

RESEARCH ARTICLE

Analytical solutions describing the oblique flow of a viscous incompressible fluid around a dendritic crystal

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This article considers the hydrodynamic problem of an oblique flow of a viscous incompressible fluid around the tip of a dendritic crystal. Approximate analytical solutions of Oseen's hydrodynamic equations are obtained in 2D and 3D cases using special curvilinear coordinates. It is shown that the projections of the fluid velocity change significantly with a change in the flow slope and Reynolds number. The theory developed in this work has a limiting transition to the previously known solutions for the rectilinear (without tilt) fluid flow around a dendrite.

KEYWORDS:

hydrodynamics, dendrites, applied mathematical modeling, crystal growth

1 | INTRODUCTION

It is well known that the dendritic shape of crystals is one of the most common growth forms in the processes of phase transformations from metastable solutions and melts.^{1–10} As this takes place, the shape of the dendrite vertex is described by a power function close to a parabola (paraboloid) at distances of the order of several radii of curvature of its tip.¹¹ Quite often, in nature, technological processes, and laboratory experiments, dendrites grow in the oncoming convective flow of a viscous liquid (melt or solution).^{12–15} In addition, such a liquid flow can be directed at an angle to the direction of crystal growth or change its direction during crystallization. This fluid flow, as is known, leads to a redistribution of temperature and impurities dissolved in the fluid (the fluid flow rate is involved in the equations of convective heat conduction and diffusion of impurities, as well as in the boundary conditions to them). Therefore, it becomes necessary to solve the hydrodynamic problem of an oblique flow of a viscous fluid around a dendrite growing in a metastable fluid. The solution of such a hydrodynamic problem is also in demand in the theory of selecting a stable mode of dendritic growth in inclined flows of an undercooled (supersaturated) liquid.^{16–18}

Taking into account the above-described practical relevance, in this article, a solution to the hydrodynamic problem of an oblique flow of a viscous fluid around a two-dimensional (three-dimensional) dendritic crystal is derived. Since the Navier-Stokes equations for this flow geometry do not have exact solutions, we use here the Oseen hydrodynamic equations.^{19–21} Strictly speaking, the Oseen system of equations takes place at low Reynolds numbers. However, in some cases, these equations describe fluid flows at Reynolds numbers of the order of unity.²¹

This paper is organized as follows. The governing equations for an oblique flow occurring around two- and three-dimensional dendritic crystals are formulated and analytically solved in Section 2. Here the solution is also rewritten in the reference frame connected with a growing dendrite. A behaviour of hydrodynamic solutions under consideration as well as the main outcomes and future developments of the theory are given in Section 3.

