

The interplay of rifting, magmatism and formation of geothermal resources in the Ethiopian Rift constrained by 3-D magnetotelluric imaging

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Abstract

The Main Ethiopian Rift (MER) is accompanied by extensive volcanism and the formation of geothermal systems, both having an imminent impact on lives of millions of local inhabitants. Although previous studies from the region found evidence that asthenospheric upwelling and associated decompression melting provide melt to magmatic mush systems that feed the tectono-volcanic segments in the rift valley, no geophysical model imaged these regional and local scale transcrustal structures within a single comprehensive 3-D model. To fill this gap, we combined regional and local magnetotelluric data sets to obtain the first multi-scale 3-D electrical conductivity model of the central MER. The model clearly images a magma ponding zone with up to 7 vol.% melt at the base of the crust in the western part of the rift, its connection to Aluto volcano via a tectonically controlled transcrustal magmatic mush system and how the melt, stored at shallow crustal depths, supplies heat for Aluto's geothermal system. Our model provides evidence that different volcano-tectonic lineaments in the rift valley share a common melt source, which has been debated in the past. The presented multi-scale model provides new constraints as well as geologic insights into the melt distribution below the rift and will facilitate future geothermal developments and volcanic hazard assessments in the MER.

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Plain Language Summary

Continental rifting is a fundamental process of plate tectonics that breaks continents apart to ultimately form new oceans. The landscape of the Main Ethiopian Rift (MER) is characterized by abundant volcanism and hot springs, which indicate presence of geothermal resources formed by magmatic heating of subsurface water. In our study we present a 3-D subsurface image of the magmatic system and geothermal reservoir beneath Aluto volcano in the MER. The model shows the electrical conductivity distribution of the subsurface which allows us to infer the distribution of electrically conductive melt. This is the first model that provides a high-resolution image of the entire magmatic system below the MER from the deep magmatic melt source up to the surface. The new model images for the first time how geothermal reservoirs form as a consequence of rifting related volcanic activity thereby providing a clear illustration of fundamental geological processes. These results also have a high societal relevance by providing a basis for volcanic risk assessment and contributing to a better understanding of how the sustainable green geothermal energy resources form.

1 Introduction

The East African Rift System (EARS) is a prominent continental rift that shaped the landscape of East Africa, including the East African Plateau, rift valleys and numerous volcanoes. Rifting and rift-related volcanism in East Africa played a role in early human evolution (King & Bailey, 2006) and to this date affect the life of humans due to volcanic hazards (Biggs et al., 2021), but also by providing diverse climate conditions and rift-associated natural resources (Burnside et al., 2021; Kebede et al., 2020). A large number of studies, especially in the northern part of the EARS, the Main Ethiopian Rift (MER), have provided a wealth of information and knowledge on the geodynamic processes that initiated and drive rifting and associated volcanism in the EARS (e.g. Agostini et al., 2011a; Casey et al., 2006; Corti, 2009; Ebinger, 2005; Kendall et al., 2005; Kendall & Lithgow-Bertelloni, 2016; Keranen & Klemperer, 2008, and references therein).

One of the main findings of these studies is that neither mechanical stretching nor magmatic upwelling could be the the major driver of rifting alone, but it is a rather complex interplay between these processes (e.g. Beutel et al., 2010; Kendall et al., 2005). Active magmatism and volcanism in the MER is sustained by asthenospheric upwelling. The main hypothesis is that decompression melting occurs in the upper mantle, melt intrudes into the lithosphere, where it feeds magmatic dykes and sills leading to the formation of volcanic systems in the MER (Gallacher et al., 2016; Rychert et al., 2012). Petrological studies and geological mapping (Bonini et al., 2005; Keranen & Klemperer, 2008) from the central part of the MER (CMER) observed a correlation between the monogenetic vent distribution and fault systems (Fig. 1), which implies that a tectono-magmatic interplay drives the rifting. Multiple studies proposed that a complex magmatic system exists below the western, mostly aseismic, Silti Debre Zeyit Fault Zone (SDFZ) (Iddon & Edmonds, 2020; Mazzarini et al., 2013; Rooney et al., 2011), where the magma stalls and fractionates at multiple depths within the crust. In contrast, the eastern Wonji Fault Belt (WFB) is seismically more active (Keir et al., 2006), hosting most of the present-day crustal extension with well-developed magmatic pathways (Bilham et al., 1999; Mazzarini et al., 2013; Rooney et al., 2011). Magma rises quickly under the WFB and fractionates at low pressures corresponding to about 5 km depth (Gleeson et al., 2017; Iddon & Edmonds, 2020; Rooney et al., 2011). Along the WFB, long-lived silicic peralkaline volcanoes are found with shallow magma chambers that have undergone several phases of eruption and recharge (Fontijn et al., 2018). Active

82 magmatism and extensional strain along the WFB created ideal geological conditions for
83 the formation of high-temperature geothermal resources (e.g. Jolie et al., 2021).

84 However, there is still a lack of geophysical subsurface models for the MER that would
85 constrain the 3-D distribution of melt and image magmatic pathways across the continental
86 crust. Such geophysical subsurface images are critical for understanding controls on magma
87 transport, magma emplacement under rift-aligned segments and the formation of numerous
88 magma-driven geothermal systems in the MER (e.g. Jolie et al., 2021; Kebede et al.,
89 2020). The mindful exploitation of these geothermal resources would be beneficial for the
90 local society (IRENA, 2020). As a source of clean and renewable baseload energy, these
91 geothermal resources can satisfy the growing energy demand and sustain the local economic
92 growth. Numerous countries along the EARS plan to expand exploitation of renewable
93 geothermal energy resources (IRENA, 2020). Ethiopia is currently aiming at installing
94 1000 MWe of its estimated 10,000 MWe geothermal energy potential (Burnside et al., 2021;
95 Kebede et al., 2020).

96 Our study focuses on the area of Ethiopia's only producing geothermal power plant,
97 Aluto-Langano. The power plant is in operation since 1998 and has an installed capacity of
98 7.3 MWe (Kebede et al., 2020). Expansion work to reach 75 MWe is underway, with four new
99 wells having been drilled in 2022 (capitalethiopia.com, 2022). Our primary goal here is to
100 investigate the magmatic heat source of Aluto's geothermal system and how it is connected
101 to deeper lower crustal magmatic system. To this end, we will use the magnetotelluric (MT)
102 method and image 3-D electrical conductivity structure of the subsurface.

