

High-resolution post-process corrected satellite AOD

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Key Points:

- Satellites produce global aerosol data, however, these data often suffer from low accuracy and spatial resolution due to data aggregation.
- Machine-learning-based post-process correction leads to a significant improvement in the AOD accuracy over the conventional retrievals.
- Post-process correction approach is also efficient for spatial downscaling of satellite aerosol data leading to high resolution AOD.

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Abstract

Poor air quality poses a great threat to human health. Accurate high-resolution satellite remote sensing of atmospheric aerosols would highly benefit satellite-based air quality estimates. We have developed and validated a post-process correction and downscaling approach for satellite remote sensing of aerosols. We use NASA's Moderate Resolution Imaging Spectroradiometer (MODIS) aerosol optical depth (AOD) over Washington D.C. - Baltimore area during the Distributed Regional Aerosol Gridded Observation Networks (DRAGON) campaign in 2011 to evaluate our approach. We derive and evaluate the AOD fields with high 250 meter resolution. The results show that the post-process correction approach is suitable for deriving downscaled, high-resolution AOD estimates and significantly improves the accuracy of the AOD retrievals.

Plain Language Summary

Satellites collect information about our atmosphere. We often use satellite data to monitor, for example, the atmospheric aerosols, which are small solid and liquid particles in the air. However, the massive amount of satellite data and partially unknown atmospheric processes and land surface properties force us to use simplified computations in aerosol monitoring. Unfortunately, the simplified computations lead to sub-optimal accuracy and low resolution in aerosol data. In this work, we have developed a new machine-learning-based algorithm that is used together with conventional satellite data processing to improve the data. Our algorithm takes advantage of accurate ground-based measurements. As a result, it significantly improves the accuracy and resolution of the aerosol data. We improved the resolution of satellite-based aerosol data from 3 km to 250 meters. New high-resolution data may allow some new applications for the satellite data, such as street-level air quality monitoring.

1 Introduction

Poor air quality poses a great threat to human health. New World Health Organization (WHO) Global Air Quality Guidelines published in September 2021 provide clear evidence of air pollution's damage to human health at lower concentrations than previously conceived (World Health Organization, 2021). WHO estimates that people's exposure to air pollution causes 7 million premature deaths every year. A key indicator in monitoring air quality and epidemiological studies is the PM_{2.5} parameter, the dry

44 mass concentration of fine particulate matter with an aerodynamic diameter less than
45 2.5 micrometers ($\mu\text{g}/\text{m}^3$ of air). Fine particulate matter originates from vehicle emis-
46 sions, coal-burning, industrial emissions, and other human and natural sources. Air qual-
47 ity monitoring networks often utilize in-situ measurements that measure air quality at
48 pointwise locations. However, remote sensing and satellite observations are needed to
49 get better spatial coverage of air quality estimates over large regions.

50 The most widely used high-resolution satellite-based air quality datasets are based
51 on downscaled aerosol optical depth (AOD) estimates combined with auxiliary data (Shaddick
52 et al., 2018; van Donkelaar et al., 2019; Hammer et al., 2020; van Donkelaar et al., 2021).
53 Auxiliary data brings, for example, aerosol vertical distribution and composition infor-
54 mation to the computations. Then, statistical methods such as land use regression or
55 graphically weighted regression are used to combine the available information and ob-
56 tain an estimate for the surface PM_{2.5}. An improvement in AOD estimates' accuracy
57 and resolution would directly translate into an improvement in PM_{2.5} estimates. There-
58 fore, high accuracy, high-resolution satellite aerosol retrieval would greatly benefit satellite-
59 based estimation of surface PM_{2.5}.

60 Moderate spatial resolution imaging spectroradiometers, such as Moderate Reso-
61 lution Imaging Spectroradiometer (MODIS), Ocean and Land Colour Instrument (OLCI),
62 and Sea and Land Surface Temperature Radiometer (SLSTR), with a native resolution
63 of some hundreds of meters at best, would be an excellent and openly available source
64 of satellite data to be used in air quality retrievals. Compared to optical instruments with
65 high-resolution of tens of meters or even better, these moderate resolution instruments
66 have advantageous characteristics for air quality retrievals, including wide swath, frequent
67 return times, good signal-to-noise ratio, and broad spectral coverage. In the operational
68 aerosol products of these instruments, however, the aerosol properties are based on ag-
69 gregated data due to high computational costs and biases related to the aerosol retrieval
70 algorithms. As a result, the most widely used aerosol data products have a spatial res-
71 olution of 3-10 km (Levy et al., 2013).

72 Recent advances in new methods to combine conventional retrieval algorithms and
73 machine learning have significantly improved satellite AOD estimate accuracy (Lipponen
74 et al., 2021, 2022). For example, the post-process correction approach for satellite AOD
75 retrieval uses a machine learning-based model to predict the retrieval error in the satel-

76 lite AOD and uses that prediction to correct the retrieval. Previous studies have shown
 77 that the combination of physics-based retrievals and machine learning leads to better ac-
 78 curacy than a machine learning-based approach alone.

