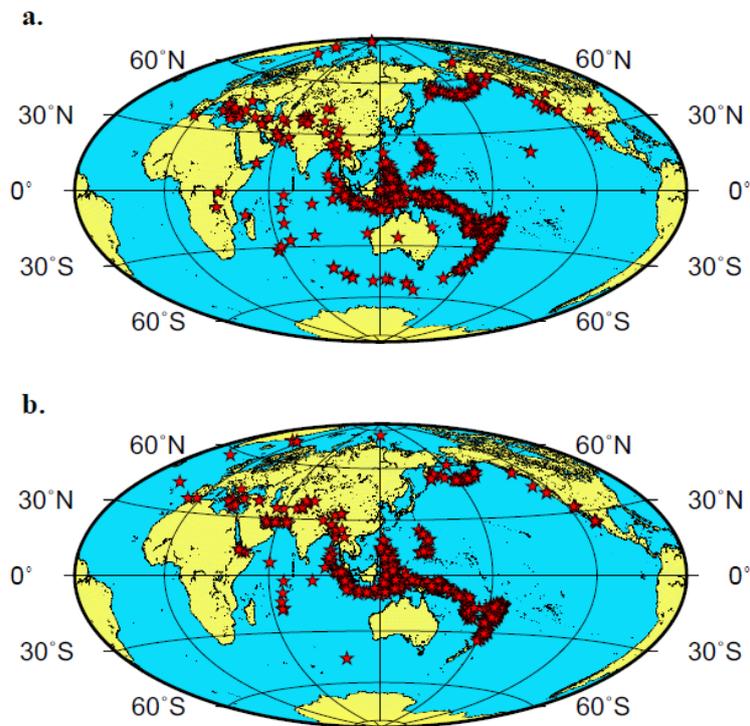
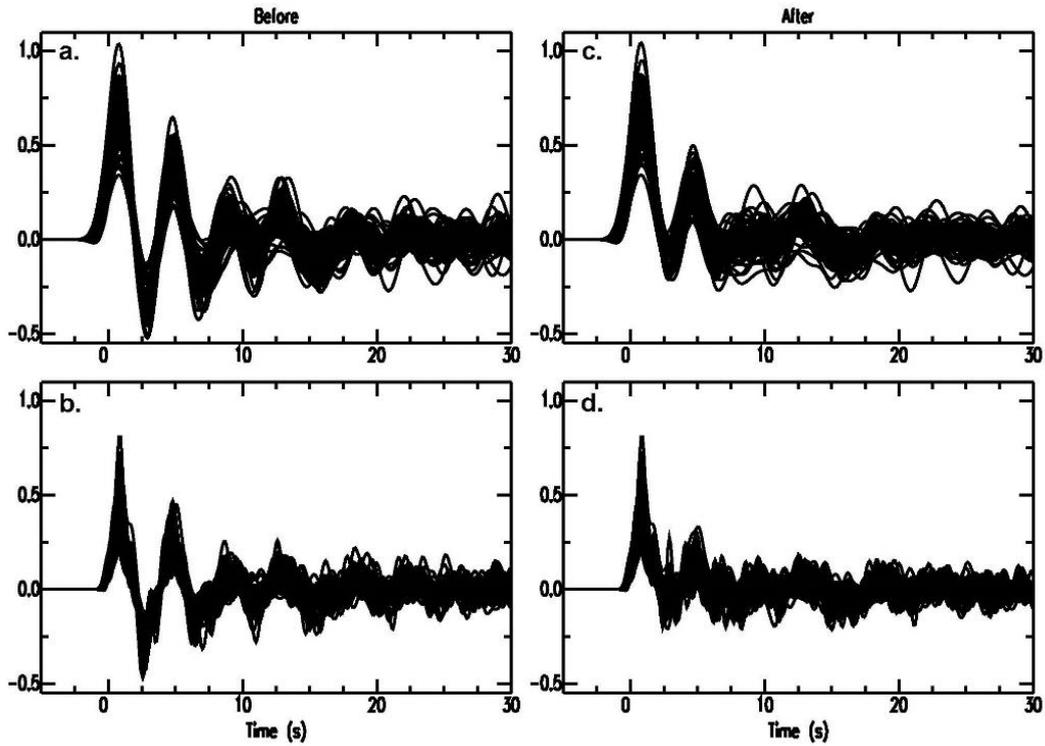


1 **Supporting Information for “Shear wave velocity structure beneath Northeast**
2 **China from joint inversion of receiver functions and Rayleigh wave group**
3 **velocities: Implications for intraplate volcanism”**