103 Previous MT and seismic studies from this region have identified electrical conduc-
104 tivity and shear wave velocity anomalies in the lower crust under the SDFZ (Hübert et
105 al., 2018; Kim et al., 2012; Samrock et al., 2015). These lower crustal seismic anomalies
106 have been interpreted as the lithospheric melt ponding zone. However, the lateral extent
107 of this anomaly and potential links to Aluto's magmatic reservoir under the WFB remain
108 poorly constrained. Further, it remains unclear whether volcanoes along the WFB and the
109 SDFZ are related to a common melt ponding zone or whether their magmas originate from
110 separated parental melt sources (e.g. Fig. 11 in Mazzarini et al., 2013; Rooney et al., 2011).

111 To address these questions and better constrain the structure below Aluto, we analyzed
112 a new MT dataset that covers both the rift and the Aluto volcanic complex. Our goal is to
113 obtain a new multi-scale 3-D electrical conductivity model of this area in the CMER (Fig. 1)

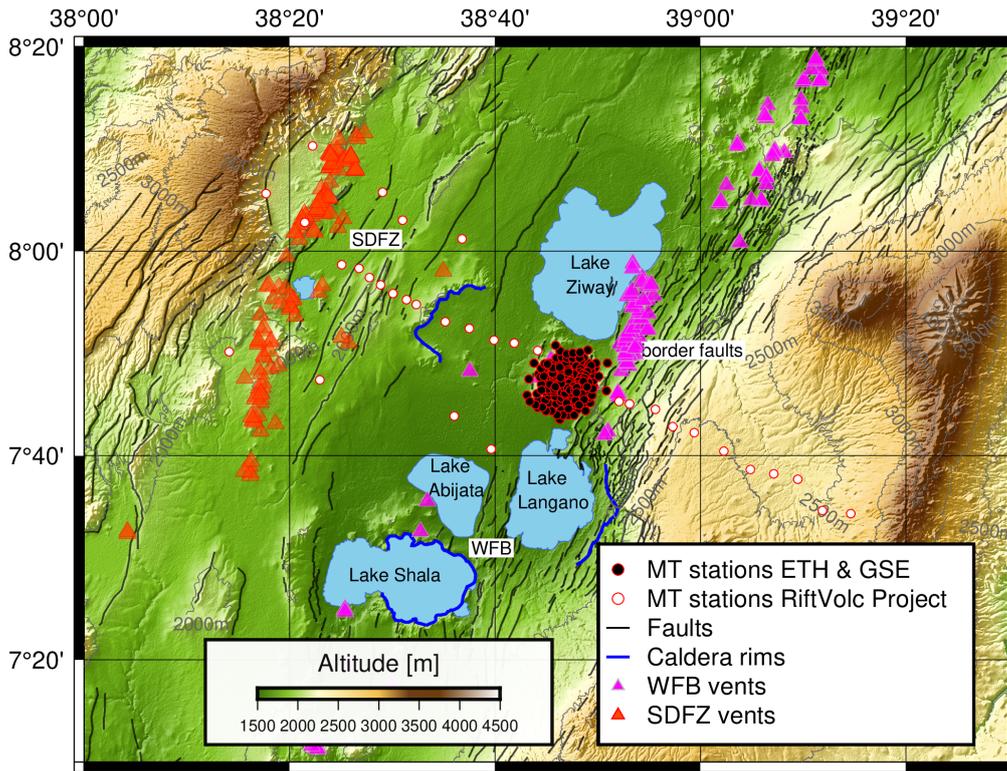


Figure 1. Study area in the Central Main Ethiopian Rift (CMER) with its faults systems (database of faults: Agostini et al., 2011b) and quaternary vents (grouped by Mazzarini & Isola, 2010). The vents belong to two different volcanic belts that are associated with the Wonji Fault Belt (WFB) and the Silti Debre Zeyit Fault Zone (SDFZ). Aluto volcano is located in the center of the study area in between the lakes Ziway and Langano. MT stations are coloured according to the institutions and projects that performed the measurement (MT-dataset by ETH Zurich (ETH) and Geological Survey of Ethiopia (GSE): Samrock et al. (2010) and MT-dataset by the RiftVolc Project: Hübert and Whaler (2020)). The survey area encompasses all fault systems of the CMER (WFB, SDFZ and border faults) and crosses the Gademotta caldera rim west of Aluto. The maximum difference in altitude along the profile is ≈ 1000 m.

114 and resolve both regional-scale structures in the lower crust and local structures related to
 115 Aluto's upper crustal magmatic and geothermal reservoirs.

116 2 Method and Data

117 To image the melt distribution across the rift and constrain the structures of Aluto's
 118 magmatic and geothermal reservoirs, we obtain the subsurface 3-D electrical conductivity
 119 distribution employing the (passive) magnetotelluric method (MT) (e.g. Cagniard, 1953).
 120 Broadband MT responses are sensitive to electrical conductivity structures across a wide

121 range of scales, providing a unique opportunity to study the subsurface from the surface
 122 down to the upper mantle. More details on the MT method are provided in the SI (Text S1).

123 2.1 Data

124 We combine data from regional and local MT surveys in the MER, as is shown in
 125 Fig. 1. The regional dataset, collected within the RiftVolc Project (Hübert & Whaler, 2020),
 126 consists of 33 MT stations that are distributed across the rift over a distance of 120 km with
 127 average site spacings between 4 km and 13 km (SI: Tab. S1). These regional-scale MT survey
 128 was supplemented by a local dataset of ETH and GSE (Samrock et al., 2010), consisting
 129 of 165 sites that cover the edifice of the Aluto volcano (15×15 km), with an average site
 130 spacing of 0.7 km. The MT transfer functions cover a period range of $T = 10^{-2} - 10^3$ s. For
 131 this period range and for the averaged electrical conductivity distribution in the study area,
 132 the penetration depth is calculated to range between 0.5 and 92.5 km, thereby providing a
 133 sufficient range for imaging both near-surface and crustal structures (SI: Fig. S2). Detailed
 134 information on the surveys and the collected MT data is provided in the SI (Text S2).

135 2.2 3-D Inversion

136 We used the GoFEM code to perform 3-D forward modelling and inversion (Arndt
 137 et al., 2020; Grayver, 2015; Grayver & Kolev, 2015). GoFEM uses locally refined meshes
 138 to facilitate multi-scale model parameterization (SI: Text S4) and accurately incorporate
 139 topography. The code was already used in earlier local-scale MT studies at Aluto (Samrock
 140 et al., 2020) and for multi-scale MT studies of volcanically active regions in Mongolia (Käuff
 141 et al., 2020).

142 Since impedance tensors are often affected by galvanic distortions, we first perform
 143 a phase tensor inversion. As the starting model for the phase tensor inversion, we used a
 144 homogeneous model with a resistivity of $\bar{\rho}_{a,ssq}^{1D} = 19.25 \Omega\text{m}$, where $\bar{\rho}_{a,ssq}^{1D}$ is the geometric
 145 mean of all observed apparent resistivities calculated from Z_{ssq} (SI: Eq. 6-11, see also Rung-
 146 Arunwan et al., 2016).