2 | GOVERNING EQUATIONS

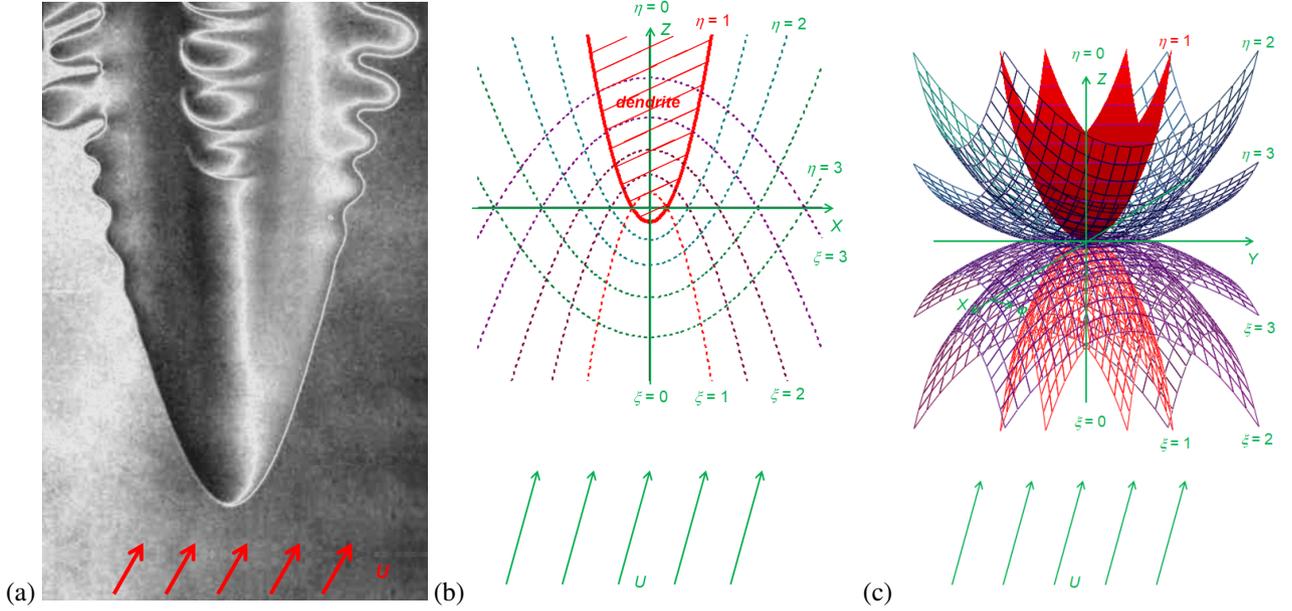


FIGURE 1 A tip region of dendritic crystal in an oblique flow of a viscous fluid (a) and the coordinate systems of a parabolic cylinder (b) and a paraboloid of revolution (c) describing its growth.

2.1 | Parabolic/paraboloidal reference frames

Suppose the vertex of a dendritic crystal is parabolic/paraboloidal. This makes it possible to use the following curvilinear coordinates when describing two- and three-dimensional fluid flows around dendrites (see figure 1).

The parabolic cylinder reference frame ξ and η (two-dimensional dendrite) is related to the Cartesian reference frame x , y and z as follows

$$\frac{z}{\rho} = Z = \frac{\xi^2 - \eta^2}{2}, \quad \frac{y}{\rho} = Y = Y, \quad \frac{x}{\rho} = X = \xi\eta, \quad (1)$$

where ρ - stands for the dendrite tip diameter. Note that the crystal surface in parabolic coordinates (1) takes the form $\eta = 1$. As this takes place, the fluid is in the domain $0 \leq \xi < \infty$ and $1 < \eta < \infty$.

The unit vectors in both coordinate systems read as

$$\mathbf{e}_z = \frac{\xi \mathbf{e}_\xi - \eta \mathbf{e}_\eta}{\sqrt{\xi^2 + \eta^2}}, \quad \mathbf{e}_x = \frac{\eta \mathbf{e}_\xi + \xi \mathbf{e}_\eta}{\sqrt{\xi^2 + \eta^2}}. \quad (2)$$

To find the partial derivatives in hydrodynamic equations, we use the Lamé coefficients

$$h_\xi = h_\eta = \rho \sqrt{\xi^2 + \eta^2}, \quad h_y = \rho. \quad (3)$$

Using (2) and (3) one can get the following expressions

$$\frac{\partial}{\partial Z} = \frac{\xi}{\xi^2 + \eta^2} \frac{\partial}{\partial \xi} - \frac{\eta}{\xi^2 + \eta^2} \frac{\partial}{\partial \eta}, \quad \frac{\partial}{\partial X} = \frac{\eta}{\xi^2 + \eta^2} \frac{\partial}{\partial \xi} + \frac{\xi}{\xi^2 + \eta^2} \frac{\partial}{\partial \eta}. \quad (4)$$

The paraboloid of revolution reference frame ξ , η and φ (three-dimensional dendrite) is related to the Cartesian reference frame x , y and z as follows

$$\frac{z}{\rho} = Z = \frac{\xi^2 - \eta^2}{2}, \quad \frac{y}{\rho} = Y = \xi\eta \sin \varphi, \quad \frac{x}{\rho} = X = \xi\eta \cos \varphi. \quad (5)$$

As before, the crystal surface is given by $\eta = 1$, and the fluid is in the domain $0 \leq \xi < \infty$, $1 < \eta < \infty$ and $0 \leq \varphi < 2\pi$.

The unit vectors and Lamé coefficients have the form

$$\mathbf{e}_z = \frac{\xi \mathbf{e}_\xi - \eta \mathbf{e}_\eta}{\sqrt{\xi^2 + \eta^2}}, \quad \mathbf{e}_y = \frac{\eta \sin \varphi \mathbf{e}_\xi + \xi \sin \varphi \mathbf{e}_\eta}{\sqrt{\xi^2 + \eta^2}} - \cos \varphi \mathbf{e}_\varphi, \quad \mathbf{e}_x = \frac{\eta \cos \varphi \mathbf{e}_\xi + \xi \cos \varphi \mathbf{e}_\eta}{\sqrt{\xi^2 + \eta^2}} + \sin \varphi \mathbf{e}_\varphi, \quad (6)$$

$$h_\xi = h_\eta = \rho \sqrt{\xi^2 + \eta^2}, \quad h_\varphi = \rho \xi \eta. \quad (7)$$