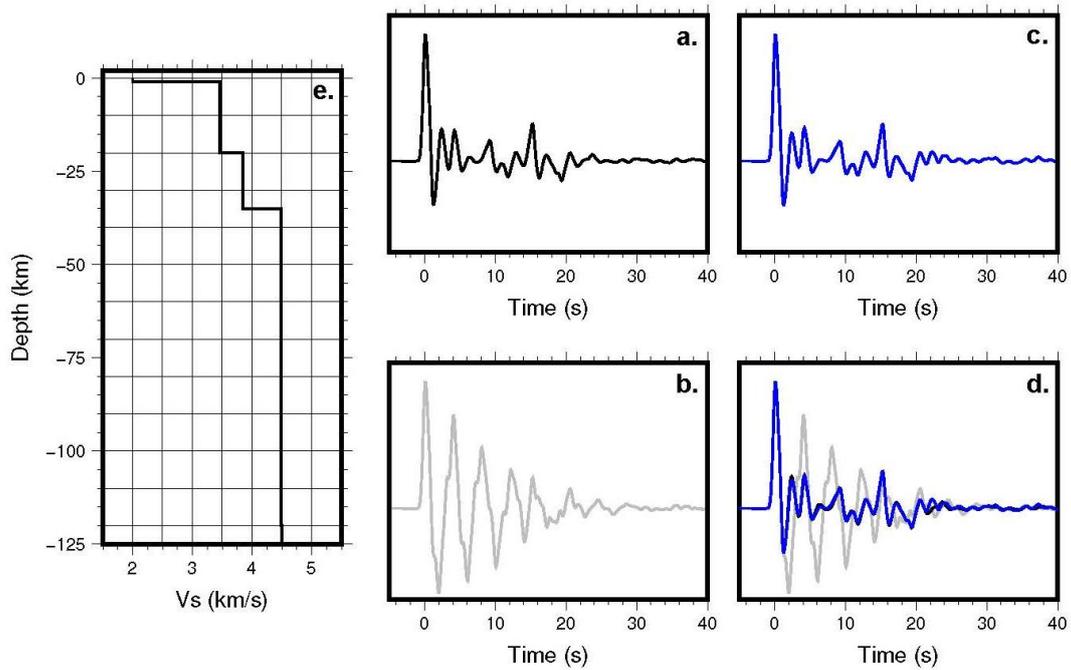


4
5 Figure S1. (a) Global distribution of earthquakes (2016–2019, red stars) for our receiver
6 function analysis at the permanent CEA stations. (b) Global distribution of earthquakes
7 (between 2009.09 and 2011.08, red stars) for obtaining receiver functions at the
8 temporary NECESSArray sites.



9

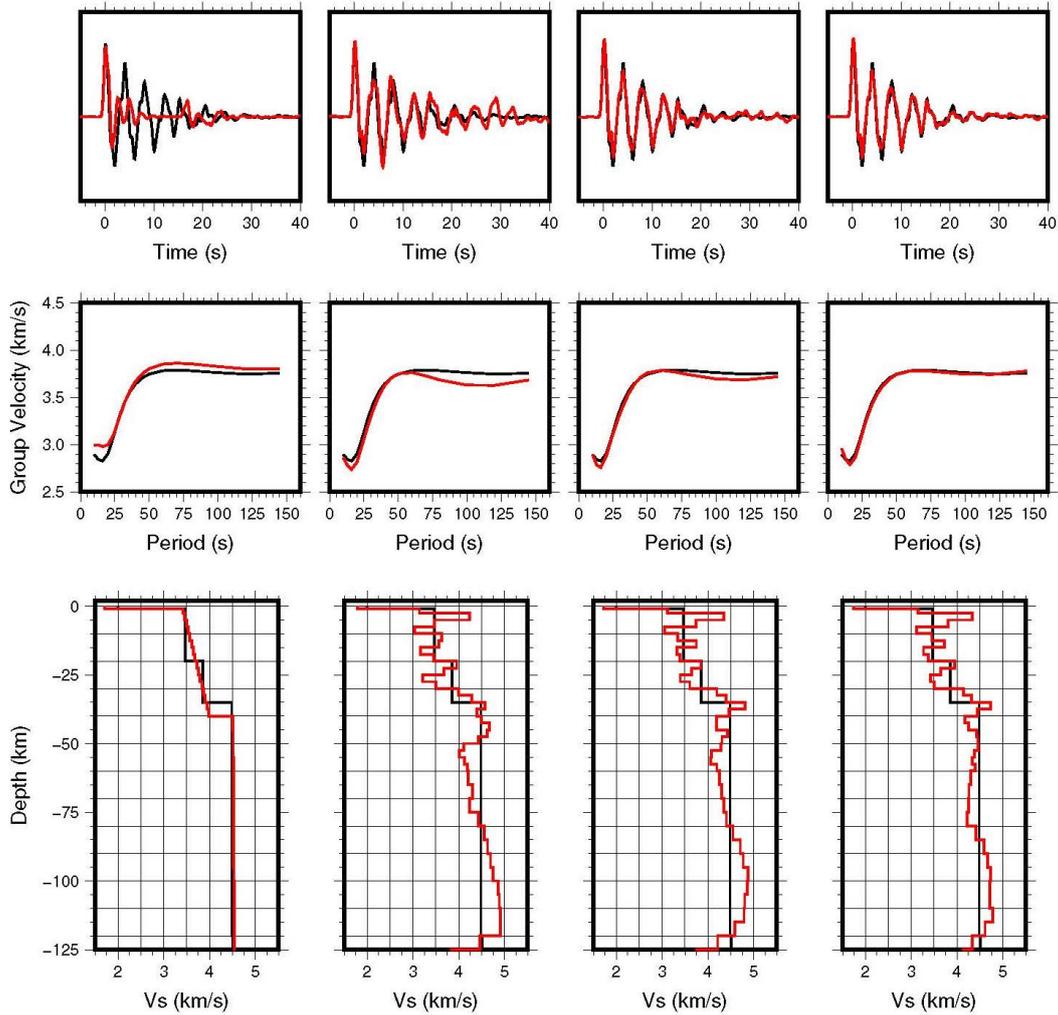
10 Figure S2. Radial receiver functions at low ($f_c \leq 0.50$ Hz, Gaussian width $\alpha = 1.0$) and
 11 high ($f_c \leq 1.25$ Hz, Gaussian width $\alpha = 2.5$) frequency bands recorded by station NEA7
 12 (located in the SLB and marked in Figure 2) are plotted in panel a and b, respectively.
 13 Panel c and d exhibit the resulting receiver functions at the two frequency ranges after
 14 applying the resonance removal filter.