147 Although phase tensors are free of galvanic distortions (e.g. Caldwell et al., 2004),
 148 absolute values of electrical conductivity in models constrained solely by phase tensor data
 149 might be less constrained, especially when survey layout is sparse (Tietze et al., 2015). To
 150 mitigate this limitation, we ran the impedance tensor inversion and used the best-fitting

151 3-D phase tensor model as a starting model. By doing so, the impedance tensor inversion
 152 is guided by the distortion-free phase tensor model and the negative impact of galvanic
 153 distortions on the inversion is reduced. If there were no distortions and both phase and
 154 impedance tensors contained the same information, we would expect the models to be
 155 identical. In reality, the models exhibit some differences, mostly because the impedance
 156 tensor inversion need to compensate for galvanic distortions by introducing some scattered
 157 conductivity structures at shallow depths (Fig. 2 Samrock et al., 2018) (SI: Fig. S13).

158 Technical information on the inversion methodology and the achieved data fit for the
 159 final phase and impedance tensor models is provided in the SI (Text S3 and S4). In what
 160 follows, we will present the final impedance tensor model. The corresponding phase tensor
 161 model is shown for completeness in the SI (Text S4.1).

162 **3 Results**

163 Both models, obtained from phase and impedance tensor inversions, fit the observed
 164 data within the uncertainty ($\text{RMS} \leq 1$), given by the error-floor of 5 % applied row-wise to the
 165 impedance tensor and propagated to the phase tensor (as in Käufel et al., 2018). Details about
 166 the inversion progress and the achieved fit are provided in Fig. 2. Starting at an initial RMS
 167 of 2.7, the phase tensor inversion converges to an RMS of 0.83 within four iterations. For
 168 the subsequent impedance tensor inversion a relatively low model regularization is chosen,
 169 as the large-scale structure is given by the phase tensor model, which is used as the starting
 170 model for the impedance tensor inversion. Starting at an initial RMS of 5.1, the impedance
 171 tensor inversion converges progressively until a final RMS of 0.81 is achieved (Fig. 2a). The
 172 RMS distribution as a function of the period shows that shorter periods tend to yield lower
 173 misfits than longer periods (Fig. 2b), which can be due to lower data quality at longer
 174 periods. The normalized residuals of both obtained final models are uniformly distributed
 175 and centered around zero, indicating that no systematic bias is present (Fig. 2c). More
 176 detailed information about the model fit is provided in the SI (Text S5.2).

177 **3.1 Final model**

178 A cross-section through the final electrical conductivity model is shown in Fig. 3 a. An
 179 approximately NW-SE-oriented vertical slice crosses the entire rift and traverses the center

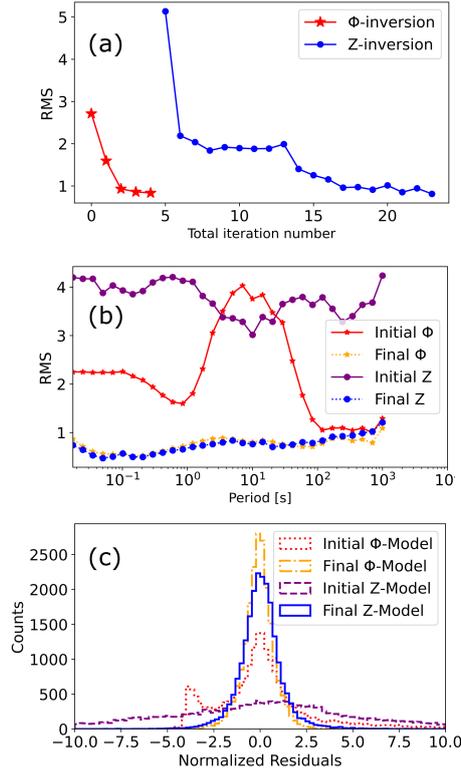


Figure 2. (a) RMS misfit during the phase tensor and the subsequent impedance tensor inversions. (b) RMS misfit versus period for the initial and final phase and impedance tensor inversion runs. (c) Residual distribution of initial and final phase tensor and impedance tensor models. Note that the final phase tensor model is used as a starting model for the impedance tensor inversion.

180 of Aluto volcano. Main electrical conductors (C) in the obtained multi-scale model are
 181 described in the following.

182 The largest conductivity anomaly in the model is the C3 conductor. The maximum
 183 recovered electrical conductivity within C3 is $\sigma = 0.18 \text{ S/m}$ (Fig. 3 a). The anomaly occupies
 184 a large volume in the lower crust under the western part of the rift and crosses the Moho
 185 boundary at depths of $z \approx 30 - 35 \text{ km b.s.l.}$ (Fig. 5). The lateral extent of C3 is about 50 km
 186 across the rift and 30 km along the rift, considering the 0.1 S/m isosurface (we note that
 187 data coverage along the rift axis is limited). It is evident that no high conductivity zone is
 188 found under the eastern part of the rift. C3 ends abruptly around the central rift axis and
 189 transitions into a continuously upward propagating channel denoted C2. The C2 structure
 190 is characterized by increased bulk electrical conductivities of $\sigma = 1.8 \text{ S/m}$ at depths of
 191 $z = 6 - 18 \text{ km b.s.l.}$. This channel terminates at a depth of $z = 4 \text{ km, b.s.l.}$ right below the
 192 Aluto volcano (Fig. 3 b). At shallower depths (down to about $z \approx 1.5 \text{ km}$ below surface), we

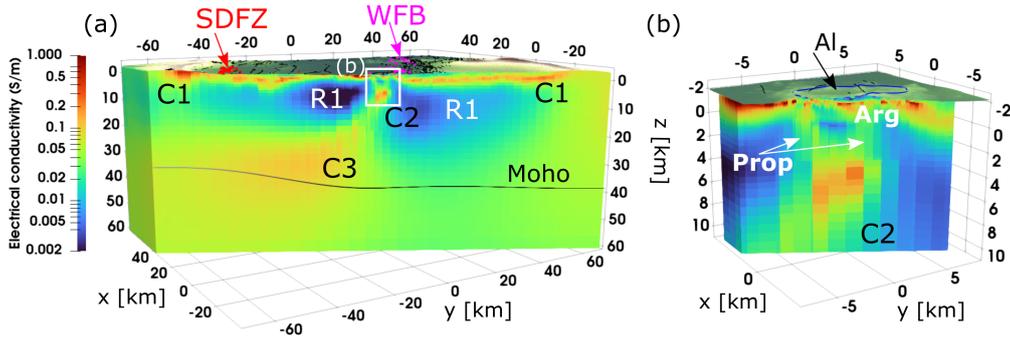


Figure 3. Final 3-D electrical conductivity model. (a) NW-SE oriented cross-section, covering the entire width of the CMER. The Moho boundary (black solid line) is taken from (Stuart et al., 2006). Pink and red triangles depict WFB and SDFZ vents, respectively (see also Fig. 1). Recovered structures are interpreted to be: (C1) Aquifer/sediment unit, (C2) magma ascent channel, (R1) solidified igneous rock and (C3) lower crustal melt ponding zone. The white box marks the area of the Aluto-Langano geothermal system (b). (b) Enlarged excerpt of the Aluto volcano (proposed caldera rim in blue). Increased conductivities in the shallow subsurface can be attributed to a clay cap, formed by argillic alteration (Arg) and higher-temperature propylitic alteration (Prop).

