

# Improved Automated Building Extraction from High Resolution Remotely-sensed Imagery using Time-optimised Deep Learning Techniques

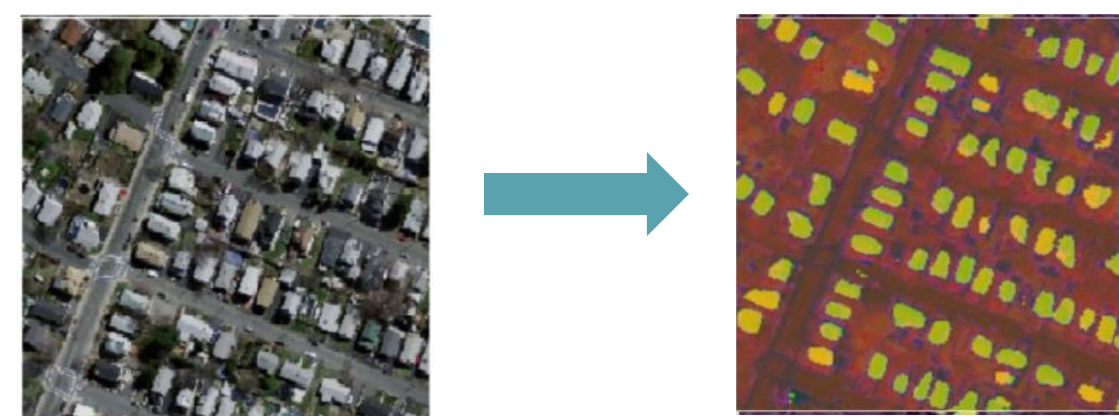
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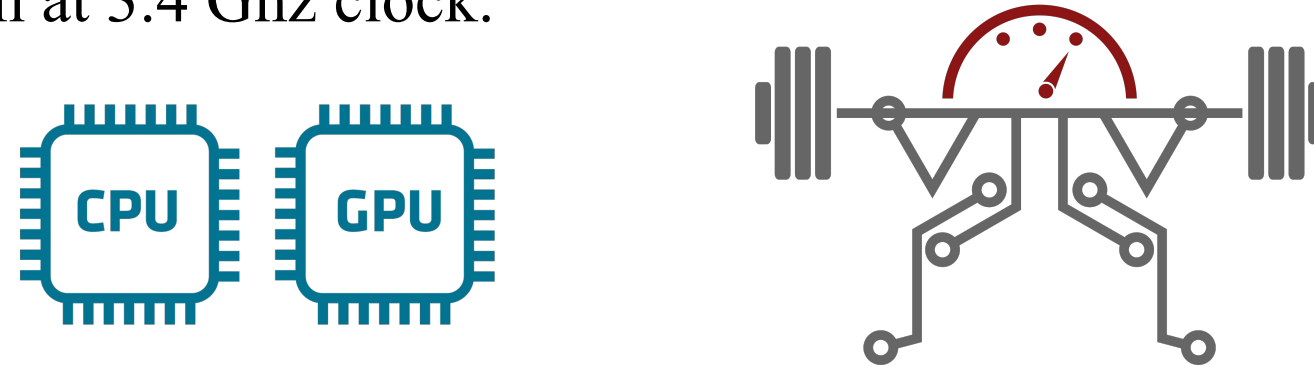
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## INTRODUCTION

- Automating building extraction has been one of the hottest research topics given its applications in urban planning, urban monitoring, urban change detection, urban heat islands, damage assessment, disaster management, building index growth, cadastral mapping etc.



- Being a highly cognitive problem, there is a hardcore requirement of high spectral-spatial contextual information, which also poses as a significant challenge as there is always a trade-off between spectral and spatial resolution in remote sensing.
- Since the past decade, Deep Learning algorithms, with their representational ability, have stepped up to address this issue by producing excellent results with high and very high resolution spatial data hence reducing the requirement for a densely spectral information plot. Moreover, there are always performance challenges in case of blurred or irregular boundaries.
- However, deep learning algorithms come with a downside of high time and resource requirement to train the model. And on a large dataset of aerial/satellite imagery, the training takes more than 20 hours even on a high memory (16 GB) and GPU (4 GB) system at 3.4 Ghz clock.