79 This study develops and validates the post-process correction and downscaling ap-
 80 proach for MODIS AOD over Washington D.C. - Baltimore area during the Distributed
 81 Regional Aerosol Gridded Observation Networks (DRAGON) campaign in 2011 (e.g. Garay
 82 et al. (2017); Virtanen et al. (2018)). The DRAGON campaign provides very dense cov-
 83 erage of accurate ground-based AERONET AOD measurements for validation of high-
 84 resolution AOD products. Therefore, the DRAGON campaign is a unique setting to val-
 85 idate the post-process correction of high-resolution AOD retrievals. Furthermore, the re-
 86 cently published post-process correction approaches have only been applied to the cor-
 87 rection of the satellite retrievals and not for the additional downscaling of the data to
 88 high spatial resolution. In this study, we take advantage of the high-resolution MODIS
 89 level-1 observations and, in addition to correction, downscale the AOD to 250 meter spa-
 90 tial resolution.

91 **2 Materials and Methods**

92 In this study, we develop and validate the post-process correction and downscal-
 93 ing approach to satellite aerosol retrievals. We apply the correction to MODIS 3 km AOD
 94 and use the DRAGON 2011 campaign aerosol data to validate the satellite retrievals.
 95 We downscale the AOD spatial resolution by mapping the aggregated data to a high-
 96 resolution grid corresponding to the best native resolution of the MODIS instrument,
 97 250 meters, and evaluate the accuracy of the corrected high-resolution AOD data.

98 **2.1 Post-process correction satellite retrievals**

99 Let

$$y = f(x) \tag{1}$$

100 be an accurate satellite retrieval algorithm. Here y denotes the retrieval algorithm out-
 101 puts, such as AOD, f is an accurate retrieval algorithm, and x are the inputs for the re-
 102 trieval algorithm such as measurement geometry information and satellite measured TOA
 103 reflectances. In reality, however, due to, for example, complex and partially unknown
 104 atmospheric parameters and surface reflectance, accurate retrieval algorithms do not ex-

105 ist. In practice, the retrievals are computed with an approximative retrieval algorithm
 106 \tilde{f} . The accurate retrieval algorithm (1) can be written as

$$y = f(x) + \tilde{f}(x) - \tilde{f}(x) \quad (2)$$

$$= \tilde{f}(x) + [f(x) - \tilde{f}(x)] \quad (3)$$

$$= \tilde{f}(x) + e(x), \quad (4)$$

107 where e denotes the retrieval error.

108 In the conventional supervised machine learning-based approach, the aim is to train
 109 a model to directly predict the satellite retrieval outputs y given the inputs x . These trained
 110 models approximate the accurate retrieval algorithm f . As these models rely on the use
 111 of machine learning models only, we refer to these models as fully learned models.

112 In the post-process correction approach, the aim is to train a machine-learning-based
 113 model to predict the retrieval error e and employ (4) to compute the retrieval output.
 114 This post-process correction approach combines the physics-based retrieval \tilde{f} and ma-
 115 chine learning. We expect the retrieval error e to be a less complex function than the
 116 full retrieval algorithm f to be learned from finite number of learning data, and thus ex-
 117 pect the post-process correction to result in more accurate retrieval than the fully learned
 118 model.

119 In the development of the post-process correction approach, we noted an interest-
 120 ing similarity between the post-process correction model architecture and the widely used,
 121 recently developed neural network architecture of residual neural networks (ResNet). In
 122 ResNets, the network architecture is constructed so that skip connections are added to
 123 allow information skip over some neural network layers and act as inputs for the sub-
 124 sequent layers. AOD post-process correction can be thought of to have a similar skip con-
 125 nection for a subset of input data corresponding to the AOD to be corrected. The skip
 126 connection for AOD is created from the model inputs directly to the final output layer
 127 of the neural network. Having these similarities, however, the starting points of the ResNet
 128 and post-process correction are fundamentally different - post-process correction aims
 129 at correcting the output of a physics-based retrieval algorithm, and the ResNets have
 130 been developed to tackle the problem of vanishing gradients in the training of deep neu-
 131 ral networks. As the practical implementations are quite similar between these two mod-
 132 els, we also expect that the post-process correction model may be relatively tolerant against

133 the problem of vanishing gradients in the training of the neural networks. Therefore, we
134 expect this feature to even further improve the accuracy of the post-process correction
135 models. We also tested the ResNet-type of algorithm in this study and found it perform
136 similarly as the post-process correction model and therefore do not show the results here.