193 recover an electrically conductive layer (C1) that extends across the entire width of the rift,
 194 with bulk conductivity values of $\sigma = 0.1 - 0.5 \text{ S/m}$. This continuous layer (C1) is interrupted
 195 only under the edifice of Aluto volcano in the center of the shown cross-section (Fig. 3).

196 A large low-conductivity zone (R1) extends across the valley, with $\sigma \leq 0.01 \text{ S/m}$. R1
 197 is situated in the crust below the continuous conductive layer (C1) and is pierced by the
 198 conductive channel C2.

199 3.2 Interpretation

200 The presented electrical conductivity model is the first 3-D model of the CMER that
 201 images the transcrustal distribution of magma in sufficient detail to interpret it across scales
 202 from the lower crust to the surface. In what follows, we provide a geological interpretation of
 203 our 3-D electrical conductivity model (Figs. 3 and 5) taking in consideration earlier studies.

204 3.2.1 C3: Lower crustal magma ponding zone

205 We interpret this high conductivity anomaly to be caused by the presence of electrically
 206 conductive basaltic melt. Hence, C3 represents a zone of melt ponding at the base of

207 the crust. A quantitative melt fraction estimate within the C3 is given in Section 3.2.2.
208 The interpretation of C3 as a lower crustal melt ponding zone is supported by seismic
209 observations, geodynamic modelling studies and petrological models for melt evolution and
210 transport in the MER. In the following these studies are presented in more detail.

211 Analysis of seismic S to- P receiver functions provides evidence for a thinned lithosphere
212 and upwelling asthenosphere below the rift valley (Rychert et al., 2012). A pronounced low
213 seismic velocity anomaly is observed in the upwelling asthenosphere, which can only be
214 explained by presence of melt that originates from decompression melting (e.g. Chambers
215 et al., 2022; Kim et al., 2012; Rychert et al., 2012). It has been shown that the Moho
216 deepens from West to East in this area (Fig. 3), indicating that asthenospheric upwelling is
217 slightly asymmetric to the rift axis and more pronounced under the western part of the rift
218 (e.g. Keranen & Klemperer, 2008; Stuart et al., 2006). Geodynamic modelling by (Rychert
219 et al., 2012) shows that melt generated through decompression melting experiences strong
220 buoyancy forces causing it to migrate into the lower crust, where it accumulates in a melt
221 ponding zone above the Moho. The C3 structure in our model is spatially coherent with an
222 identified low shear wave velocity anomaly, that has been interpreted as such a melt ponding
223 reservoir (e.g. Chambers et al., 2022; Kim et al., 2012).

224 The observation that melt is asymmetrically distributed across the rift has also been
225 made by a regional MT study, approximately 110 km north of our study area (Whaler &
226 Hautot, 2006). There, authors report high electrical conductivities west of the rift-axis at a
227 depth of about 25 km.

228 That the lower crustal melt emplacement and asthenospheric upwelling occur asym-
229 metric with respect to the rift axis is not surprising. The tectonic analogue modelling has
230 suggested that the distribution of melt in the crust is guided by en-échelon structures, such
231 as the SDFZ and the WFB volcano-tectonic segments (Corti, 2009, and references therein).
232 However, it is interesting that lower crustal melt ponding is restricted to the area under
233 the SDFZ en-échelon segment, whereas no melt is ponding in the lower crust under the
234 WFB en-échelon segment, which is a much more active region in terms of volcano-tectonic
235 activity (e.g. Mazzarini et al., 2013). We suggest that the focusing of magma to the west
236 is likely caused by an "inherited" structure from the early rifting stage. In general, magma
237 emplacement during early stages of rifting could be dominated by a lateral squeezing of the
238 melt from the rift axis towards the border faults, as demonstrated by analogue modelling

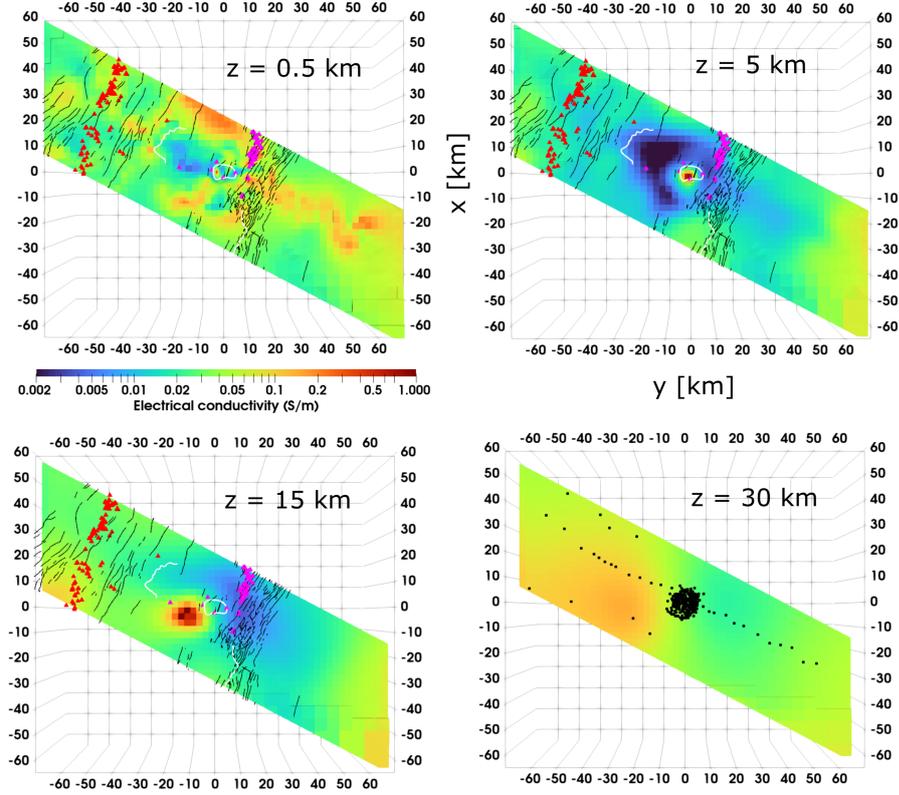


Figure 4. Horizontal slices at several depths from $z = 0.5 - 30$ km b.s.l. through the final impedance tensor model. It is evident from the figure that maximum electrical conductivities occur locally confined to the WSW of Aluto. Pink and red triangles depict WFB and SDFZ vents, respectively, black lines are faults and white lines are the western Gademotta caldera rim and the proposed Aluto caldera rim. Black dots on the 30 km b.s.l. depth slice indicate MT site locations.