Taking (6) and (7) into account, we arrive at

$$\frac{\partial}{\partial Z} = \frac{\xi}{\xi^2 + \eta^2} \frac{\partial}{\partial \xi} - \frac{\eta}{\xi^2 + \eta^2} \frac{\partial}{\partial \eta}, \quad \frac{\partial}{\partial Y} = \frac{\eta \sin \varphi}{\xi^2 + \eta^2} \frac{\partial}{\partial \xi} + \frac{\xi \sin \varphi}{\xi^2 + \eta^2} \frac{\partial}{\partial \eta} - \frac{\cos \varphi}{\xi \eta} \frac{\partial}{\partial \varphi}, \quad (8)$$

$$\frac{\partial}{\partial X} = \frac{\eta \cos \varphi}{\xi^2 + \eta^2} \frac{\partial}{\partial \xi} + \frac{\xi \cos \varphi}{\xi^2 + \eta^2} \frac{\partial}{\partial \eta} + \frac{\sin \varphi}{\xi \eta} \frac{\partial}{\partial \varphi}. \quad (9)$$

2.2 | The Oseen hydrodynamic equations

We describe the flow of a viscous incompressible fluid around a dendritic crystal using linear Oseen equations. Methods for solving these equations are well-known in modern literature.^{19–22} We use here the approach developed by Dash and Gill.²¹ So, the hydrodynamic model takes the form of

$$\mathbf{U} \cdot \nabla \mathbf{u} = -\frac{1}{\rho_l} \nabla p + \nu \nabla^2 \mathbf{u}, \quad \nabla \cdot \mathbf{u} = 0. \quad (10)$$

Here $\mathbf{u} = (u, v, w)$ is the fluid velocity with components u, v, w on the coordinate axes z, y, x , $\mathbf{U} = (U_z, U_y, U_x)$ stands for the fluid velocity far from the solid surface $\eta = 1$ with coordinates U_z, U_y, U_x , ρ_l - is the density, p is the pressure, ν is the kinematic viscosity.

These equations should be supplemented with the following boundary conditions

$$u = v = w = 0, \quad \eta = 1; \quad u \rightarrow U_z, \quad v \rightarrow U_y, \quad w \rightarrow U_x, \quad \eta \rightarrow \infty. \quad (11)$$

For the convenience of solving the problem, we use the relative velocities

$$u' = u - U_z, \quad v' = v - U_y, \quad w' = w - U_x, \quad (12)$$

$n = U_y/U_z$, $l = U_x/U_z$ and the Reynolds number $\text{Re} = U_z \rho / \nu$. Taking these designations into account, we rewrite (10) as

$$\text{Re} \frac{\partial u'}{\partial Z} + n \text{Re} \frac{\partial u'}{\partial Y} + l \text{Re} \frac{\partial u'}{\partial X} = -\frac{\rho}{\rho_l \nu} \frac{\partial p}{\partial Z} + \frac{\partial^2 u'}{\partial Z^2} + \frac{\partial^2 u'}{\partial Y^2} + \frac{\partial^2 u'}{\partial X^2}, \quad (13)$$

$$\text{Re} \frac{\partial v'}{\partial Z} + n \text{Re} \frac{\partial v'}{\partial Y} + l \text{Re} \frac{\partial v'}{\partial X} = -\frac{\rho}{\rho_l \nu} \frac{\partial p}{\partial Y} + \frac{\partial^2 v'}{\partial Z^2} + \frac{\partial^2 v'}{\partial Y^2} + \frac{\partial^2 v'}{\partial X^2}, \quad (14)$$

$$\text{Re} \frac{\partial w'}{\partial Z} + n \text{Re} \frac{\partial w'}{\partial Y} + l \text{Re} \frac{\partial w'}{\partial X} = -\frac{\rho}{\rho_l \nu} \frac{\partial p}{\partial X} + \frac{\partial^2 w'}{\partial Z^2} + \frac{\partial^2 w'}{\partial Y^2} + \frac{\partial^2 w'}{\partial X^2}, \quad (15)$$

$$\frac{\partial u'}{\partial Z} + \frac{\partial v'}{\partial Y} + \frac{\partial w'}{\partial X} = 0. \quad (16)$$

In addition, expressions (11) read as

$$u' = -U_z, \quad v' = -U_y, \quad w' = -U_x, \quad \eta = 1; \quad u' \rightarrow 0, \quad v' \rightarrow 0, \quad w' \rightarrow 0, \quad \eta \rightarrow \infty. \quad (17)$$