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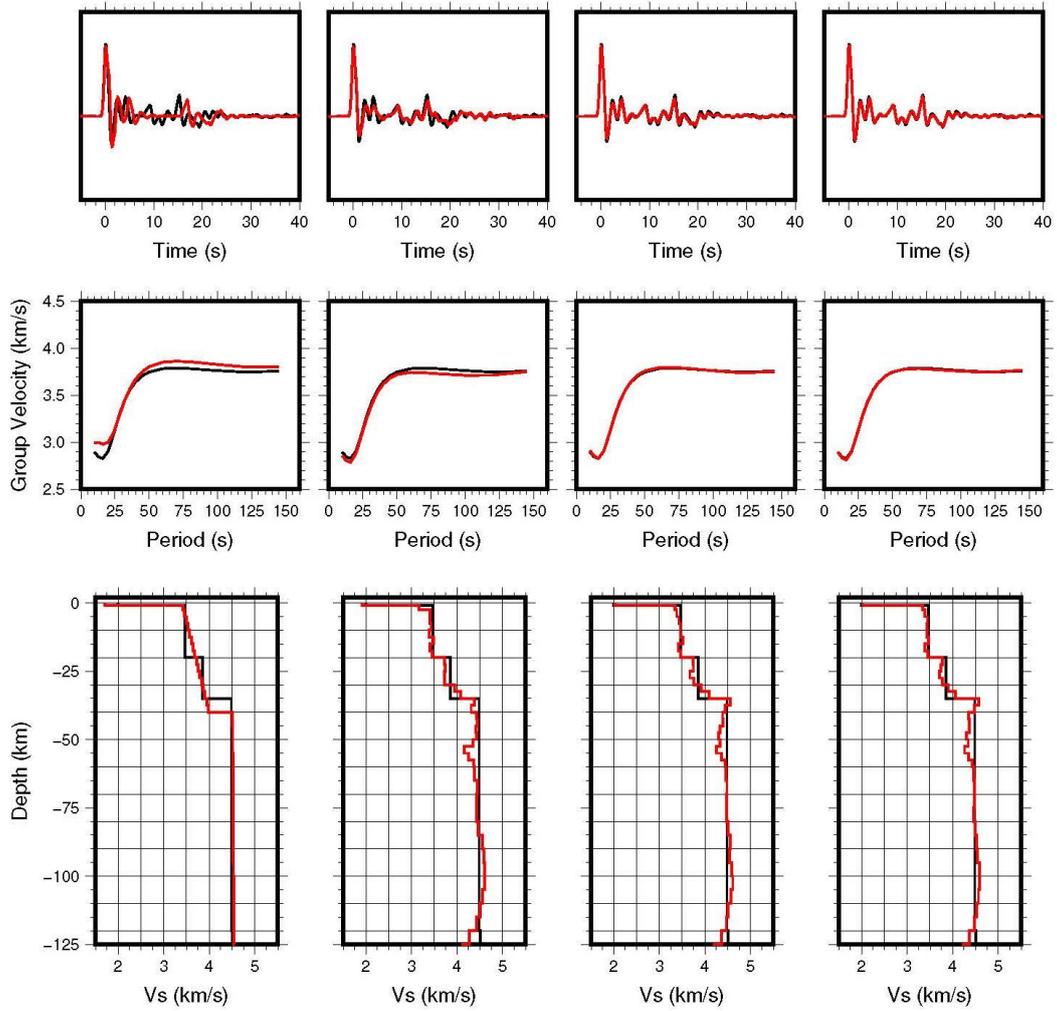
16 Figure S3. (a) Synthetic receiver function (ray-parameter 0.05 s/km, at Gaussian width
 17 of $\alpha = 2.5$) corresponding to the true model in panel (e). Note that a 1.0 km thick
 18 sedimentary layer is presumed and the primary P-to-S phases triggered by the
 19 sedimentary structure are likely between 1 and 3 s. However, it does not account for
 20 the complex situation that energy reverberating within the sedimentary layer (i.e.,
 21 multiples of converted shear waves). (b) Synthetic receiver function corresponding to
 22 the same true model, but including strong near-surface reverberations of converted
 23 shear phases. It is defined by the equation (2) in Yu et al. (2015). (c) Resulting receiver
 24 function after applying the resonance removal filter on the time series in panel (b). (d)
 25 Comparison between the synthetic receiver function without near-surface
 26 reverberations (black), the synthetic receiver function with strong near-surface
 27 multiples (gray), and the resulting receiver function after applying the resonance
 28 removal filter (blue). The blue trace is quite consistent with the black one (in both
 29 amplitude and lag time), which illustrates that the resonance removal filter effectively
 30 removes the near-surface multiples of converted shear phases and successfully recovers

31 the right signals from deep interfaces.