239 studies (see Fig. 29 in Corti et al., 2003). Because rift development was asymmetric (e.g.
 240 Ebinger, 2005), with master border faults at the western side (e.g. in Corti et al., 2018,
 241 Fig. 2, profile 3), it is likely that the melt was favourably squeezed towards the western
 242 border faults, ultimately leading to the presently observed western asymmetric melt distri-
 243 bution. Hence, the observed asymmetric melt distribution is plausible, even though major
 244 present-day volcano-tectonic structures are found to the east of the rift axis.

245 Further, our electrical conductivity model suggests that the melt is not distributed
 246 uniformly along the imaged en-échelon segment of the SDFZ, rather the melt is focused
 247 in a region spatially confined to the WSW of Aluto (Fig. 4, Fig. 5). To the best of our
 248 knowledge, such detailed variations of along-rift melt distributions have not been resolved

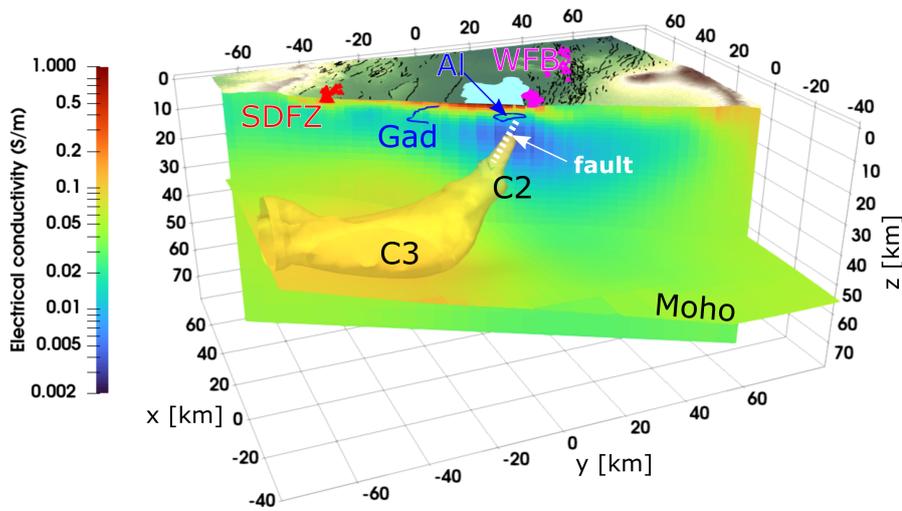


Figure 5. Vertical slice through the final model, approximately along the northern profile line of the MT sites (see Fig. 1). The Moho, as in Fig. 3, is colored by the electrical conductivities at the corresponding depth. The $\sigma = 0.1$ S/m-isosurface illustrates the extent of the magmatic ascent channel (C2) and the lower crustal melt ponding zone (C3). The magma ascent channel (C2) is situated exactly beneath Aluto and follows the dip angle of the WFB faults (65° ; Corti (2009)). The dipping of faults intersecting Aluto is indicated as a dashed white line. The melt ponding zone (C3) is confined to the area west of the rift-axis and WSW of Aluto volcano. Its lower bound roughly coincides with the Moho. Vents at the WFB and SDFZ are represented as red and pink triangles, respectively. The Gademotta (Gad) caldera rim is shown as a blue line, faults as black lines.

249 in the existing regional seismic models (e.g. Chambers et al., 2022; Kim et al., 2012). Our
 250 model indicates that lower crustal melt emplacement occurs much more punctuated and
 251 locally than previous geophysical models have shown and than tectonic analogue models
 252 have suggested (Corti, 2009, and references therein).

253 *3.2.2 Melt fraction estimates*

254 The model obtained from this study allows us to use electrical conductivity as an in-
 255 dependent constraint to quantify the amount of basaltic melt present in the lower crust.
 256 Until now, such estimates in the CMER relied mainly on seismic studies, of which some are
 257 summarized in the SI (Tab.S2). Adding electrical conductivity as an additional constraint
 258 reduces uncertainty of melt estimates and adds previously lacking knowledge on the spatial
 259 extent of the melt reservoir. To estimate the melt content, we used the experiment-calibrated
 260 model by Ni et al. (2011) (SI: Text S6), which parameterizes the electrical conductivity of

261 basaltic melt in terms of temperature and dissolved water content. The estimated tem-
 262 perature range for the primary basaltic melt within our interpreted source region (C3) is
 263 $\mathcal{T} = 1300 - 1400$ °C (SI: Tab. S2). Thermodynamic modelling of melt evolution constrains
 264 the dissolved water content within the parental basaltic melt of samples erupted at Aluto
 265 (Gleeson et al., 2017) to $c_{H_2O}^{melt} \leq 1$ wt%. This amount is well below the maximum wa-
 266 ter solubility of $\max(c_{H_2O}^{melt}) = 6.7$ wt% for identical magma storage conditions, which we
 267 calculated using MagmaSat by Ghiorso and Gualda (2015).

268 Under the relevant conditions (see SI: Tab. S2), the electrical conductivity of a basaltic
 269 melt is approximately $\sigma_{melt} = 2.9 - 8.4$ S/m (SI: Fig. S15). Based on the basaltic melt
 270 conductivity and the observed range of $\sigma_{bulk} = 0.1 - 0.18$ S/m in the magma ponding
 271 zone (C3), we calculate the melt fraction, using a modified Archie’s law (SI: Eq. 17 Glover,
 272 2015). The melt fraction is estimated for high melt-connectivities, reflected by a cementation
 273 exponent of $m = 1.15$, corresponding to the upper Hashin-Shtrikman bound, and lower
 274 connectivities, reflected by $m = 1.5$, which correspond to interstitial melt storage in a
 275 matrix of closely packed, perfect spheres (e.g. Glover, 2015). With these constraints, the
 276 melt fraction within the C3 conductor is 1.8–7.1 vol.% and 4.5–14.7 vol.% for maximum and
 277 minimum basaltic melt conductivities, respectively. Seismic studies estimated 2–7 vol.% of
 278 vertically aligned melt, based on modelling seismic velocities and seismic anisotropies in the
 279 uppermost mantle (Hammond & Kendall, 2016, SI: Tab. S2), fitting well into the range of
 280 our estimates. However, given the estimates from seismic studies, our maximum estimated
 281 melt fraction of 14.7 vol.% appears rather high. Taking into account that a melt fraction
 282 of 14.7 vol.% would be even higher than what has been estimated from a MT study in the
 283 Afar region (Desissa et al., 2013, SI: Tab. S2), where rifting is far more advanced and thus
 284 higher melt fractions are expected (e.g. Keranen & Klemperer, 2008). We consider our
 285 maximum estimate of 14.7 vol.%, and the underlying connectivity model, to be unrealistic,
 286 suggesting that higher temperatures, higher water contents and better melt connectivities
 287 are the conditions that better describe the in situ setting. In this case, our maximum
 288 estimated melt fraction is 7 vol.%. These estimated melt fractions are in agreement with
 289 independent estimates that are based on seismic velocities (see SI: Tab. S2) and support the
 290 interpretation of the C3 conductor to be a lower crustal magma ponding zone.