## OBJECTIVE

This study has the following objectives:

- To develop a single deep neural network for multiscale building extractions.
- To propose a cost function that can handle irregular shapes and blurred boundaries for building detection
- To optimize the training process of neural network without reducing the trainable parameters and meeting the benchmarks for building extraction

## METHODOLOGY

- U-Net with dynamic encoder-decoder architecture is built on top of a pretrained
- A new loss function, “Combo Loss”, which is a combination of two fundamental cost functions based on edge loss and region loss, is suggested. This way a single loss function accounts for irregular shapes (region loss) and blurred boundaries (edge loss)

- Loss Functions – Unique Combo Loss

$$\text{ComboLoss} = \text{BCE}_{\text{Loss}} + \text{DiceLoss}$$

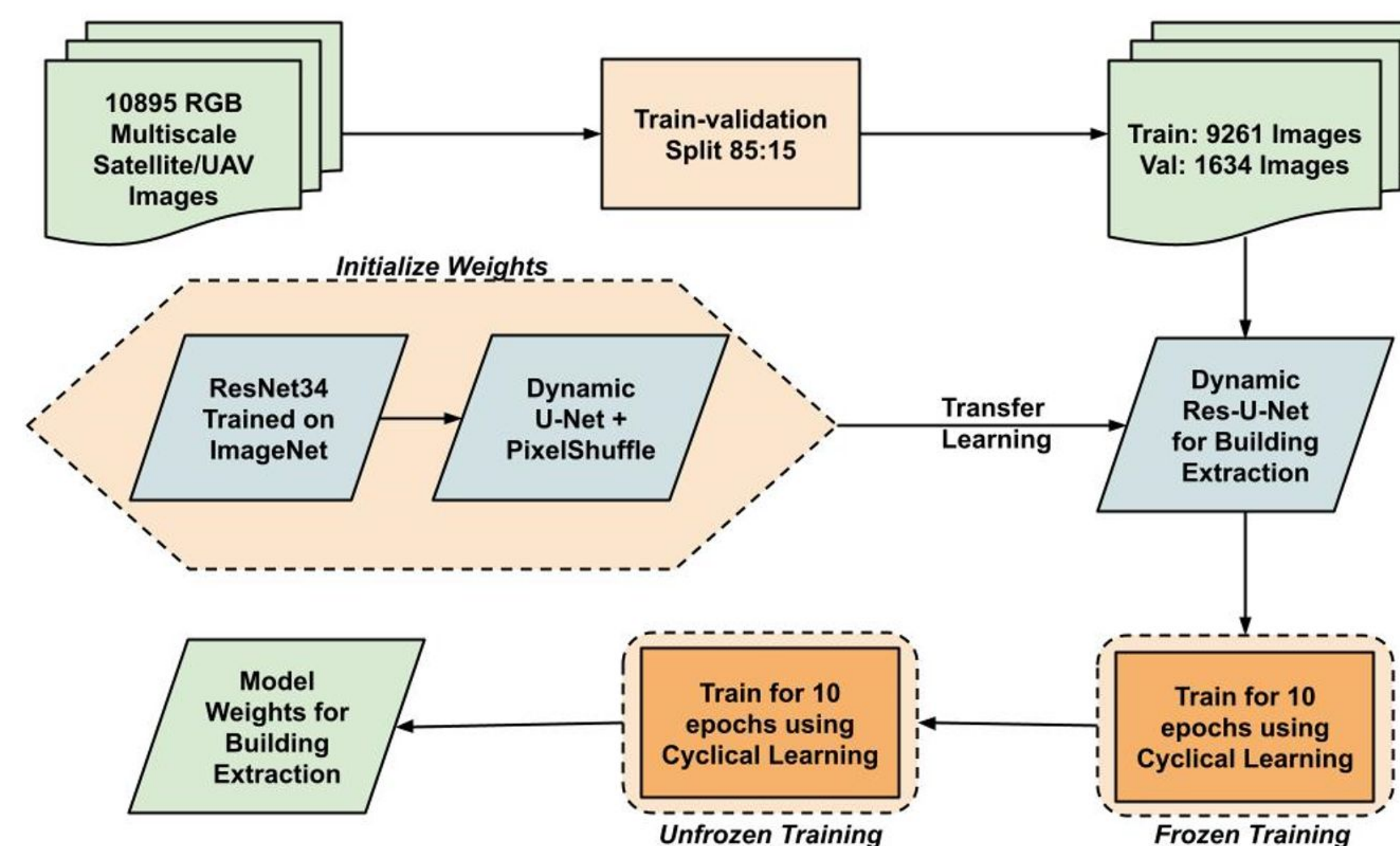
Where g = ground truth image and p = predicted image

$$\text{BCE}_{\text{Loss}} = -\frac{1}{\text{patchsize}} \sum_{i=1}^{\text{patchsize}} g_i \times \log p_i + (1 - g_i) \times \log(1 - p_i)$$

$$\text{DiceLoss} = \frac{2 \times \sum_{i=0}^{\text{patchsize}} p_i g_i}{\sum_{i=0}^{\text{patchsize}} p_i^2 + \sum_{i=0}^{\text{patchsize}} g_i^2}$$



