging
 568 within the domain $1 < Re_b < 1000$ yields $Ri_f \approx 0.05$. For a compilation of oceanic
 569 datasets, Monismith et al. (2018) found $Ri_f \approx 0.17$ when considering data from below the
 570 thermocline. The same analysis for the cross-shore transect data (M0; inset in Figure 11)
 571 indicates $Ri_f \approx 0.09$, only slightly more efficient than the interior despite the considerable

572 enhancement of turbulence close to the sloping boundary (Figure 9a). Altogether, Figure
 573 11 reveals that turbulent mixing in Lake Geneva was considerably less efficient during our
 574 sampling than in the ocean, raising concerns about the applicability of the Osborn diffusivity
 575 model in lakes. Therefore, mixing efficiency in deep, strongly stratified, and weakly energized
 576 lakes requires further research. Notwithstanding, Figure 11 clearly shows the dependency of
 577 Ri_f on C_x and Re_b , supporting the need for more elaborated parameterizations of mixing
 578 efficiency (e.g., Mashayek et al., 2021).

579 **5.4 Lateral variability of turbulence along sloping topography**

580 The transect towards the southern shore of Lake Geneva (Figure 9a) captured con-
 581 siderable horizontal variability of turbulent dissipation. An intuitive and plausible process
 582 generating such a feature is internal wave breaking (Lorke, 2007; Nakayama et al., 2020),
 583 but we do not have temporally resolved temperature profile data to assess it. Comparable
 584 measurements in Lake Geneva were performed with microstructure sensors mounted on a pi-
 585 loted submarine (Fer et al., 2002). Although their measurements correspond to winter, when
 586 stratification is weaker, our turbulent dissipation estimates near the slopes ($10^{-9} - 10^{-7}$ W
 587 kg^{-1} ; Figure 9a) agree with those of Fer et al. (2002), reported for windy conditions. Our
 588 measurements reveal a more intense mixing at the boundaries, supporting results from tracer
 589 release experiments (e.g., Goudsmit et al., 1997) and microstructure studies (e.g., Bouffard
 590 et al., 2012). For unknown reasons, the high dissipation rates observed in the coastal region
 591 during mission M0 extended 10 to 20 m above the expected bottom boundary layer (~ 10
 592 m thickness in L. Geneva; Bouffard & Lemmin, 2013a).

593 During our measurements, the interior of Lake Geneva resulted in a challenging environ-
 594 ment for the assessment of horizontal variability due to a lack of prominent hydrodynamic
 595 features. However, Figure 9a suggests that glider deployments could be valuable to study
 596 cross-shore turbulence patterns, particularly when approaching sloping boundaries. Safe
 597 glider navigation through steep bathymetry is the main complication to advance this knowl-
 598 edge. A more agile underwater glider (i.e., equipped with a shallow pump enabling faster
 599 vertical turns) and interactive navigation strategies interfacing glider-mounted acoustics
 600 could help overcome this technical barrier.

601 **5.5 Centrifugal instabilities**

602 Recent advancements in ocean research have identified centrifugal instabilities as a
 603 mechanism transferring kinetic rotational energy from geostrophic flows to the submesoscales
 604 and, subsequently, to small-scale turbulence (Gula et al., 2016). These instabilities alter
 605 circulation driving unbalanced motions, and promote horizontal transport. Specifically,
 606 centrifugal instabilities caused by interactions between cyclonic currents (counter-clockwise
 607 in the northern hemisphere) and the sloping bathymetry can trigger vigorous turbulent
 608 mixing (Naveira Garabato et al., 2019; Wenegrat & Thomas, 2020). We hypothesize that
 609 this mechanism may account for the enhanced turbulence adjacent to the sloping topography
 610 above the expected bottom boundary layer in our cross-shore transect (Figure 9a).

611 The occurrence of these instabilities is tied to the direction of the vertical component
 612 of Ertel’s potential vorticity, q_v , by:

$$q_v = (\zeta + f)N^2 < 0 \quad (9)$$

613 where $\zeta = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y}$ is the vertical relative vorticity with u and v the east- and north-ward
 614 velocity component, respectively and f the inertial frequency. In simple words, centrifugal
 615 instabilities develop in the presence of cyclonic background circulation (e.g., a Kelvin wave)
 616 when the resulting vertical relative vorticity is negative, and its magnitude exceeds the Earth
 617 rotational forcing.

618 We used velocity results from the open-access lake forecast model
 619 `meteolakes.ch` (Baracchini et al., 2020) to extract the vertical relative vorticity and eval-

620 uate our hypothesis. Figure S13 offers validation of the model results. The resemblance
621 of model velocities' rotary spectra (Figure S13i,j) at the different ADCP stations (Figure
622 2) indicates that the model can resolve the main basin-scale processes. We acknowledge
623 the coarse resolution of the available model (450 m horizontal grid) and recognize that a
624 dedicated finer resolution model would better resolve the velocity field. However, even from
625 the horizontal resolution used in `meteolakes.ch` (>10 grid points in one Rossby radius), it
626 is possible to evaluate the potential for the occurrence of centrifugal instabilities. Figures
627 9b-c show $\zeta + f$ at three times during the same day of M0 along the glider's transect. On
628 the sloping topography section, $\zeta + f < 0$, signaling the presence of unstable flow 20 m
629 above the bottom. This first approach confirms the potential for centrifugal instabilities.