2.3 | Complete solutions of 2D and 3D models

For the convenience of finding analytical solutions, we introduce additional functions M and N

$$u' = \frac{\partial M}{\partial Z} + \frac{1}{\text{Re}} \frac{\partial N}{\partial Z} - N, \quad v' = \frac{\partial M}{\partial Y} + \frac{1}{\text{Re}} \frac{\partial N}{\partial Y} - nN, \quad (18)$$

$$w' = \frac{\partial M}{\partial X} + \frac{1}{\text{Re}} \frac{\partial N}{\partial X} - lN, \quad p = -\frac{\rho_l \nu}{\rho} \text{Re} \left(\frac{\partial M}{\partial Z} + n \frac{\partial M}{\partial Y} + l \frac{\partial M}{\partial X} \right). \quad (19)$$

In the two-dimensional case, $v' = 0$ and M is independent on Y .

Substitution of (18) and (19) into (13)-(16) leads to

$$\frac{\partial^2 M}{\partial Z^2} + \frac{\partial^2 M}{\partial Y^2} + \frac{\partial^2 M}{\partial X^2} = 0, \quad \frac{\partial^2 N}{\partial Z^2} + \frac{\partial^2 N}{\partial Y^2} + \frac{\partial^2 N}{\partial X^2} - \operatorname{Re} \left(\frac{\partial N}{\partial Z} + n \frac{\partial N}{\partial Y} + l \frac{\partial N}{\partial X} \right) = 0. \quad (20)$$

An important point is that we consider the problem in the vicinity of the dendritic tip where ξ is small. Keeping this in mind, assuming $M = M(\eta)$ and $N = N(\eta)$, we rewrite (20) with the help of (4), (8), (9), and arrive at

$$\text{2D case : } \frac{d^2 M}{d\eta^2} = 0, \quad \frac{d^2 N}{d\eta^2} + \operatorname{Re} \eta \frac{dN}{d\eta} = 0, \quad (21)$$

$$\text{3D case : } \frac{d^2 M}{d\eta^2} + \frac{1}{\eta} \frac{dM}{d\eta} = 0, \quad \frac{1}{\eta} \frac{d}{d\eta} \left(\eta \frac{dN}{d\eta} \right) + \operatorname{Re} \eta \frac{dN}{d\eta} = 0. \quad (22)$$

The solution of equations (21) and (22) has the form

$$\text{2D case : } M(\eta) = A_1 \eta + B_1, \quad N(\eta) = C_1 \int_1^\eta \exp \left(-\frac{\operatorname{Re} t^2}{2} \right) dt + C_2, \quad (23)$$

$$\text{3D case : } M(\eta) = A_2 \ln \eta + B_2, \quad N(\eta) = D_1 \int_1^\eta \exp \left(-\frac{\operatorname{Re} t^2}{2} \right) \frac{dt}{t} + D_2. \quad (24)$$

Substitution of (23) and (24) into (17), (18) and (19) enables us to find the arbitrary constants

$$A_1 = A_2 = -\frac{C_1 \exp(-\operatorname{Re}/2)}{\operatorname{Re}}, \quad C_1^{-1} = -C_2^{-1} \int_1^\infty \exp \left(-\frac{\operatorname{Re} t^2}{2} \right) dt, \quad (25)$$

$$D_1^{-1} = -D_2^{-1} \int_1^\infty \exp \left(-\frac{\operatorname{Re} t^2}{2} \right) \frac{dt}{t}, \quad C_2 = D_2 = U_z. \quad (26)$$

Let us especially highlight that expressions (18) and (19) do not include B_1 and B_2 since the components u' , v' and w' are the functions of $M(\eta)$ -derivatives only. Taking (12), (18), (19), (25), and (26) into account, we come to

$$u = U_z \left\{ 1 - \frac{\operatorname{erfc}(\sqrt{\operatorname{Re}/2}\eta)}{\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} - \frac{\eta [\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)]}{\sqrt{\pi \operatorname{Re}/2} (\xi^2 + \eta^2) \operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right\}, \quad (27)$$

$$w = U_z \left\{ l \left[1 - \frac{\operatorname{erfc}(\sqrt{\operatorname{Re}/2}\eta)}{\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right] + \frac{\xi [\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)]}{\sqrt{\pi \operatorname{Re}/2} (\xi^2 + \eta^2) \operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right\} \quad (28)$$