137 **2.2 Training and validation of the neural network models**

138 The dense network of AERONET stations available in the DRAGON campaign al-
139 lowed validation of the downscaled 250 m resolution aerosol product. In the validation,
140 we used a cross-validation approach in which some of the AERONET stations were used
141 for training the models, while others were used in the validation of the results. We train
142 and validate both fully learned and post-process correction models to compare the per-
143 formance between these two approaches. For training and validation, we randomly di-
144 vided the MODIS-AERONET collocated pixels into three separate groups by AERONET
145 station.

146 The division is carried out by AERONET station to avoid too similar data sam-
147 ples between the training and validation datasets. As is well known, too similar data sam-
148 ples could potentially lead to over-optimistic results. The evaluation of the accuracy of
149 the models was carried out using cross-validation so that one group was used as train-
150 ing data, one group was used as validation to monitor the convergence of the training,
151 and the resulting model was applied to the third independent group of test data. This
152 was repeated three times so that each AERONET station was present once in the val-
153 idation data. Training of every model was carried out 20 times with different random
154 initial weights of the neural networks and the best performing model was always selected
155 to be used in the evaluation of the test data.

156 Based on results shown in Lipponen et al. (2022) and our preliminary tests, we uti-
157 lized fully connected feed-forward networks and fixed both the fully learned and post-
158 process correction neural network architectures to 3 hidden layers. In addition, we set
159 the batch size for training to 8, used an initial learning rate of 5×10^{-5} with the Adam
160 optimization algorithm, used mean square error loss, and selected rectified linear unit
161 (ReLU) as the activation function for all hidden layers and linear activation for the out-
162 put.

163 To determine the optimal number of neurons for each layer of the neural networks,
164 the Asynchronous Successive Halving (ASHA) method was used (Li et al., 2020). The
165 ASHA optimization tested all combinations of 8, 32, 128, 512, and 1024 neurons for each
166 layer as a grid search and computed the validation losses for each trained network. The
167 optimization was repeated for 10 different random initializations of the neural networks
168 and the best average validation loss neural network structures were selected for the fi-
169 nal models to be trained. The optimal number of neurons for the three layers in the fully
170 learned model was found as 128, 1024, 128, and for the post-process correction model
171 512, 32, 512.

172 We also carried out full processing of the MODIS AOD data in the region of in-
173 terest (ROI) during the whole DRAGON campaign period to produce AOD maps. In
174 contrast to cross-validation evaluation of the model accuracies, for this use we trained
175 separate fully learned and post-process correction models using full datasets. In the train-
176 ing of the full dataset models, eight AERONET stations were selected to be validation
177 stations that were used to monitor the training convergence and the rest of the data were
178 used as training data. The training of these models was also carried out 20 times with
179 different random initial weights and the models with the smallest validation loss were
180 selected as the final models for the data processing.

181 The dataset used for the training and validation of the models consisted of 2728
182 samples with 26 and 33 input parameters for the fully learned and post-process correc-
183 tion models, respectively. The model training and data processing used in this study were
184 not computationally very expensive and were carried out using a regular laptop computer
185 without GPU capabilities.

186 **2.3 Region of interest and data gridding**

187 We use Washington, D.C. - Baltimore, Maryland, USA, region as our region of in-
188 terest (ROI). The size of the ROI is 120 by 120 km and it is divided into 480 by 480 pixel
189 grid with 250 meter pixel size. The Universal Transverse Mercator (UTM) map projec-
190 tion zone 18 is used for constructing the grid. All spatially distributed parameters are
191 projected to this grid using nearest-neighbor interpolation before the model training and
192 evaluation computations. The ROI is shown in Figure 1.

193 **2.4 Satellite data**

194 We use MODIS data of both Terra and Aqua satellites in this study. As the top-
195 of-atmosphere (TOA) reflectance data, MODIS collection 6.1 level-1b data of bands 1-
196 13, 15, and 19-22 were used. Bands 14, 16-18 were not used as a significant portion of
197 the data was missing. MODIS bands 1 and 2 have native spatial resolution of 250 me-
198 ters, bands 3-7 500 meters, and other bands 1 km at nadir.

199 The physics-based AOD retrieval $\tilde{f}(x)$ we used was the MODIS collection 6.1 aerosol
200 data product MOD04_3KM Dark Target AOD over land with native 3 km spatial res-
201 olution. The measurement geometry information, solar and view zenith and azimuth an-
202 gles, the scattering and glint angles, and also the topographic land altitude were also taken
203 from the MOD04_3KM data product to the aerosol retrieval data.

204 We only accepted pixels with the MODIS view zenith angle less than 50 degrees.
205 This selection was made to restrict the pixels to the central part of swath pixels. As the
206 MODIS pixel size grows towards the edges of the swath, this selection kept the pixel size
207 reasonable and filtered out too large pixels to be used for high-resolution retrievals.