630 Notably, the cyclonic current exceeding the inertial effect (e.g., Figures 9b-c) seems
631 to last for approximately one inertial period (16.6 h; $f = 1.05 \times 10^{-4} \text{ s}^{-1}$), which sets
632 the minimal time-scale required for the development of centrifugal instabilities. Hence, the
633 flow interaction with the sloping topography could unfold centrifugal instabilities and would
634 explain the elevated turbulent dissipation encountered around 19:00 h during M0 (Figure
635 9a). Further comparison of geometrical and hydrodynamic characteristics can inform on
636 the likelihood of instabilities occurrence by comparing the gradient Richardson number
637 (Ri_g) with the slope Burger number (Wenegrat et al., 2018). The former is canonical
638 ($Ri_g = N^2/S^2$, where $S^2 = (\partial u/\partial z)^2 + (\partial v/\partial z)^2$ is the vertical shear squared) while the
639 slope Burger number is defined by:

$$S_{Bu} = \left(\frac{\beta N}{f} \right)^2 \quad (10)$$

640 where β (m m^{-1}) is the bathymetric slope. Numerical analyses by Wenegrat et al. (2018)
641 indicate that centrifugal instabilities will develop at sloping bottoms when $S_{Bu} > Ri_g$ for
642 $S_{Bu}, Ri_g \geq 1$. The region scanned by the glider during M0 exhibits $\beta \approx 0.030$; thus,
643 $S_{Bu} \geq 1$ for $N^2 \geq 1.25 \times 10^{-5} \text{ s}^{-2}$, which is largely fulfilled for our measurements. Yet,
644 `meteolakes.ch` results indicate $S^2 \approx 10^{-5} \text{ s}^{-2}$ at the slope, which renders $S_{Bu} \sim Ri_g$.
645 Therefore, according to Wenegrat et al. (2018), the conditions during M0 could trigger
646 centrifugal instabilities, although the analysis is not categorical.

647 Centrifugal instabilities have been identified as crucial mechanisms for energy cascading
648 and mixing at slopes in the Gulf Stream (Gula et al., 2016) and deep boundary currents
649 (Naveira Garabato et al., 2019). However, in lakes, this process remains overlooked. The
650 coastal region of lakes develops recurrent cyclonic motions such as Kelvin waves, coastal jets,
651 and gyres. Therefore, as defined by Wenegrat et al. (2018), this process is likely to occur
652 on gentle slopes during stratified conditions. As closing energy budgets in lakes remains
653 elusive, further investigations of centrifugal instabilities may reveal unaccounted transport
654 and mixing processes key to expanding these budgets to the spatial extent. Combining a
655 cross-shore array of high vertical resolution moorings resolving temperature (e.g., van Haren,
656 2018; van Haren et al., 2021) and velocity fluctuations with repeated glider transects could
657 be an interesting strategy for future exploration.

658 **6 Conclusions**

659 Our glider-based observations and analyses of spatially-distributed water physical quan-
660 tities in Lake Geneva offer the following conclusions:

661 1. We present the first comprehensive study of underwater glider-based turbulence mea-
662 surements in lakes. Moreover, we validate the use of such moving platforms for
663 turbulent dissipation estimates using temperature microstructure despite the strong
664 stratification and weak-to-moderate energetics.

665 2. Our results indicate that gliders are better suited for characterizing spatial variabil-
666 ity when focusing on basin-scale processes with characteristic scales larger than the
667 resolution enabled by two consecutive profiles (or yo's). However, despite the specific
668 conditions during the sampling in Lake Geneva, we provide a compelling example of
669 how they enable connecting large to small (turbulence) scales and vertical to horizon-
670 tal dimensions.

671 3. Despite the comparatively elevated turbulent dissipation, consistent with the level
672 of wind forcing, our study strongly suggests that the thermocline region exhibited
673 inhibited mixing due to the strong stratification.

674 4. We observed an increase in water column dissipation near the lake coastal slope and
675 suggest that centrifugal instabilities, a previously unaccounted process in lakes, could
676 explain the enhanced near-boundary turbulence observations. Cyclonic circulation
677 perpendicular to the gentle sampled slope forced this process. As these flow condi-
678 tions are ubiquitous in large lakes (e.g., basin-scale internal Kelvin waves and gyres),
679 centrifugal instabilities are a potentially critical mechanism to study in other similar
680 lakes.

681 Much effort is still needed to unravel the spatial extent of energy budgets in lakes. This
682 research provides a first step towards that direction. Future research could combine the
683 approach presented here with seasonal monitoring of turbulence microstructure and small-
684 scale velocity field in bottom boundary layers (Fernández Castro, Bouffard, et al., 2021) to
685 reveal temporal and lake-wide resolved energy pathways.

686 **Data Availability Statement**

687 Field measurements (glider and ADCPs) supporting the findings of this research are
688 available online ([zenodo-link-to-be-created](#)). Meteorological data is available at [https://](https://www.datalakes-eawag.ch)
689 www.datalakes-eawag.ch Data Portal (Buchillon Field Station). Lake Geneva 3D model
690 results are available at www.meteolakes.ch (Data Order/API).

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