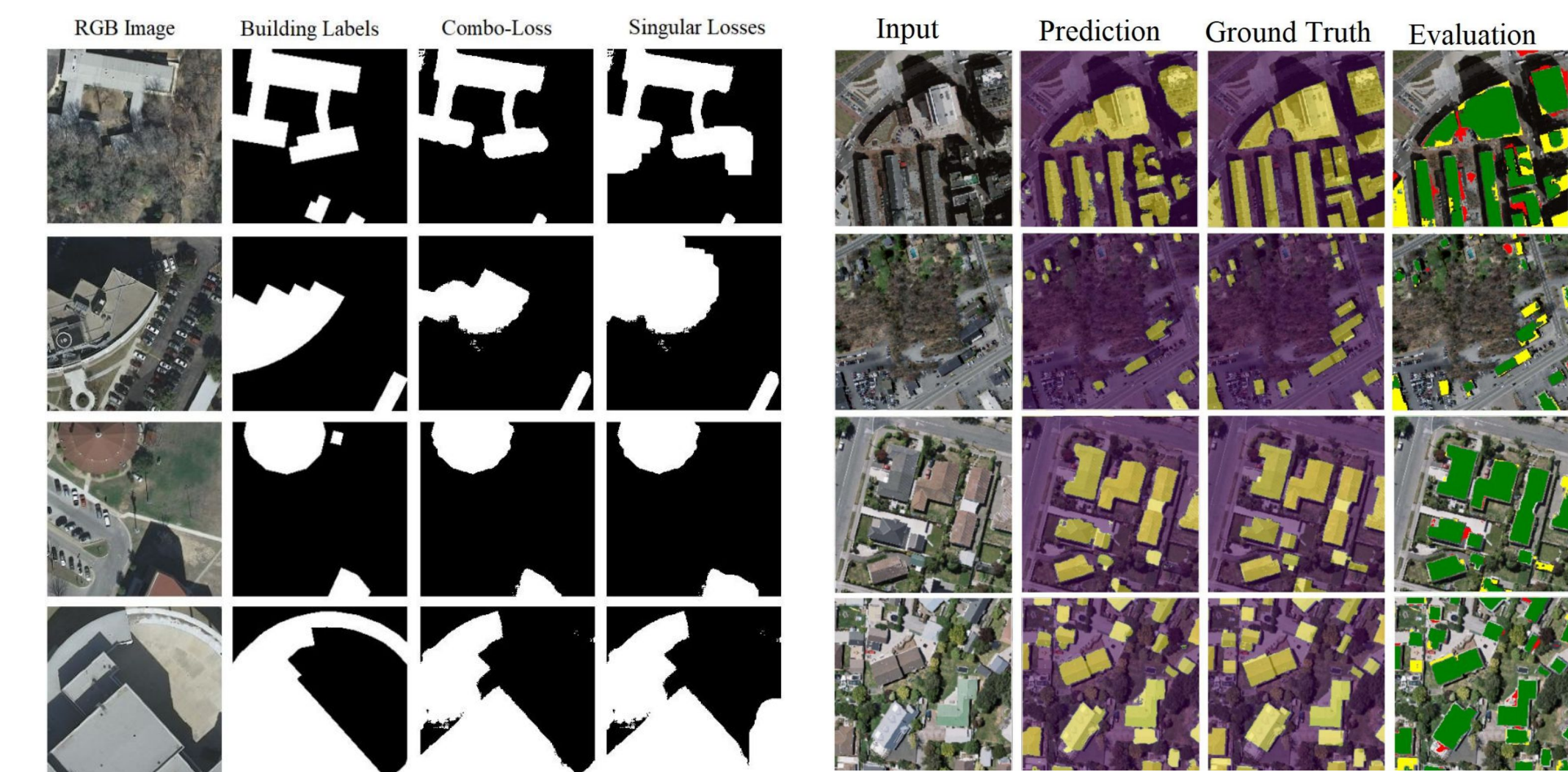
- To reduce the training time and consequently the resource consumption for the deep learning model, a unique order to train the network layers is suggested. Since the last few layers are most difficult to train, we train them first, until they start to converge.
- This is done by freezing the model, training the last layers until earliest convergence and then unfreezing the model, training the entire model from the input layer to the output layer.