208 **2.5 Ground-based AERONET AOD data**

209 As an accurate ground-based reference AOD data, we used the sunphotometer-based
210 AOD of AERONET stations in the ROI during the DRAGON 2011 campaign. The du-
211 ration of the DRAGON campaign was from June 1 to August 15, 2011. The DRAGON
212 campaign consisted of more than 40 AERONET stations deployed to Washington D.C.
213 - Baltimore region. In this study, we use level 2.0 AERONET AOD at 550 nm which is
214 computed from AOD measurement at 500 nm and Ångström exponent for 440-870 nm.
215 AERONET AOD at visible wavelengths have been reported to have a low uncertainty
216 of 0.01 and therefore we consider the AERONET AOD estimates accurate (Eck et al.,
217 1999). We use AERONET AOD both for training and validation of our models.

218 **2.6 Auxiliary high-resolution data**

219 As we aim at high spatial resolution aerosol data, in addition to satellite-based data,
220 we also used a high-resolution digital elevation model (DEM) as auxiliary data for machine-

221 learning-based models. These auxiliary data were added as additional input parameters
222 in the models.

223 We used GMTED2010 DEM which has 7.5 arc-seconds (about 225 meters) reso-
224 lution (Danielson & Gesch, 2011). For our use, GMTED2010 DEM data was interpo-
225 lated to the 250 meter grid in our ROI.

226 In the post-process correction model, surface reflectance at three different wave-
227 lengths and AOD fields at four different wavelengths retrieved with Dark Target were
228 added as auxiliary inputs. As the 3 km Dark Target AOD fields are noisy and therefore
229 contain sharp changes between the neighboring 3 km pixels, we smoothed the AOD fields
230 before the post-process correction. A 2D convolution using a Gaussian kernel with a 3
231 km standard deviation was used for the AOD field smoothing.

232 **2.7 MODIS-AERONET collocation**

233 For the MODIS-AERONET collocation, we followed a similar protocol as in Bilal
234 et al. (2013). That is, we required the distance between the high-resolution grid pixel
235 center and AERONET station to be less than 750 meters and restricted our data to a
236 maximum number of nine pixels per overpass around an AERONET station. For tem-
237 poral collocation, we used a maximum time difference of ± 250 seconds. With our col-
238 location protocol and data criteria, we ended up having data from 37 different AERONET
239 stations. The excluded stations did not contain any valid pixels.