291 **3.2.3 C2: Transcrustal magma ascent channel**

292 We interpret the upward rising conductor C2 to be the magma ascent channel in
293 which melt migrates from the deeper melt ponding zone (C3) to the shallow magmatic
294 system beneath Aluto (Fig. 4, 5). The enhanced conductivity within C2 requires that melt
295 is present in the channel up to shallow depths of about 3 km b.s.l.. Hence, the upper part
296 of C2 also represents the magmatic heat source of Aluto's geothermal reservoir (Fig. 3 b).
297 The interpretation of C2 as a mature magmatic ascent channel is supported by petrological
298 studies, which predict that magma under the WFB rises quickly towards the surface, where
299 it either stalls and fractionates to eventually erupt as rhyolite, or the melt erupts quickly
300 as basalt (Mazzarini et al., 2013; Rooney et al., 2011). Another evidence for melt fractions
301 within C2 beneath Aluto is the observed aseismic zone in roughly the same area that was
302 interpreted as hot ductile crust (Wilks et al., 2020). The shallower part of channel C2 has
303 already been described by Samrock et al. (2020, 2021), who noted that the dip of the channel
304 ($\sim 65^\circ$) is coherent with the dominant fault plane of faults intersecting Aluto volcano. A
305 strong link between magmatic pathways and tectonically weak zones has been described by
306 numerous studies investigating magma-assisted continental rifting (e.g. Casey et al., 2006).
307 The close coupling between active tectonic structures and magma pathways in the central
308 MER is directly observable from the distribution of vents (Fig. 1), which shows that magma
309 preferentially rises along fault zones, where the crust has been weakened (e.g. Mazzarini et
310 al., 2013). The spatial conjunction of tectonic and magmatic features furthermore supports
311 the concept of "self-sustained" magmatic segments, where strain is preferentially localized
312 in magmatic segments, which promote intrusions (Beutel et al., 2010).

313 **3.2.4 R1: Solidified igneous rock**

314 The most striking feature of this electrical resistor is that it is clearly bounded to
315 the west by the Gademotta caldera rim (Fig. 4). The spatial correlation between R1 and
316 the Caldera rim leads us to the most plausible interpretation that R1 constitutes cooled
317 intrusive rock, as has already been previously suggested (Hübert et al., 2018; Samrock et
318 al., 2020). Its formation is likely related to the formation of the Gademotta caldera, where
319 volcanism ceased 1 Ma ago (Hutchison et al., 2016b).

3.2.5 C1: Aquifer/sediment unit

In agreement with the conceptual hydrogeological model of the study area by Ghiglieri et al. (2020), the conductor C1 images a shallow layer of pyroclastics and lavas that has been classified as a fissured aquifer. Considering reported groundwater electrical conductivities in the area (Burnside et al., 2021), the most widely distributed observed bulk conductivities within C1 ($\sigma = 0.1 - 0.2 \text{ S/m}$) would require an unreasonably large fluid fraction within C1 (see SI: Text S6.2). It is thus likely that enhanced conductivities in C1 are attributed to a superposition of ionic conduction in porous rocks and sediments as well as electrical conduction through conductive compounds such as clays, which also form through rock weathering processes and are commonly found in soils around the study area (Fritzsche et al., 2007).

3.2.6 Geothermal system

The shallow cap-like conductor ($\sigma = 0.1 - 0.3 \text{ S/m}$), shown in Fig. 3 b under Aluto volcano down to depths of 1.5 km below surface, and the underlying zone of decreased electrical conductivities ($\sigma = 0.02 \text{ S/m}$) between the cap and the upper part of the magma ascent channel C2 are typical features of volcano-hosted, high-temperature geothermal systems. The electrically conductive cap represents the argillic alteration zone, where electrically conductive clays are formed along the flow paths of circulating hot fluids on top of the convective hydrothermal reservoir, at temperatures of $\mathcal{T} \approx 80 - 180 \text{ }^\circ\text{C}$ (e.g. Kristmannsdottir, 1979; Lévy et al., 2018). An electrically more resistive region under the clay cap represents the propylitic alteration zone, where less electrically conductive alteration minerals form at higher temperatures of $\mathcal{T} > 250 \text{ }^\circ\text{C}$. The C2 structure is the heat source that drives hydrothermal convection (Fig. 3 b). A more detailed description of the geothermal system can be found in previous local MT studies of the Aluto-Langano geothermal field (Cherkose & Mizunaga, 2018; Samrock et al., 2015, 2020).

3.3 Discussion

The electrical conductivity structure, revealed by our 3-D multi-scale model, is in agreement with the concept and models of magma-assisted continental rifting. A unique feature of our new 3-D model is that it images both the distribution of melt throughout the crust and the geothermal system. Based on this model and previous studies, we present an updated conceptual model of the central MER in Fig. 6.