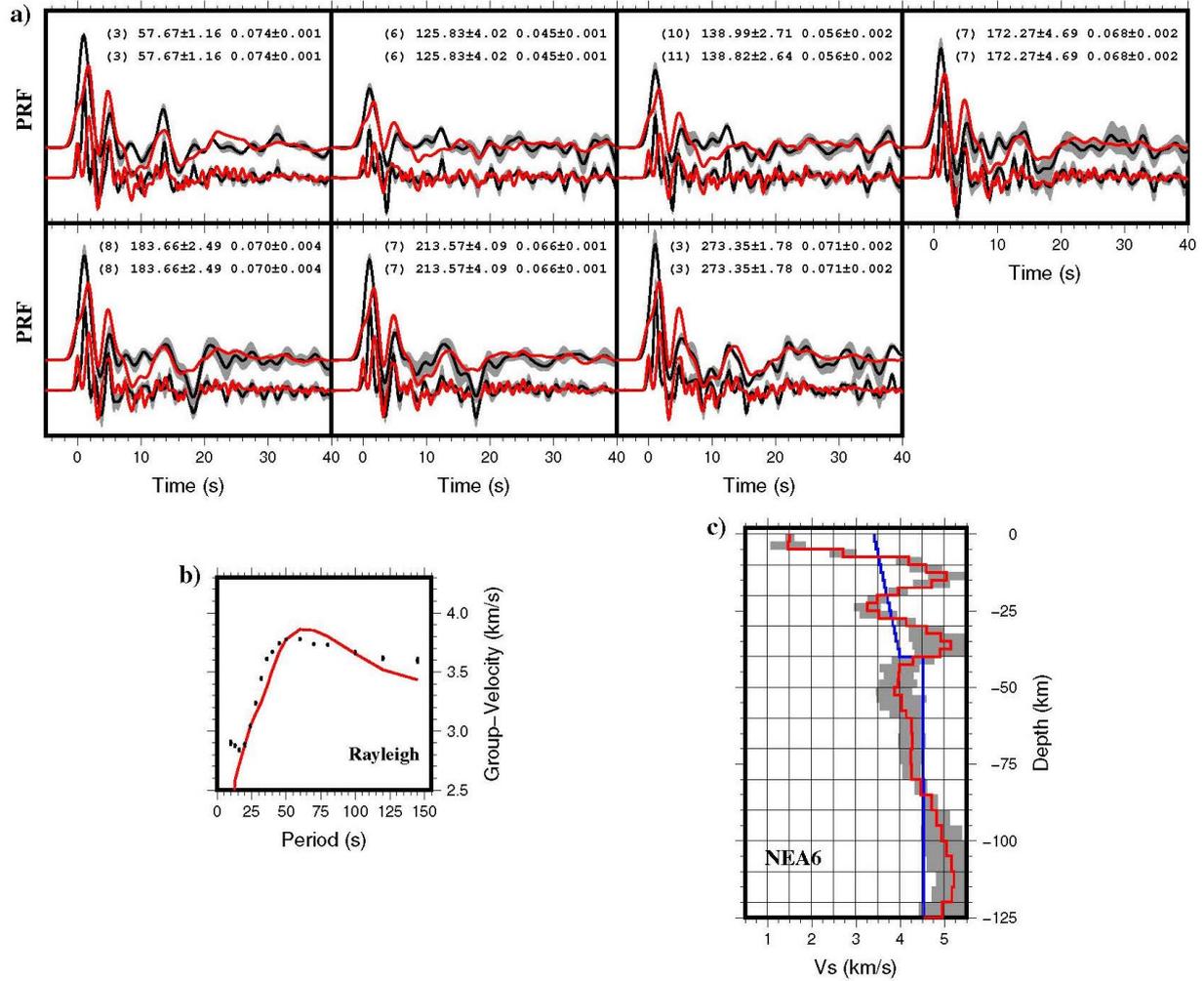
32

33 Figure S4. A synthetic test for joint inversion. Theoretical receiver function with strong
34 near-surface reverberations (the one in Figure S3b) and Rayleigh wave group velocity
35 dispersion curve that are corresponding to the true model (black) are represented by
36 black lines. Evolution of the iterated solutions and the corresponding predicted data are
37 shown by red lines. Note that the joint inversion converges to a solution, which however