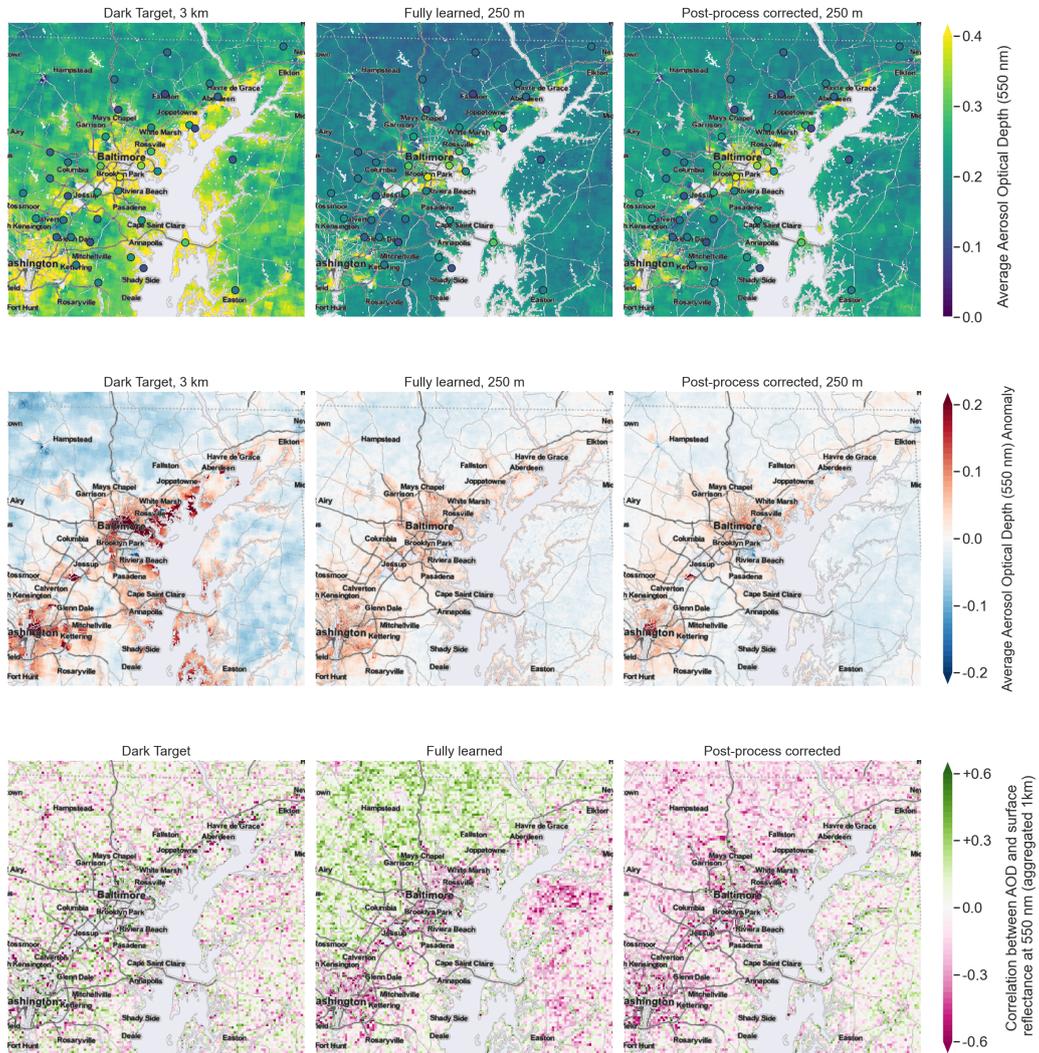
240 **3 Results**

241 Figure 2 shows the MODIS-AERONET AOD comparison for the Dark Target, fully
242 learned model, and the post-process corrected model. The post-process corrected model
243 is clearly the best performing model. The post-process corrected model has all the best
244 metrics with the only exception of bias. The bias of the fully learned model and the post-
245 process corrected models are the same (-0.004). The root mean squared error (RMSE)
246 of the post-process corrected data is only 0.038, which is 28% smaller than the fully learned
247 model RMSE and about 64% smaller than the Dark Target RMSE. The fully learned
248 model has some problems in predicting large AOD values and the highest AOD values
249 are significantly underestimated whereas the highest AODs predicted by the post-process
250 corrected model are all within the Dark Target expected error (EE) envelope. The Dark

251 Target, on the contrary, is overestimating AOD in almost all AERONET overpasses. This
252 type of systematic over- or underestimation is not observed in machine-learning-based
253 AODs. The maximum absolute value of the retrieval error in the post-process corrected
254 AOD is less than half of the one obtained with the fully learned model. The fraction of
255 retrievals within the Dark Target EE envelope is also clearly better in the post-process
256 corrected AOD (96.4%) than in the fully learned AOD retrievals (91.6%). The Dark Tar-
257 get fraction within EE envelope was 67.2%.

258 All MODIS overpasses of the DRAGON campaign were processed using the final
259 trained fully learned and post-process correction models. Figure 1 shows the average AOD
260 and the average of daily AOD anomalies with respect the daily mean of the AOD in the
261 ROI for the DRAGON campaign duration for the Dark Target, fully learned model, and
262 post-process correction model. Average AERONET AOD for the DRAGON campaign
263 duration collocated with MODIS overpasses are also shown. The AOD anomalies were
264 constructed by first computing daily anomalies as the differences of the full AOD fields
265 and the daily ROI average AODs and then temporally averaging the daily anomalies over
266 the whole duration of the DRAGON campaign. On average, there were 2.8 daily MODIS
267 overpasses during the campaign. The map figure shows that the Dark Target AODs are
268 significantly higher than the AOD obtained with fully learned or post-process correction
269 approaches. The machine-learning-based AOD datasets match better the AOD from the
270 AERONET stations. Near the coastline both of the machine-learning-based approaches
271 seem to work well and do not show any clear anomalies near the coast whereas Dark Tar-
272 get shows elevated AOD values near the coast with no clear physical explanation to it.
273 AERONET observations do not show elevated AOD values near the coastline. The AOD
274 anomaly maps show higher AOD values over the urban areas in Washington D.C. and
275 Baltimore and between them. The average positive AOD anomaly is stronger in the DT
276 dataset, about 0.2 over the densest urban areas, than those based on machine learning
277 that have anomaly value of about 0.1 over the densest urban areas. Both of the machine-
278 learning-based datasets have a good agreement with the AERONET over urban areas.

279 To evaluate the possible contribution of surface reflectance to the retrieved AOD,
280 we studied the correlation between the MODIS nadir bidirectional reflectance distribu-
281 tion function (BRDF)-adjusted surface reflectance from the MCD43A4 data product and
282 AOD over the ROI. This surface reflectance dataset is based on atmospheric correction
283 that treats the aerosols independently of the DT algorithm. The same daily surface re-



Map tiles by Stamen Design, under CC BY 3.0. Data by OpenStreetMap, under ODbL.

Figure 1. Top row: average MODIS AOD at 550 nm during the DRAGON campaign. Middle row: Average daily MODIS AOD at 550 nm anomaly. Bottom row: Correlation between AOD and MODIS surface reflectance at 550 nm. Correlation is shown with data aggregated to 1 km spatial resolution. Left column: Dark Target. Middle column: Fully learned model. Right column: Post-process corrected Dark Target.