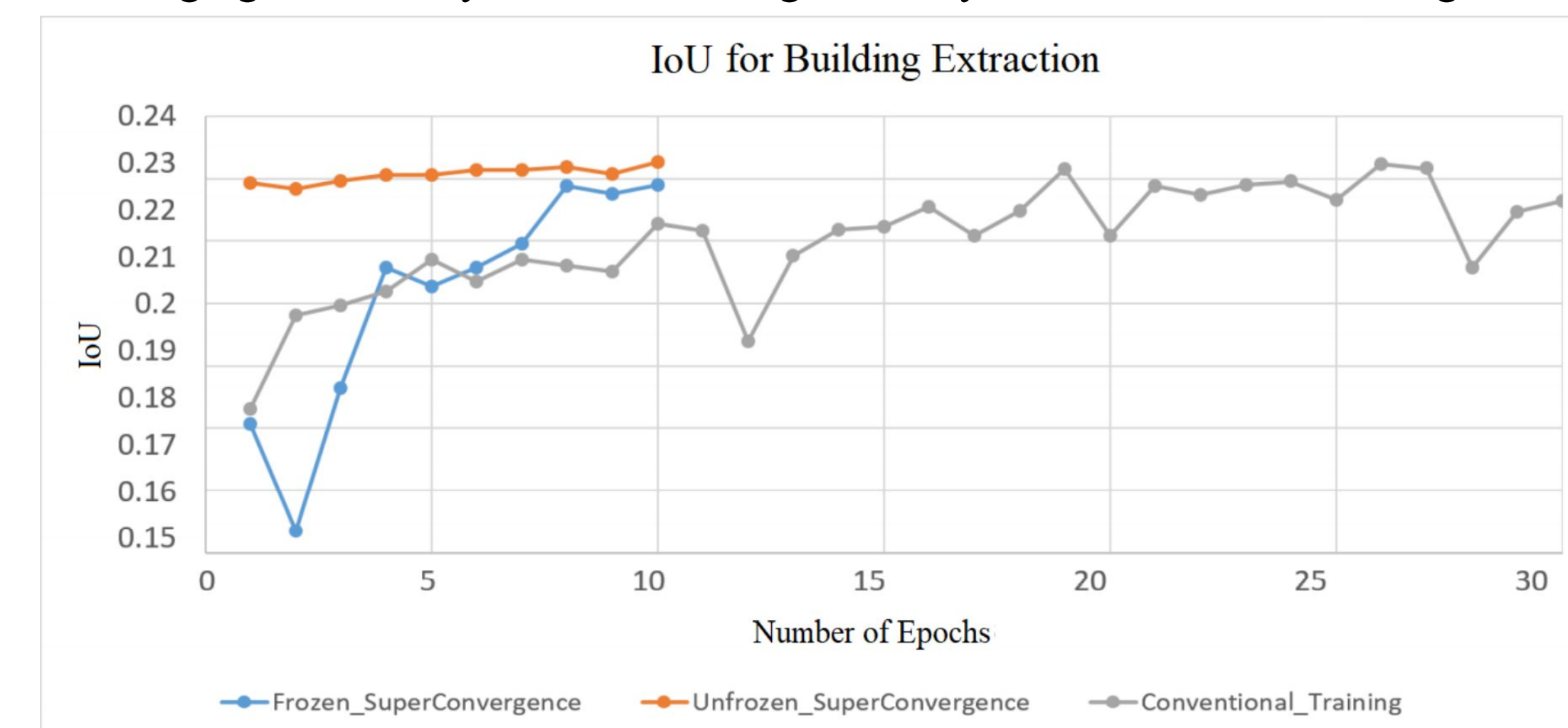
- In addition to changing the order of training the layers, we also implement the policy of cyclical learning, which dynamically changes the learning rate while training the model, depending on the gradient of loss.

## RESULTS

- Combo Loss improves building extraction for irregular shapes and blurred boundaries. One-cycle fit policy identifies optimum learning rate dynam



- Changing order of layers while training evidently makes the model converge faster



	Conventional Training Method	Proposed Training Method
Accuracy	95.6%	96.55%
Dice Score	0.772	0.785
Mean IoU	0.80	0.84
Mean F1-Score	0.88	0.91
Training Epochs	30	10
Training Time	~11.2 hours	~4.5 hours