in 2D geometry and

$$u = U_z \left\{ 1 - \frac{E_1(\operatorname{Re}\eta^2/2)}{E_1(\operatorname{Re}/2)} - \frac{2 [\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)]}{\operatorname{Re} (\xi^2 + \eta^2) E_1(\operatorname{Re}/2)} \right\}, \quad (29)$$

$$v = U_z \left\{ n \left[1 - \frac{E_1(\operatorname{Re}\eta^2/2)}{E_1(\operatorname{Re}/2)} \right] + \frac{2\xi \sin \varphi [\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)]}{\operatorname{Re} (\xi^2 + \eta^2) \eta E_1(\operatorname{Re}/2)} \right\}, \quad (30)$$

$$w = U_z \left\{ l \left[1 - \frac{E_1(\operatorname{Re}\eta^2/2)}{E_1(\operatorname{Re}/2)} \right] + \frac{2\xi \cos \varphi [\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)]}{\operatorname{Re} (\xi^2 + \eta^2) \eta E_1(\operatorname{Re}/2)} \right\} \quad (31)$$

in 3D geometry. Note that

$$\operatorname{erfc}(q) = \frac{2}{\sqrt{\pi}} \int_q^\infty \exp(-\kappa^2) d\kappa, \quad E_1(q) = \int_q^\infty \frac{\exp(-\kappa)}{\kappa} d\kappa.$$

An important point is that this solution contains the previously studied case of symmetric flow: $n = l = 0$. Indeed, (27)-(31) lead to formulas (68) and (69)²¹ if $n = l = 0$.

Representing the velocity vector in component-wise form $\mathbf{u} = u\mathbf{e}_z + v\mathbf{e}_y + w\mathbf{e}_x = u_\xi\mathbf{e}_\xi + u_\eta\mathbf{e}_\eta + u_\varphi\mathbf{e}_\varphi$ and taking (2) and (6) into consideration, we arrive at

$$u_\xi = \frac{U_z(\xi + l\eta)}{\sqrt{\xi^2 + \eta^2}} \left(1 - \frac{\operatorname{erfc}(\sqrt{\operatorname{Re}/2}\eta)}{\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right), \quad (32)$$

$$u_\eta = \frac{U_z}{\sqrt{\xi^2 + \eta^2}} \left\{ (l\xi - \eta) \left[1 - \frac{\operatorname{erfc}(\sqrt{\operatorname{Re}/2}\eta)}{\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right] + \frac{\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)}{\sqrt{\pi\operatorname{Re}/2}\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right\} \quad (33)$$

in 2D geometry and

$$u_\xi = \frac{U_z(\xi + n\eta \sin \varphi + l\eta \cos \varphi)}{\sqrt{\xi^2 + \eta^2}} \left(1 - \frac{E_1(\operatorname{Re}\eta^2/2)}{E_1(\operatorname{Re}/2)} \right), \quad (34)$$

$$u_\eta = \frac{U_z}{\sqrt{\xi^2 + \eta^2}} \left[(n\xi \sin \varphi + l\xi \cos \varphi - \eta) \left(1 - \frac{E_1(\operatorname{Re}\eta^2/2)}{E_1(\operatorname{Re}/2)} \right) + \frac{2[\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta^2/2)]}{\operatorname{Re}\eta E_1(\operatorname{Re}/2)} \right], \quad (35)$$

$$u_\varphi = U_z(l \sin \varphi - n \cos \varphi) \left(1 - \frac{E_1(\operatorname{Re}\eta^2/2)}{E_1(\operatorname{Re}/2)} \right) \quad (36)$$

in 3D geometry. Let us again note that (32)-(36) are identical to (70)-(75)²¹ if $l = n = 0$.

2.4 | Hydrodynamic solutions in the reference frame of a moving crystal

For the convenience of mathematical modeling of crystal growth, a frame of reference is often used that moves with the dendrite. Let the origin of such a coordinate system coincides with the radius of curvature of the crystal tip. Also, we use below the modified coordinates accordingly to many previous studies^{16,23-28}

$$2D : z = \frac{\rho}{2}(\eta - \xi), \quad x = \rho\sqrt{\xi\eta}; \quad 3D : z = \frac{\rho}{2}(\eta - \xi), \quad y = \rho\sqrt{\xi\eta} \sin \varphi, \quad x = \rho\sqrt{\xi\eta} \cos \varphi. \quad (37)$$