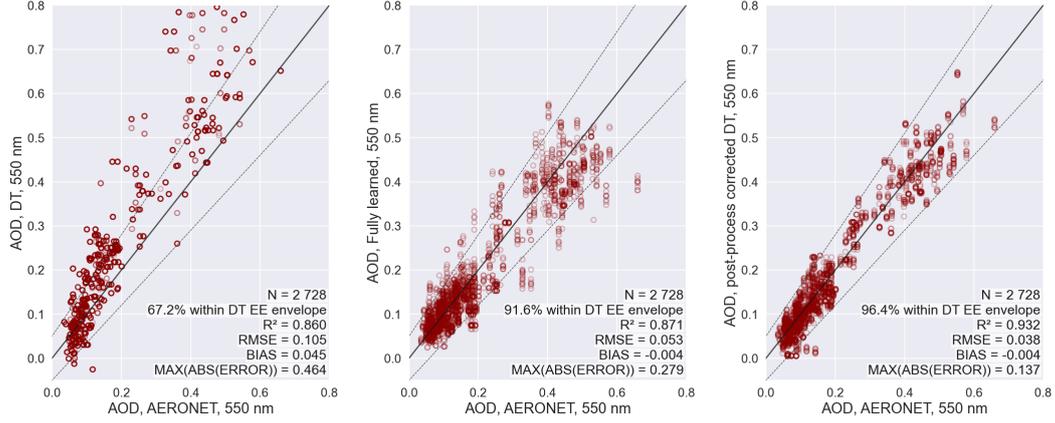


Figure 2. MODIS-AERONET AOD at 550 nm comparison. Left: Dark Target (DT) 3 km. Middle: Fully learned model. Right: Post-process corrected Dark Target. Each marker in the image corresponds to a single collocated MODIS-AERONET overpass. The following metrics are shown for each model: the number of samples N , the fraction of retrievals within the Dark Target expected error (DT EE) envelope $0.05 \pm 15\%$, root mean squared error (RMSE), mean bias (BIAS), and the maximum absolute error ($\text{MAX}(\text{ABS}(\text{ERROR}))$).

284 reflectance data were used for computing the correlations for all AOD datasets. The cor-
 285 relations between AOD and surface reflectance at 550 nm is shown in Figure 1. To
 286 reduce the noise in the correlation maps, the correlations were computed with data aggre-
 287 gated to 1 km spatial resolution. The maps showing the correlation between the surface
 288 reflectance and AOD for DT and post-process corrected AOD do not have a clear con-
 289 trast between the dense urban and surrounding regions. Both of the machine-learning-
 290 based datasets generally show opposite signed correlation between the southeast and north-
 291 west corners of the ROI. The fully learned model results in mainly positive correlation
 292 on the northwest corner and negative on the southeast corner, and the post-process cor-
 293 rected AOD behaves the opposite way. We did not find a clear explanation for this be-
 294 havior. For the fully learned model AOD and surface reflectance correlation, the urban
 295 areas of Washington D.C. and Baltimore are visible as they have a negative correlation,
 296 whereas the nearby surrounding regions have a positive correlation. Furthermore, the
 297 fully learned model AOD was observed to be underestimated in most retrievals over AERONET
 298 stations associated with the highest surface reflectances. This type of behaviour was not
 299 observed with DT or the post-process corrected AOD.

300 Regardless of the DRAGON campaign being a unique campaign for high-resolution
301 validation of satellite data, the distance between the stations is still not good enough for
302 very high resolution evaluation. In this study, regardless of the dense and unique AERONET
303 setting in the ROI, the average distance between two AERONET stations was 1.2 km,
304 and the average distance of a pixel in our ROI to the nearest AERONET station about
305 12 km. As the distances are significantly larger than our pixel size 250 meters, we need
306 to visually inspect these retrieval maps and see some features to assess the results. We
307 do not observe any very local and clearly distinctive AOD features in any of the aver-
308 age AOD datasets. This was expected as aerosols are easily transported and mixed lo-
309 cally in the atmosphere and we expected the average AOD fields to be relatively smooth.
310 Over cities, the average satellite-based AOD fields are clearly higher than in the surround-
311 ing regions in all datasets.