38 contains many artifacts and unsuccessfully recovers the true model.



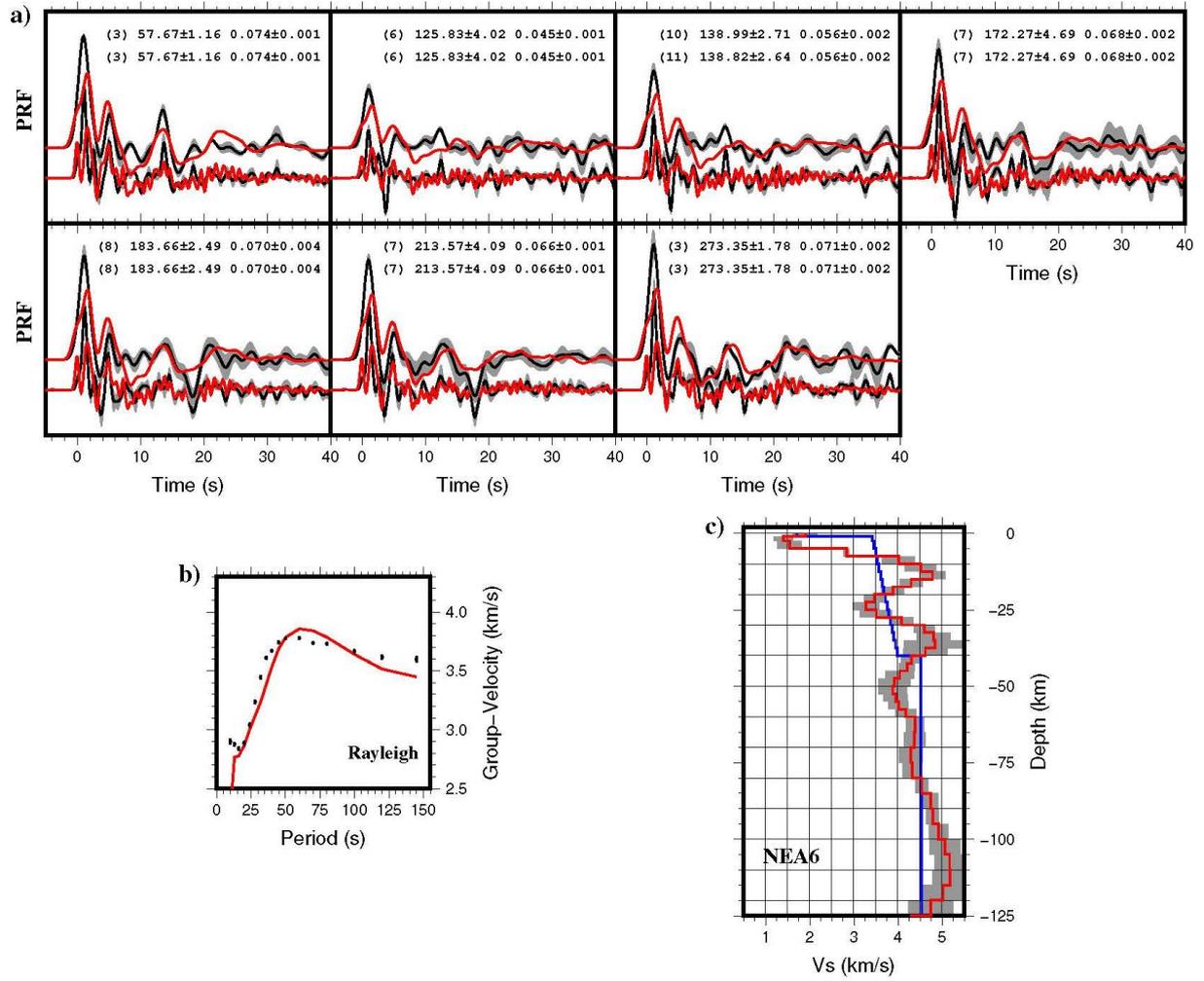
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40 Figure S5. The resulting receiver function after the application of the resonance removal
 41 filter (the one in Figure S3c) is inverted jointly with synthetic Rayleigh wave dispersion
 42 data (black). Evolution of the iterated solutions and the predicted data are displayed by
 43 red lines. The inversion recovers the true model in three iterations.