366 magma migrates upwards along zones of crustal weaknesses to shallower crustal levels (C2),
367 where melt is stored in a smaller upper crustal reservoir (Fig. 3 b), which represents only the
368 small, uppermost part of a much larger magmatic system (Cashman et al., 2017). Hence
369 the WFB and the magma ascent channel (C2) form a well-developed tectono-magmatic sys-
370 tem that allows melt to rise quickly (e.g. Mazzarini et al., 2013; Rooney et al., 2011). In
371 contrast to the crustal structure below the WFB, our model does not show enhanced upper
372 crustal conductivities below the monogenetic vents in the western SDFZ region (Figs. 3,5).
373 Such anomalies could have been expected since C3 is the most obvious source of magma for
374 magmatic vents in the SDFZ. The absence of a significant electrical conductivity anomaly
375 under the SDFZ can be explained by the fact that ancient magma channels of the mono-
376 genetic vents are ephemeral and cooled quickly. If small amounts of melt are still present,
377 melt is probably stored in form of a highly crystalline and poorly interconnected mush and
378 is therefore more difficult to image, given the rather sparse distribution of MT stations in
379 this region. This is supported by petrological studies, which suggest that melt rises in a
380 complex dike system and is stored at multiple levels under the the SDFZ, where it cools
381 (e.g. Mazzarini et al., 2013; Rooney et al., 2011). The absence of significant amounts of melt
382 in the upper crust under SDFZ is also in agreement with the observed low seismic activity
383 beneath this area (Keir et al., 2006), which hints at much fewer or no ongoing intrusions in
384 that region. However, we note again that the 5 – 10 km site spacing in that area is much
385 larger than at Aluto and smaller-scale variations under the SDFZ might remain undetected
386 in our model. Despite the absence of significant conductivity anomalies in the upper crust
387 under the SDFZ, it is important to point out that volcanic activity in the SDFZ most likely
388 originates from the imaged deeper magmatic ponding zone (C3). Thus, our model suggests
389 that magmas, erupted at the SDFZ and at Aluto within the WFB, may come from a com-
390 mon magma source, which would be the lower crustal magma ponding zone (C3) in our
391 nomenclature. Although some geochemical studies have suggested spatially separated lower
392 crustal melt ponding zones for the volcanoes located along the fault zones of the SDFZ
393 and the WFB (e.g. Rooney et al., 2011), recent studies show that compositional variations
394 can be explained solely by different rates of magma ascent rather than by the existence of
395 distinct melt reservoirs (Nicotra et al., 2021).

396 Our current 3-D model differs in parts from the 2-D model by Hübert et al. (2018),
397 who performed a 2-D inversion of the 120 km long MT profile crossing Aluto (Fig. 1, see
398 SI: Tab. 1). (Hübert et al., 2018) imaged a strong conductivity anomaly below the SDFZ,

399 situated at much shallower depths than the lower magma ponding zone (C3) in our model.
400 Furthermore, the 2-D model of (Hübert et al., 2018) did not image a magma ascent channel
401 between the deeper source and the Aluto volcano. There can be several reasons for the
402 observed differences between the models. First, a large portion of the data exhibit 3-D
403 effects (see SI: Fig. S5) and, indeed, we observe significant conductivity variations along
404 the rift (Fig. 4), which demand and justify a 3-D modelling approach. Additionally, the
405 density of MT sites in our new study is significantly higher around Aluto, which can further
406 contribute to the observed differences.

407 **4 Conclusions and Outlook**

408 Our model provides a 3-D subsurface image of the Aluto volcano region in the MER and
409 reveals regional geological structures across the rift and a local geothermal system under
410 Aluto. The main contributions of this study concern the understanding of the magma-
411 assisted rifting of the MER and its geothermal systems, namely: (i) imaging the lower
412 crustal magmatic ponding zone with MT and thereby adding another geophysical constraint
413 (electrical conductivity) to its characterization and (ii) imaging, for the first time, the entire
414 volcano-hydrothermal system under Aluto, along with its connection to the deep-seated
415 lower crustal magma source.

416 The number of geophysical models imaging transcrustal magmatic mush systems at
417 this scale (e.g. Cashman et al., 2017) is still limited (e.g. Comeau et al., 2015; Hill et
418 al., 2022; Huang et al., 2015), especially when the setting of actively evolving continental
419 rifts is considered. Our detailed study provides previously missing geophysical evidence for
420 the hypothesized (e.g. Ebinger, 2005; Rooney et al., 2011) conceptual model of the CMER
421 (Fig. 6).

422 These observations, and the subsequent geological interpretation, were enabled by
423 combining regional and local MT datasets and by using a modern multi-scale magnetotelluric
424 imaging approach. Future regional-scale MT studies along the rift valley are required to
425 provide further insights into along-rift variations of the lower crustal magma ponding zone
426 (C3) and its connection to the volcanic geothermal centers of Tulu Moye and Corbetti,
427 where high-resolution MT surveys, comparable to Aluto, have been conducted (Gíslason et
428 al., 2015; Samrock et al., 2018).

Data availability

The MT data collected at Aluto by ETH Zurich are available from Samrock et al. (2010) via the IRIS EMTF Database: <http://ds.iris.edu/spud/emtf> under the Project entry "Ethiopia", and the survey name "Aluto-Langano Geothermal". The MT-dataset by project RiftVolc is available from Hübert and Whaler (2020) by DOI: 10.5285/2fb02ed4-5f50-4c14-aeec-27ee13aafc38. The MT data by the Geological Survey of Ethiopia are available for academic purposes on request from the Geological Survey of Ethiopia, as was the case for this study. The model will be made available for download in the ETH research collection (www.research-collection.ethz.ch) under Dambly et al. (2022) (DOI: 10.3929/ethz-b-000576313) in form of a Visualization Toolkit (VTK) data file for ParaView.

Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

CReDit Authorship statement

M.L.T.D. performed modelling and inversion of the magnetotelluric data, model visualization and developed numerical tools. F.S. contributed to the 3-D modelling and inversion of the data and model visualization. A.G. developed the GoFEM code and contributed to the 3-D modelling and inversion of the data. All authors interpreted the results and contributed to the writing and review of the paper.

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Supporting Information for

The interplay of rifting, magmatism and formation of geothermal resources in the Ethiopian Rift constrained by 3-D magnetotelluric imaging

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Introduction The supplementary information includes basic equations explaining the MT method (Text S1.); information on the MT dataset and how apparent resistivities of the starting model were obtained from SSQ-impedances (Text S2.); details on the mesh used for inversion and forward modelling (Text S3.); a comparison of the best fitting phase tensor and impedance tensor models (Text S4.1); an in-depth analysis of the data fit for the final impedance and phase tensor model (Text S4.2. and S4.3.); and details about the melt fraction estimation in the lower crustal magma ponding zone (Text S5.1.) and of electrical conductivities in the shallow aquifer/sediment unit (C1) (Text S5.2.).

Text S1. In the magnetotelluric (MT) method, the natural variations of the electric and magnetic field are measured on the Earth's surface. In the frequency domain, the magnetic field (\mathbf{H}) can be linearly related to the electric field (\mathbf{E}) through a transfer function, known as impedance tensor (\mathbf{Z}):

$$\begin{pmatrix} E_x(\mathbf{r}, \omega) \\ E_y(\mathbf{r}, \omega) \end{pmatrix} = \begin{pmatrix} Z_{xx}(\mathbf{r}, \omega) & Z_{xy}(\mathbf{r}, \omega) \\ Z_{yx}(\mathbf{r}, \omega) & Z_{yy}(\mathbf{r}, \omega) \end{pmatrix} \begin{pmatrix} H_x(\mathbf{r}, \omega) \\ H_y(\mathbf{r}, \omega) \end{pmatrix}. \quad (1)$$

Here E_i and H_i ($i \in [x, y]$) are the North (X) and East (Y) components of electric and magnetic field variations. \mathbf{Z} depends on the angular frequency $\omega = 2\pi f$ and the position vector (\mathbf{r}). Although omitted from equation above, but all quantities also depend on distribution of the subsurface electrical conductivity $\sigma(\mathbf{r})$. Note that the reciprocal of electrical conductivity, resistivity ($\rho = 1/\sigma$), is often used interchangeably.