312 We used SHapley Additive exPlanations (SHAP) to explain the variables that have
313 the largest impact on the correction of AOD (Lundberg & Lee, 2017). We used the Deep-
314 Explainer model of the Shap Python library and computed the average SHAP values for
315 10000 randomly selected pixels based on set of background values of another 10000 ran-
316 domly selected pixels. The results show that, on average, the most significant variables
317 to explain the retrieval error correction terms are the AOD at 440 nm, 675 nm, and 550
318 nm, the GMTED2010 surface elevation, TOA reflectances at bands 11 and 9, and the
319 AOD at 2100 nm. The mentioned variables explain about 60% of the AOD correction
320 term. As the DT AOD is typically overestimated, it is expected that AOD input terms
321 explain quite a large fraction of the correction. Topographic altitude terms in the list
322 for this ROI probably act as a proxy for some other quantity and indicate some indirect
323 effect, such as distance from the coastline, not the real dependency of the AOD correc-
324 tion to surface altitude. The most important TOA reflectance bands correspond to wave-
325 lengths 526-536 nm and 438-448 nm.

326 Figure 3 shows AOD time series for the DRAGON_ARNLS station and AOD fields
327 corresponding to two MODIS overpasses for the Dark Target, the fully learned model,
328 and the post-process correction. The DRAGON_ARNLS station was one of the 8 sta-
329 tions not used in the actual training of the models but the convergence monitoring only.
330 The figure shows Dark Target mostly overestimates AOD at this location. Both of the
331 machine-learning-based models follow well the changes in AOD over the whole campaign
332 duration. The AOD maps corresponding to single overpasses clearly show the coarser

333 3 km resolution of the Dark Target. Both the fully learned and post-process corrected
334 models result in smooth AOD fields. Regardless of the high spatial resolution and the
335 independent treatment of all pixels in both fully learned and post-process correction ap-
336 proaches, the AOD fields are highly consistent and look feasible. There are no single pix-
337 els that would have significantly higher or lower AOD than the neighboring pixels. The
338 AOD fields do not seem to contain significant noise. The MODIS overpass correspond-
339 ing to 24 July 2011 15:45Z has a significant fraction of missing data. This indicates most
340 of the ROI was covered by clouds at the satellite overpass time. The maps show that all
341 retrieval approaches do work well in the vicinity of clouds and do not show any behav-
342 ior correlated for example with the distance from the cloud.

343 **4 Summary and Conclusions**

344 In this study, we developed a machine-learning-based post-process correction ap-
345 proach to correct and downscale the MODIS AOD. The post-process correction approach
346 combines both the physics-based conventional retrieval algorithms and machine learn-
347 ing. In the development, we concentrated on downscaling and improving the accuracy
348 of the satellite-based AOD. We used the AERONET year 2011 DRAGON campaign over
349 the Baltimore - Washington D.C. area to evaluate our approach.

350 We compared our post-process corrected AOD to the 3 km MODIS Dark Target
351 aerosol data product and the fully-learned machine learning approach in which the machine-
352 learning model was trained to carry out the AOD retrieval. The results show that our
353 post-process correction approach is suitable for the downscaling of existing aerosol data
354 products and results in clearly improved AOD accuracy over both the Dark Target and
355 fully learned AOD.

356 Accurate high-resolution AOD would be highly beneficial, for example, for the air
357 quality applications. Improvements in satellite-based AOD estimates will directly trans-
358 late into improved PM_{2.5} estimates. The post-process corrected AOD serves as a highly
359 promising starting point for satellite-based air quality PM_{2.5} estimates.

360 Extension of the post-process correction approach is straightforward to other re-
361 trieved quantities and instruments as long as suitable training data is available. We ex-
362 pect the post-process correction approach to be highly beneficial, especially for appli-
363 cations with scarce training data. With a small number of training data samples, the fully