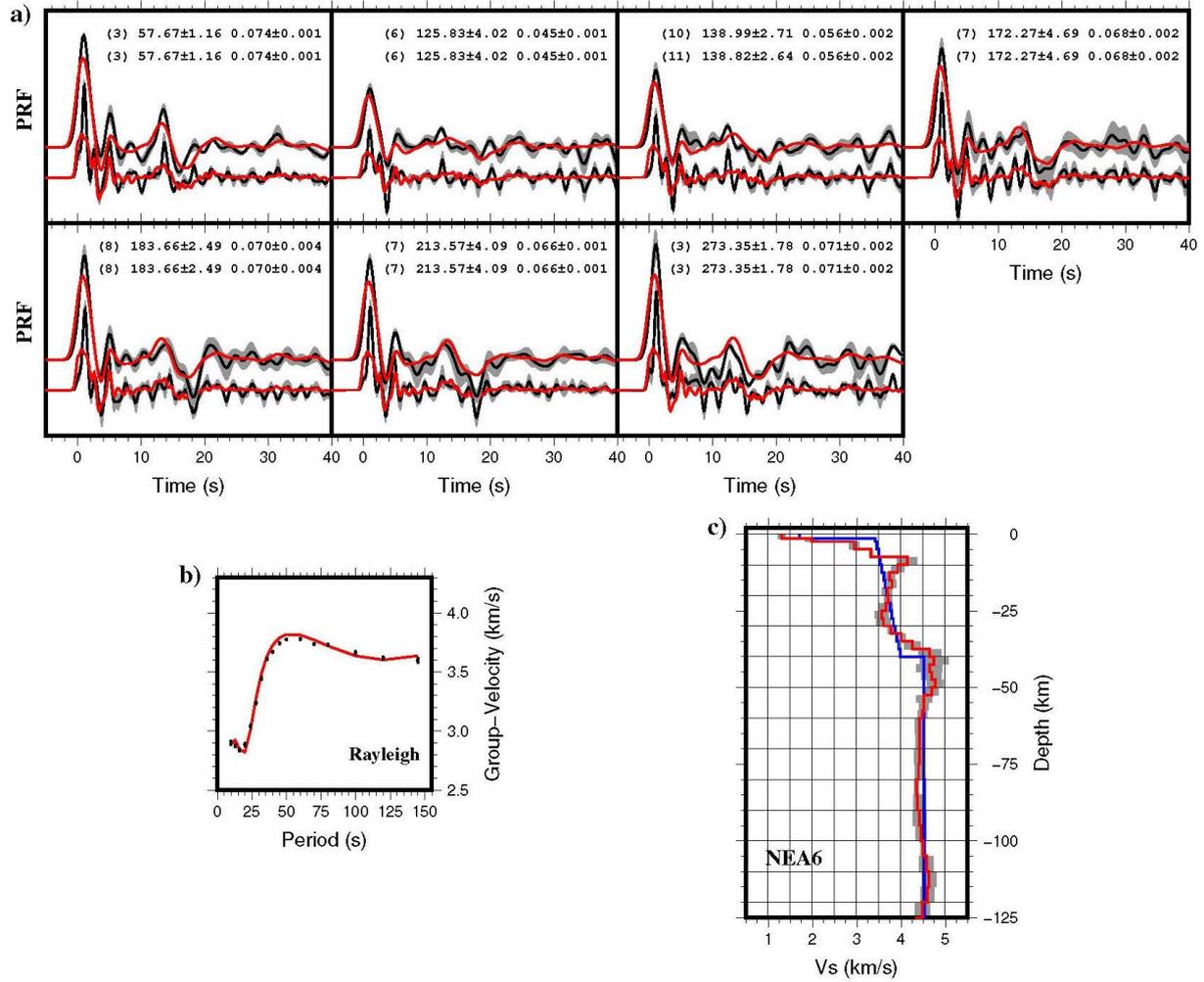


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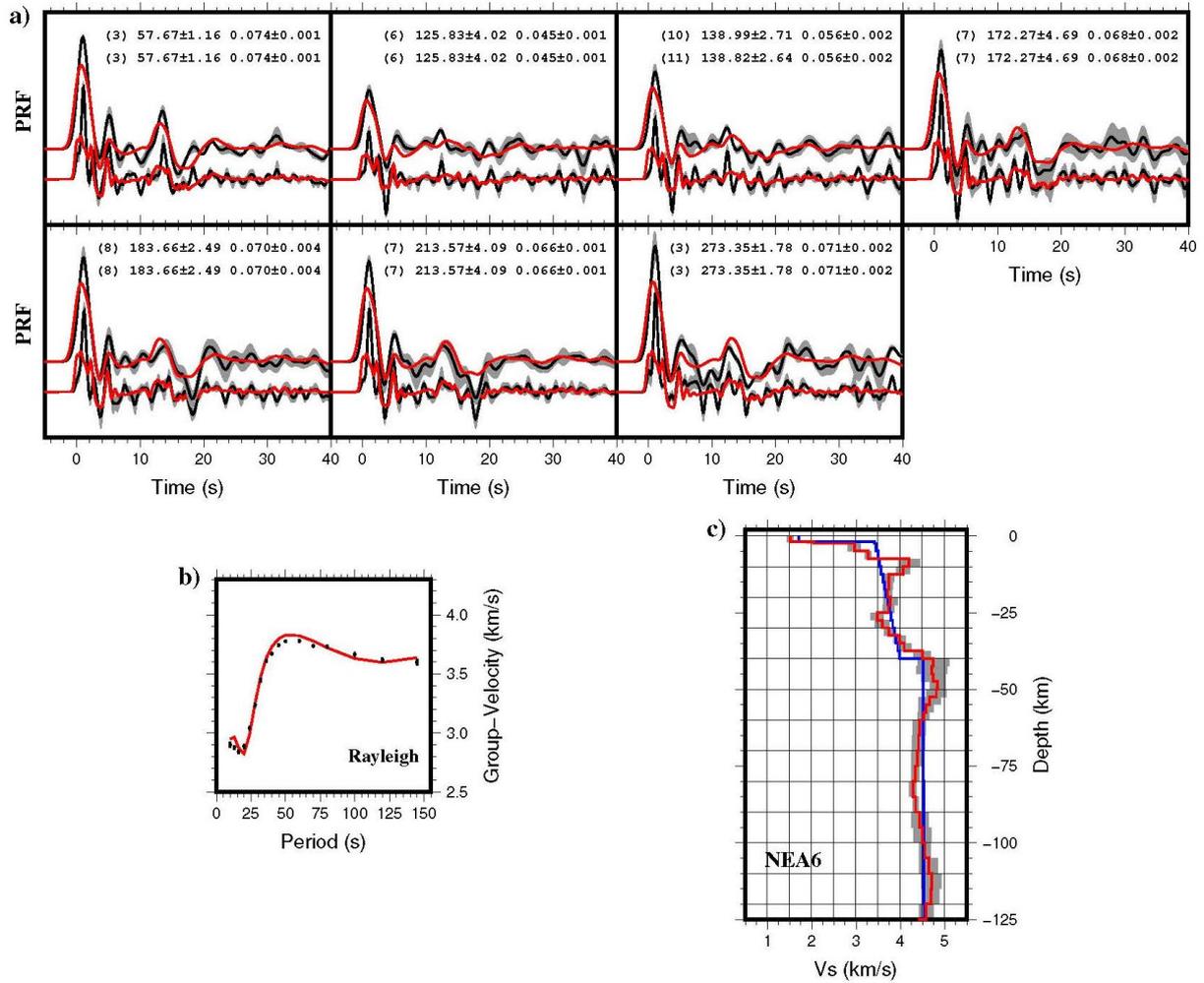
45 Figure S6. Unsuccessful joint inversion at station NEA6. The initial model (blue in
 46 panel c) that does not include a sedimentary layer is employed. Note that the solution
 47 (red in panel c) driven away from the convergence and the poor data fitting in both
 48 receiver functions (panels a) and Rayleigh wave dispersion velocities (panel b).



50 Figure S7. Joint inversion at NEA6, but applying a starting model with a 1.0 km thick
 51 sedimentary layer (blue in panel c). The inversion is still unsuccessful.