Let us introduce the opposite coordinate axis z of the dendrite evolving with an unchangeable rate V . In this case, one can get

$$u_\xi = \frac{V\sqrt{\xi}}{\sqrt{\xi + \eta}} + \frac{U_z(\sqrt{\xi} + l\sqrt{\eta})}{\sqrt{\xi + \eta}} \left(1 - \frac{\operatorname{erfc}(\sqrt{\operatorname{Re}\eta/2})}{\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right), \quad (38)$$

$$u_\eta = -\frac{V\sqrt{\eta}}{\sqrt{\xi + \eta}} + \frac{U_z}{\sqrt{\xi + \eta}} \left\{ (l\sqrt{\xi} - \sqrt{\eta}) \left[1 - \frac{\operatorname{erfc}(\sqrt{\operatorname{Re}\eta/2})}{\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right] + \frac{\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta/2)}{\sqrt{\pi\operatorname{Re}/2}\operatorname{erfc}(\sqrt{\operatorname{Re}/2})} \right\} \quad (39)$$

in the 2D case, and

$$u_\xi = \frac{V\sqrt{\xi}}{\sqrt{\xi + \eta}} + \frac{U_z(\sqrt{\xi} + n\sqrt{\eta} \sin \varphi + l\sqrt{\eta} \cos \varphi)}{\sqrt{\xi + \eta}} \left(1 - \frac{E_1(\operatorname{Re}\eta/2)}{E_1(\operatorname{Re}/2)} \right), \quad (40)$$

$$u_\eta = -\frac{V\sqrt{\eta}}{\sqrt{\xi + \eta}} + \frac{U_z}{\sqrt{\xi + \eta}} \left[(n\sqrt{\xi} \sin \varphi + l\sqrt{\xi} \cos \varphi - \sqrt{\eta}) \left(1 - \frac{E_1(\operatorname{Re}\eta/2)}{E_1(\operatorname{Re}/2)} \right) + \frac{2[\exp(-\operatorname{Re}/2) - \exp(-\operatorname{Re}\eta/2)]}{\operatorname{Re}\sqrt{\eta}E_1(\operatorname{Re}/2)} \right], \quad (41)$$

$$u_\varphi = U_z(l \sin \varphi - n \cos \varphi) \left(1 - \frac{E_1(\operatorname{Re}\eta/2)}{E_1(\operatorname{Re}/2)} \right) \quad (42)$$

in the 3D case. It is significant that expressions (38)-(42) transform to the corresponding solutions in the case of a direct (with zero angle) liquid flow to the dendrite ($l = n = 0$).^{16,29}