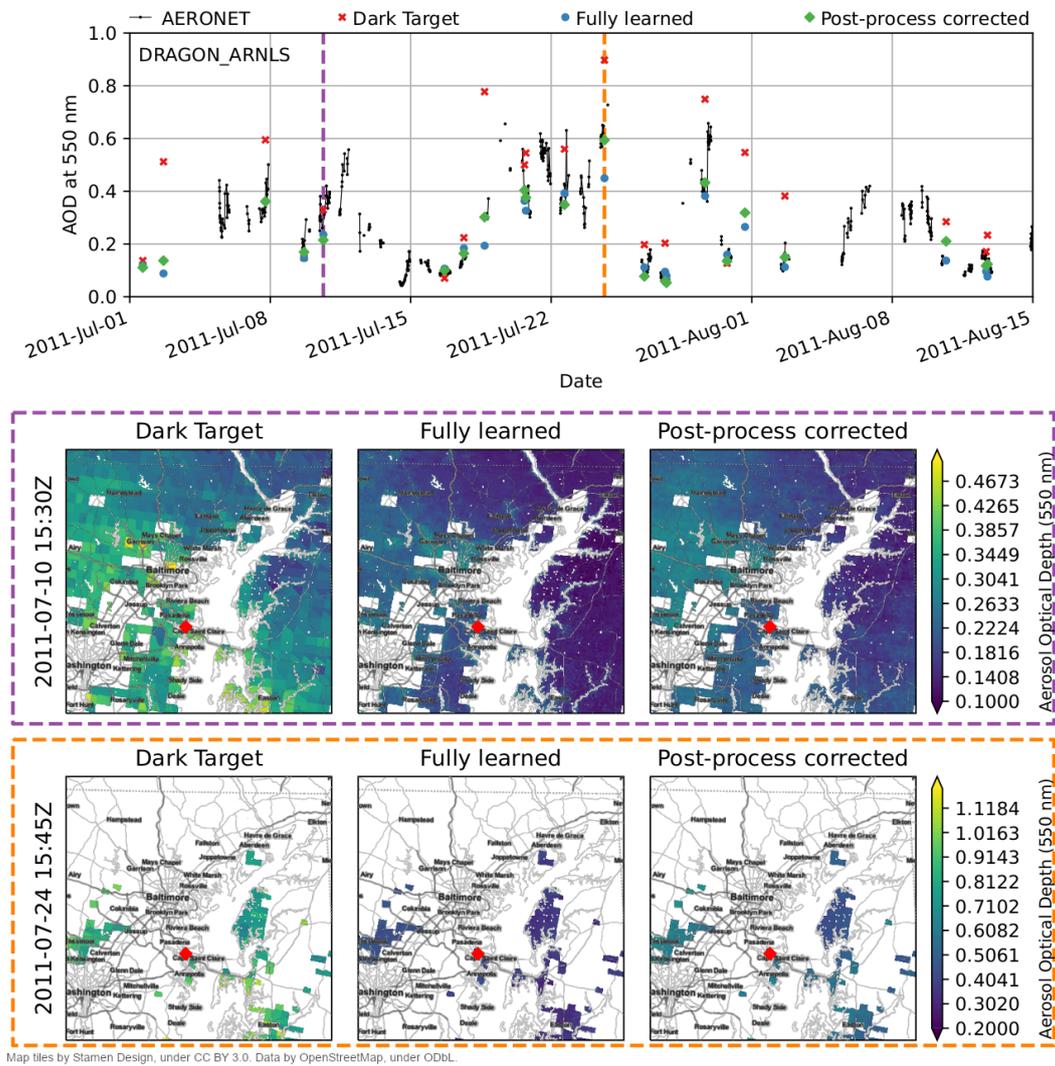


Figure 3. Top row: AOD 550 nm time series for the DRAGON_ARNLS station. Middle row: MODIS overpass on 10 July 2011 at 15:30Z. Left: Dark Target AOD. Middle: Fully learned AOD. Right: Post-process corrected AOD. Bottom row: MODIS overpass on 24 July 2011 at 15:45Z. Left: Dark Target AOD. Middle: Fully learned AOD. Right: Post-process corrected AOD. The purple and orange dashed lines on the top time series figure correspond to middle and bottom row overpasses, respectively. The red diamond symbol on the maps indicates the location of the AERONET station.

364 learned models may generalize poorly and fail with inputs not present in the training
365 data. By the support of physics-based retrieval algorithms, we expect better generaliza-
366 tion in the prediction of the retrieval error than the retrieval itself and therefore expect
367 post-process correction to be a successful approach in many applications.

368 **5 Open Research**

369 The AERONET DRAGON 2011 campaign data used in this study are openly avail-
370 able and were obtained from the NASA AERONET website [https://aeronet.gsfc.nasa](https://aeronet.gsfc.nasa.gov/)
371 [.gov/](https://aeronet.gsfc.nasa.gov/). All MODIS data used in this study are open data and were obtained from the
372 NASA Level-1 and Atmosphere Archive & Distribution System Distributed Active Archive
373 Center (LAADS DAAC) <https://ladsweb.modaps.eosdis.nasa.gov/>. The GMTED2010
374 digital elevation model data is public domain and were obtained from the U.S. Geolog-
375 ical Survey Earth Resources Observation and Science (EROS) Center website [https://](https://www.usgs.gov/centers/eros/science/usgs-eros-archive-digital-elevation-global-multi-resolution-terrain-elevation)
376 [www.usgs.gov/centers/eros/science/usgs-eros-archive-digital-elevation-global](https://www.usgs.gov/centers/eros/science/usgs-eros-archive-digital-elevation-global-multi-resolution-terrain-elevation)
377 [-multi-resolution-terrain-elevation](https://www.usgs.gov/centers/eros/science/usgs-eros-archive-digital-elevation-global-multi-resolution-terrain-elevation).

378 Software (version 1.0.0 / 24 May 2022) associated with this manuscript to carry
379 out and reproduce the data download, pre-processing, downscaling and post-process cor-
380 rection and validation of AOD is licensed under MIT and published on GitHub [https://](https://github.com/TUT-ISI/DRAGONcorr/)
381 github.com/TUT-ISI/DRAGONcorr/ (Lipponen, 2022).

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