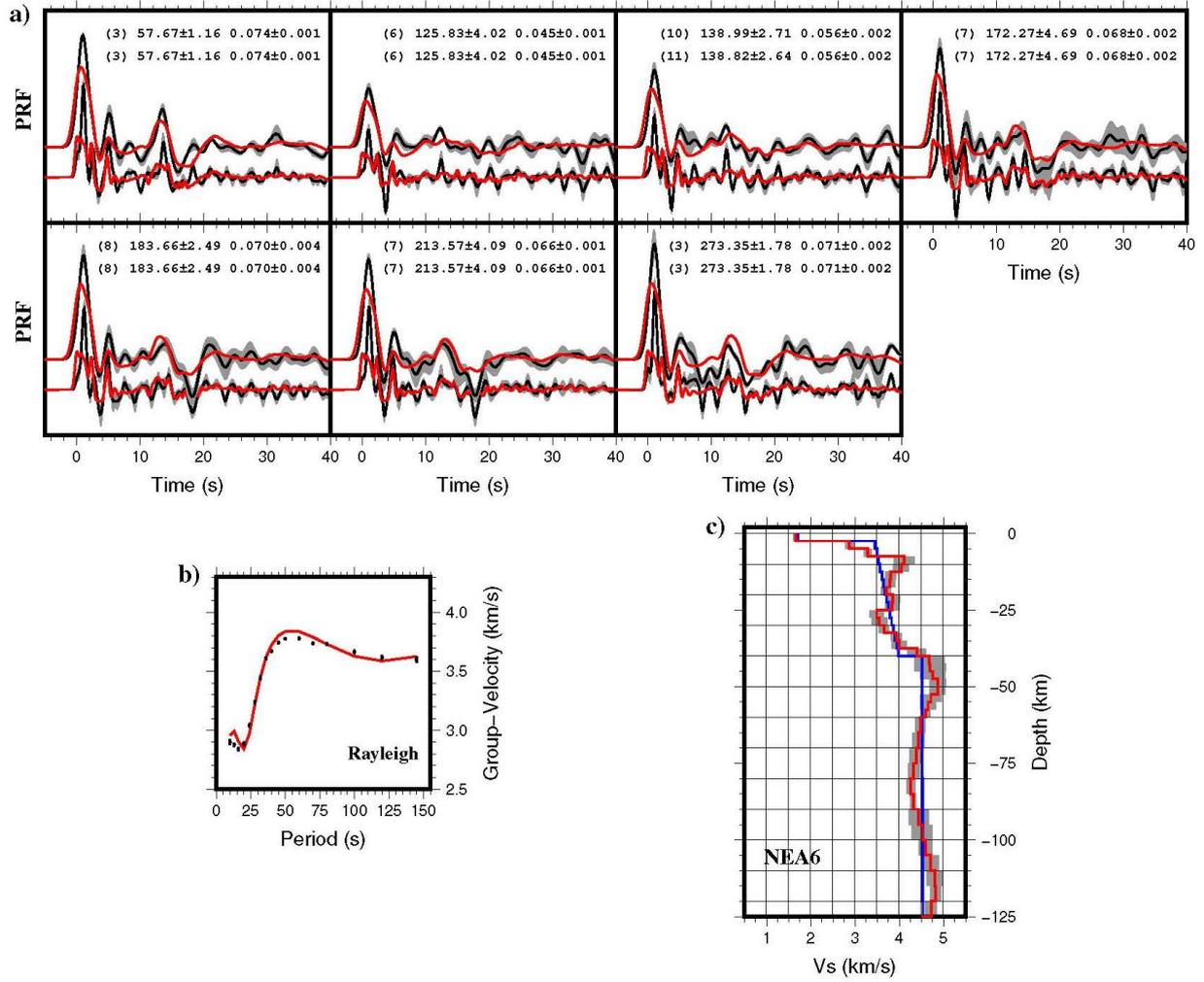


53 Figure S8. Joint inversion at NEA6, but employing an initial model with a 1.5 km thick
 54 sedimentary layer (blue in panel c). This case is successful. The inverted S velocity
 55 model is displayed in panel c. Note that the excellent match between predicted and
 56 observed data in both receiver functions (panels a) and dispersion curve (panel b).



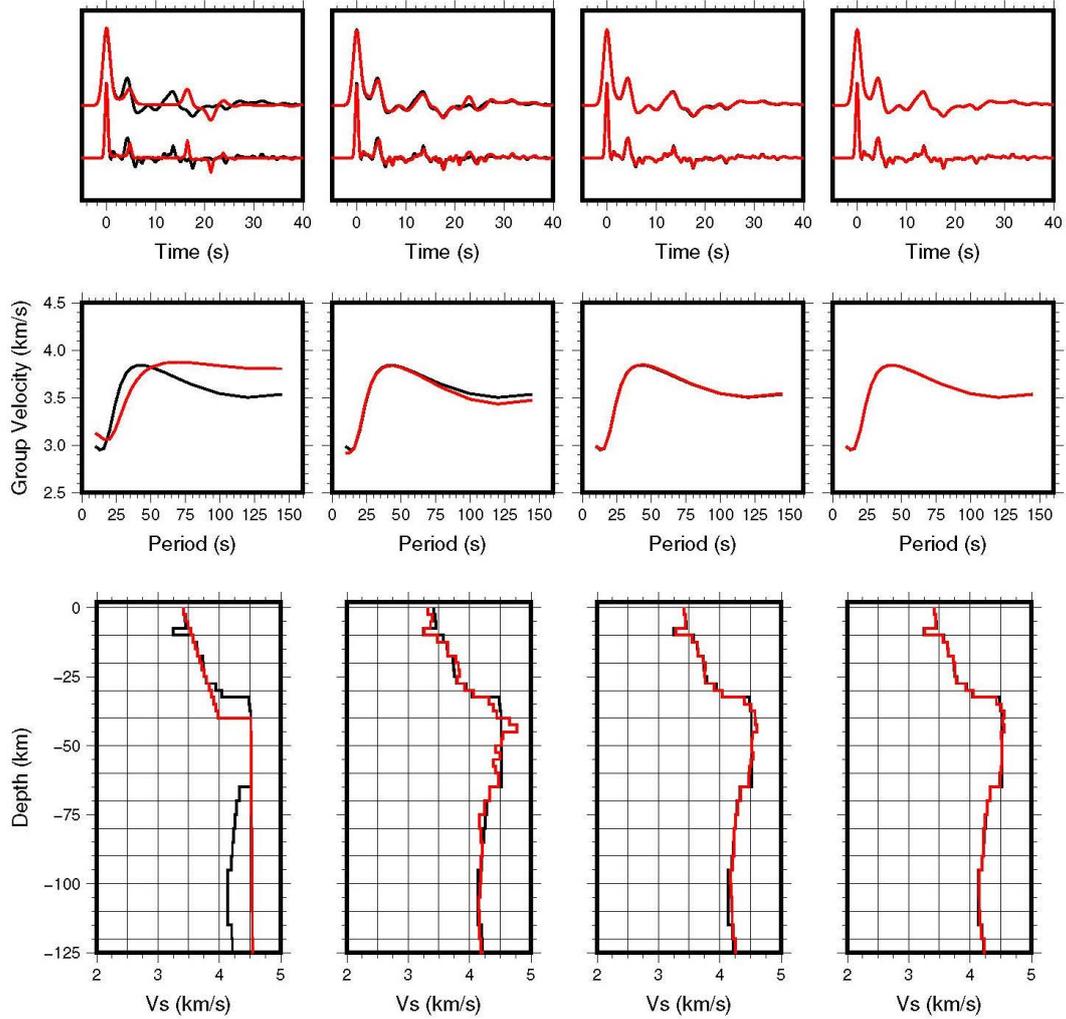
c.