3 | DISCUSSION AND CONCLUSION

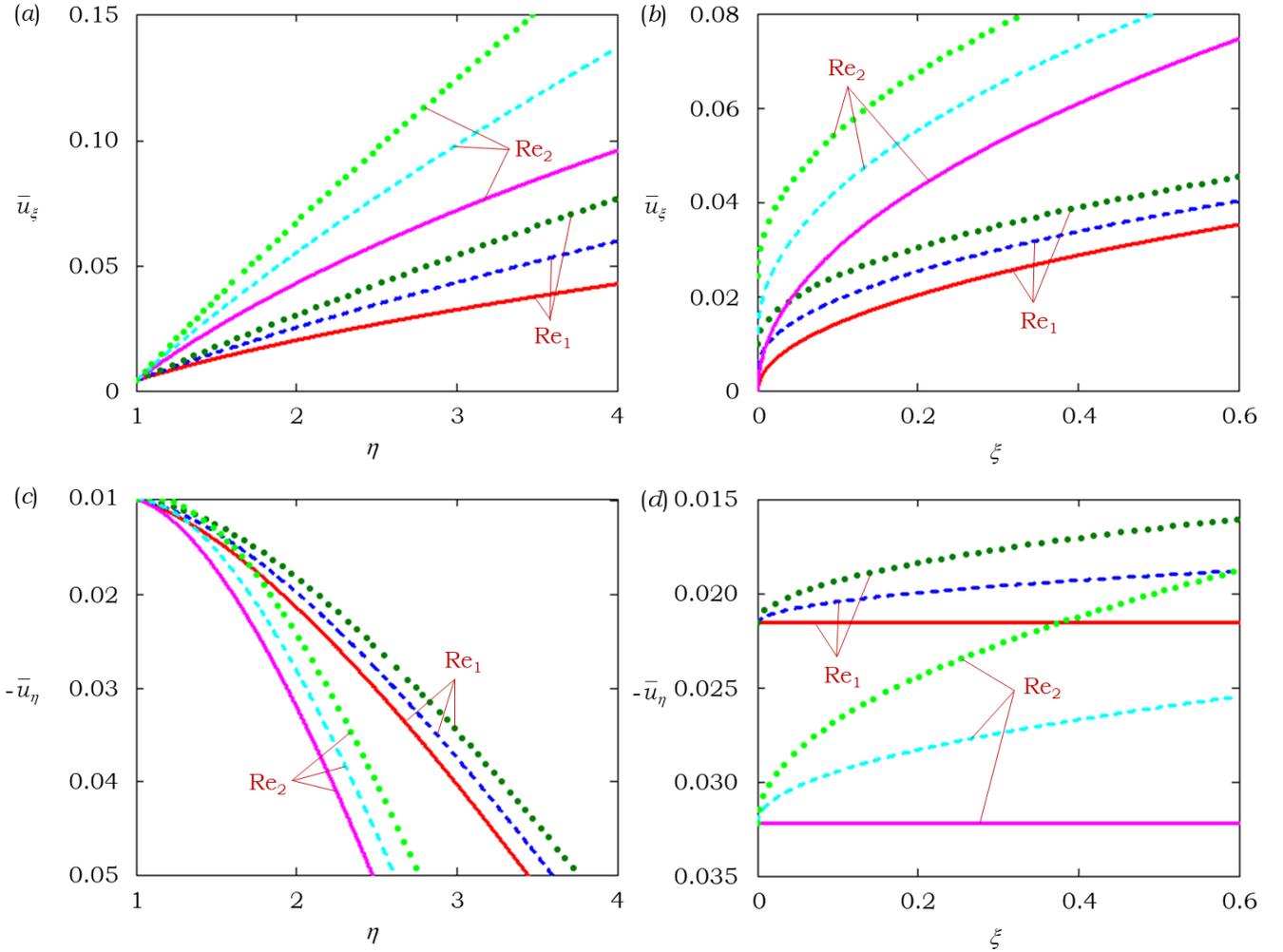


FIGURE 2 2D solutions. The modified velocities $\bar{u}_\xi = u_\xi \sqrt{\xi + \eta}/U_z$ (panels a, b) and $\bar{u}_\eta = u_\eta \sqrt{\xi + \eta}/U_z$ (panels c, d) versus the spatial variables η ($\xi = 0.2$) and ξ ($\eta = 2$) accordingly to solutions (38) and (39) in cases of $l = 0$ (solid curves), $l = 0.1$ (dashed curves), and $l = 0.2$ (dotted curves); $Re_1 = 0.01$, $Re_2 = 0.05$, and $V/U_z = 0.01$.

Figures 2 and 3 illustrate the role of hydrodynamic flow slope $l = U_x/U_z$ and Reynolds number $Re = U_z \rho/\nu$ on modified velocity projections $\bar{u}_\xi = u_\xi \sqrt{\xi + \eta}/U_z$ and $\bar{u}_\eta = u_\eta \sqrt{\xi + \eta}/U_z$ in accordance with analytical solutions (38)-(41). Our calculations demonstrate that both velocity projections change quite strongly with a slight change in the hydrodynamic slope. As this takes place, small variations in Reynolds number also have a significant effect on the distribution of the components of the hydrodynamic flow. Such significant changes in the distribution of the flow velocity must lead to a change in the temperature and concentration fields around the dendrite tip. This is caused by the corresponding changes in the convective terms in the equations of heat conduction and diffusion of impurities.

Another important circumstance is the asymmetry of the inclined flow relative to the dendrite axis. This, obviously, should lead to a change in the direction of its growth when the angle of inclination of the hydrodynamic flow changes. And this, in turn, entails a change in the main parameters of stable growth of the dendritic vertex - its diameter and velocity. Therefore, one of the directions of research development is to determine the criterion for stable dendritic growth in oblique hydrodynamic flows in the spirit of the previously constructed theory^{4,15,16,29} for flows with a zero inclination coefficient to the axis of dendritic growth. In