58 Figure S9. Joint inversion at NEA6, with a 2.0 km thick sedimentary layer in the initial
 59 model (blue in panel c).



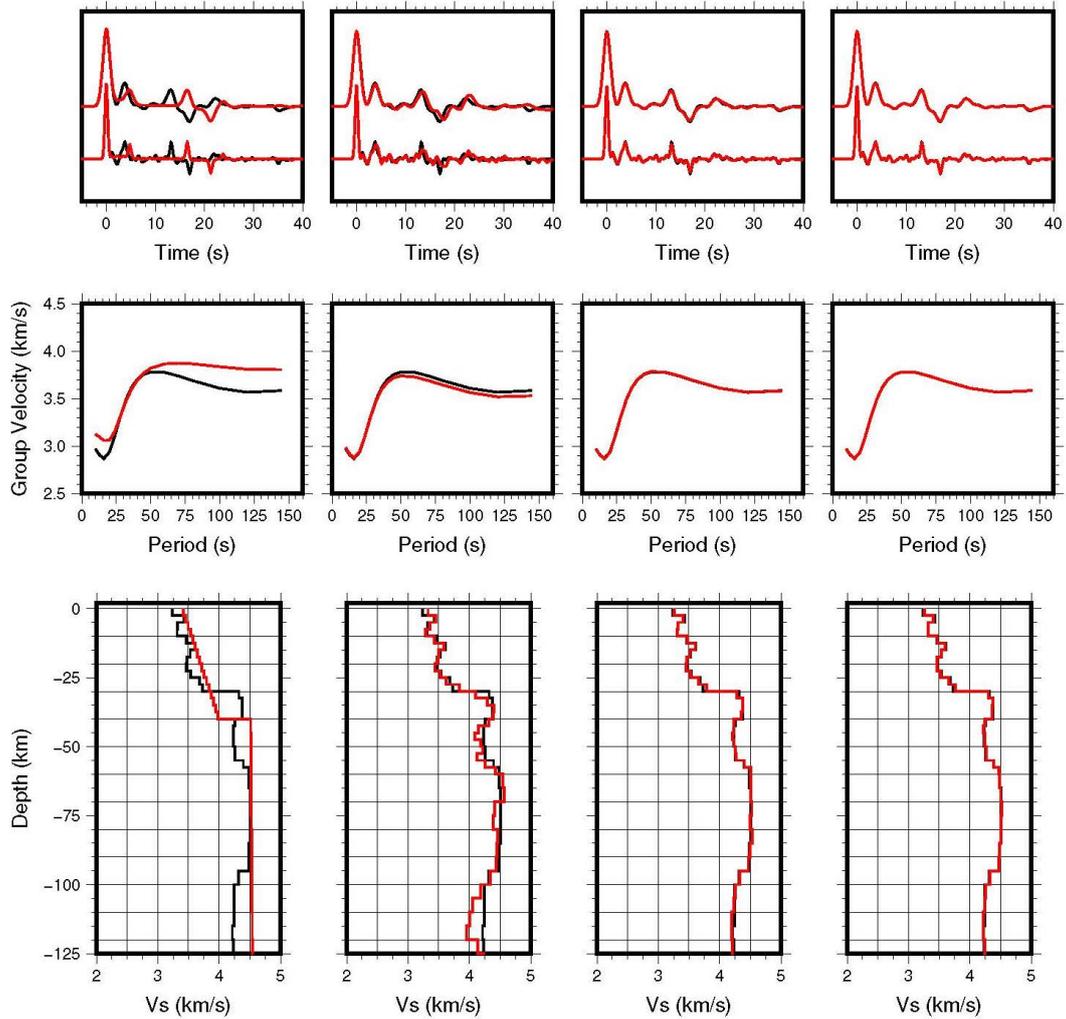
61

61 Figure S10. Joint inversion at NEA6, with a 2.5 km thick sedimentary layer in the
 62 starting model (blue in panel c).



63

64 Figure S11. A synthetic joint inversion test. The true model (black) contains a 2.5 km
 65 thick low V_s anomaly in the crust and an upper-mantle low shear velocity zone below
 66 65 km depth. The synthetic receiver functions (ray-parameter 0.05 s/km, at Gaussian
 67 widths of $\alpha = 2.5$ and 1.0) and Rayleigh wave group velocity dispersion curve (at
 68 periods of 10–145 s) corresponding to the true model are represented by black lines.
 69 Evolution of the iterated solutions and the corresponding predicted data are shown by
 70 red lines. Note that the resulting model converged to the true solution and the presumed
 71 crustal and upper-mantle V_s anomalies are perfectly recovered in three iterations.



72

73 Figure S12. Same as Figure S11, but for a different true model. This true model (black)
 74 includes a slow S velocity feature at 40-60 km depths (i.e., uppermost-mantle levels)
 75 and an upper-mantle low velocity zone below 95 km. Note that the significant shear
 76 velocity anomalies at the crustal and upper-mantle depths are successfully recovered
 77 by joint inversion.