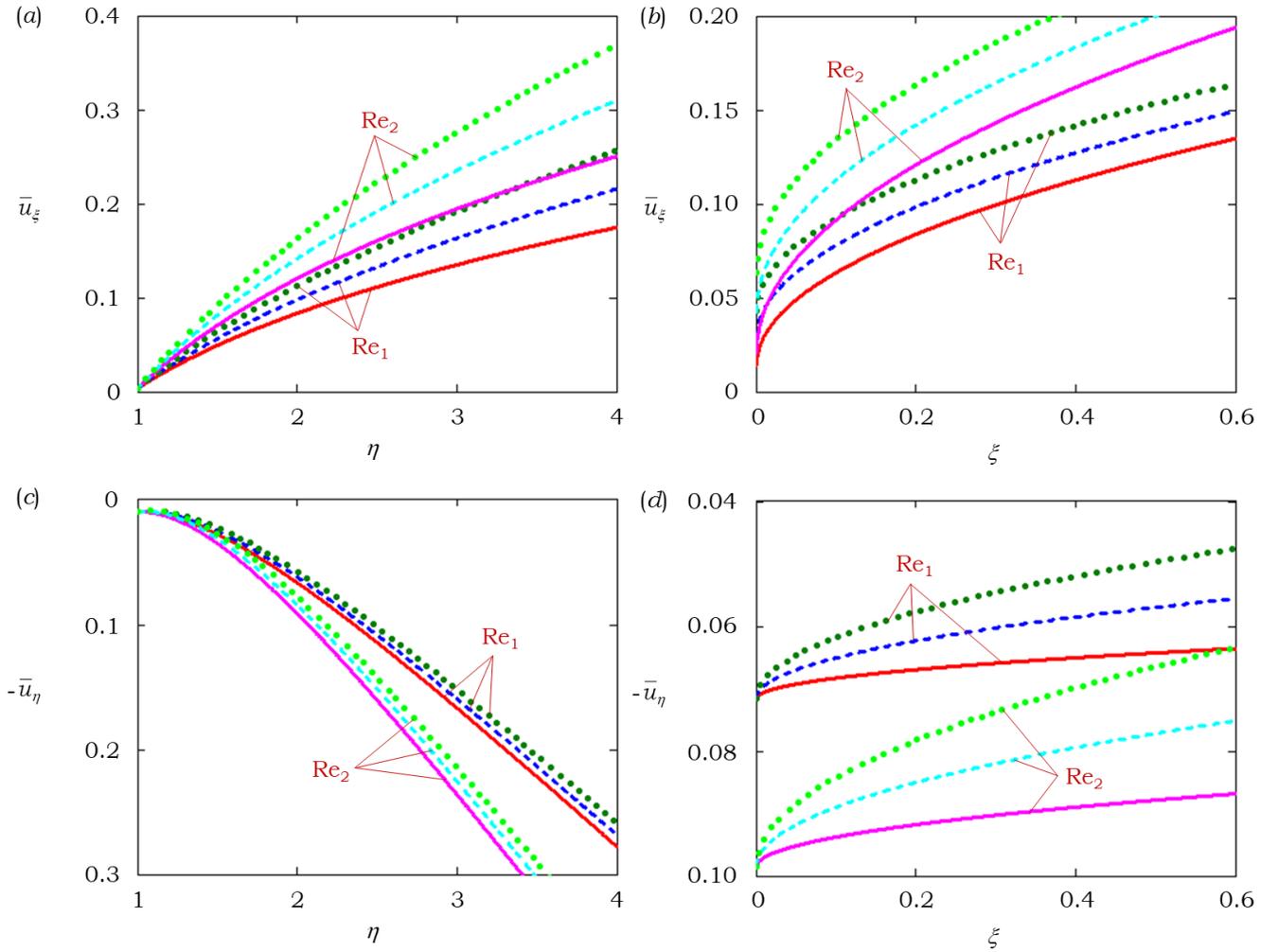


FIGURE 3 3D solutions. The modified velocities $\bar{u}_\xi = u_\xi \sqrt{\xi + \eta}/U_z$ (panels a, b) and $\bar{u}_\eta = u_\eta \sqrt{\xi + \eta}/U_z$ (panels c, d) versus the spatial variables η ($\xi = 0.2$) and ξ ($\eta = 2$) accordingly to solutions (40) and (41) in cases of $l = 0$ (solid curves), $l = 0.1$ (dashed curves), and $l = 0.2$ (dotted curves); $Re_1 = 0.01$, $Re_2 = 0.05$, $V/U_z = 0.01$, $n = 0.1$, and $\varphi = \pi/4$.

addition, oblique flows of supercooled melts and supersaturated solutions should lead to a more complex structure of secondary branches of dendritic crystals in the phase transformation region. In general, growth forms in such a two-phase region in the presence of inclined flows should differ significantly from the forming microstructure in the absence of a flow or the presence of a rectilinear (non-oblique) fluid flow. The development of the theory of phase transformation in such a two-phase zone is also an important direction of scientific research, which can be carried out by analogy with several existing theories.^{30–45}

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Author contributions

The authors contributed equally to the present research article.

Conflict of interest

The authors declare no potential conflict of interests.

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