The complex-valued tensor elements Z_{ij} are commonly plotted in terms of their phase

$$\phi_{ij} = \tan^{-1} \left(\frac{\text{Im}(Z_{ij})}{\text{Re}(Z_{ij})} \right), \quad i, j \in [x, y]. \quad (2)$$

and apparent resistivity

$$\rho_{a,ij} = \frac{|Z_{ij}|^2}{\omega \mu_0}, \quad i, j \in [x, y], \quad (3)$$

where μ_0 is the magnetic permeability of free space $\mu_0 = 4\pi * 10^{-7}$ Vs/Am.

Information about the dimensionality and directionality of the conductivity structures can be obtained from the phase tensor (Φ) (e.g. *Caldwell et al.*, 2004):

$$\mathbf{Z} = \text{Re}(\mathbf{Z}) + \text{Im}(\mathbf{Z}) = X + iY, \quad \Phi = X^{-1}Y \quad (4)$$

The phase tensor Φ can be visualized as an ellipse, that is mathematically described by one direction (α) and three rotational invariants ($\beta, \Phi_{min}, \Phi_{max}$), where \mathbf{R} is the rotation matrix:

$$\Phi = \mathbf{R}^T(\alpha - \beta) \begin{pmatrix} \Phi_{max} & 0 \\ 0 & \Phi_{min} \end{pmatrix} \mathbf{R}(\alpha + \beta) \quad (5)$$

The tilt angle ($\alpha - \beta$) of the Φ -ellipse represents the electric strike direction at the measurement location for the respective sounding period. In case of a 2-D subsurface Φ_{min} and Φ_{max} will be parallel and perpendicular to the linearly polarized \mathbf{E} - and \mathbf{H} -fields.

Text S2. The magnetotelluric dataset of our study is a combination of different surveys conducted by ETH Zurich, the Geological Survey of Ethiopia (GSE) and the RiftVolc project, as summarized in Table S1.

Dataset	Measured by	Study	Survey Area	Average MT site spacing	Number of MT sites	Inversion
Local at Aluto	ETH Zurich & GSE	<i>Samrock et al. (2015)</i>	Grid: 5 x 15 km	0.7 km	165	ModEM 3-D: \mathbf{Z}
		<i>Cherkose and Mizunaga (2018)</i>				ModEM 3-D: \mathbf{Z}
		<i>Samrock et al. (2020)</i>				GoFEM 3-D: Φ
Regional across rift	RiftVolc Project	<i>Hübert et al. (2018)</i>	Profile: 120 km	4.3 km	25	EMILIA 2D: DET mode
Regional western rift		-	Profile: 32 km	9.6 km		4
			Profile: 51 km	12.9 km	4	-

Table S1: Information on the MT datasets analyzed in this study. MT data from the surveys of the RiftVolc project are publicly available for download (*Hübert and Whaler, 2020*) as well as ETH survey data (*Samrock et al., 2010*). Detailed information about the different inversion codes can be found in (*Kelbert et al., 2014*) (ModEM 3-D) and in (*Kalscheuer et al., 2008*) (EMILIA 2D).

Text S2.1. Following (*Rung-Arunwan et al., 2016*), we calculated SSQ-responses over N_s stations to obtain Z_{SSQ}^{1D} (Eq. 7). Further averaging Z_{SSQ}^{1D} over all periods gives a homogeneous model (\bar{Z}_{SSQ}^{1D} : Eq. 8). Starting models based on a regional 1-D SSQ-average have been proved to enable successful phase tensor inversion (e.g. *Rung-Arunwan et al., 2022*).

$$Z_{SSQ}(\mathbf{r}, \omega) = \sqrt{(Z_{xx}(\mathbf{r}, \omega)^2 + Z_{xy}(\mathbf{r}, \omega)^2 + Z_{yx}(\mathbf{r}, \omega)^2 + Z_{yy}(\mathbf{r}, \omega)^2)/2} \quad (6)$$

$$Z_{SSQ}^{1D}(\omega) = \sqrt[2]{\prod_{i=1}^{N_s} Z_{SSQ}(\mathbf{r}_i, \omega)} \quad (7)$$

$$\bar{Z}_{SSQ}^{1D} = \sqrt[2]{\prod_{i=1}^{N_p} Z_{SSQ}^{1D}(\omega_i)} \quad (8)$$

$$\rho_{a,SSQ}(\omega) = \frac{|Z_{SSQ}(\omega)|^2}{\omega \mu_0}, \quad \phi_{SSQ}(\omega) = \tan^{-1} \left(\frac{\text{Im}(Z_{SSQ}(\omega))}{\text{Re}(Z_{SSQ}(\omega))} \right) \quad (9)$$

$$\rho_{a,SSQ}^{1D}(\omega) = \frac{|Z_{SSQ}^{1D}(\omega)|^2}{\omega \mu_0}, \quad \phi_{SSQ}^{1D}(\omega) = \tan^{-1} \left(\frac{\text{Im}(Z_{SSQ}^{1D}(\omega))}{\text{Re}(Z_{SSQ}^{1D}(\omega))} \right) \quad (10)$$

$$\bar{\rho}_{a,SSQ}^{1D} = \sqrt[2]{\prod_{i=1}^{N_T} \rho_{a,SSQ}^{1D}(\omega_i)}, \quad \bar{\phi}_{SSQ}^{1D} = \sqrt[2]{\prod_{i=1}^{N_T} \phi_{SSQ}^{1D}(\omega_i)} \quad (11)$$

The apparent resistivities $\rho_{a,SSQ}$ and phases ϕ_{SSQ} obtained from Z_{SSQ} at each MT site (Eq. 9) and the corresponding regional averages over all sites ($\rho_{a,SSQ}^{1D}, \phi_{SSQ}^{1D}$ from Eq. 10) are shown in Fig. S1.

Text S2.2. Information about the penetration depth z_p of the MT signal comes from the real part of the C -response $\text{Re}(C)$, that we derived from the regional average impedance (Z_{SSQ}^{1D} , Eq. 7). The C -response is a transfer function related to the 1-D impedance by $Z^{1D} = -i\omega \mu_0 C$ and has units of metres. Following *Weidelt (1972)* and *Schmucker and Weidelt (1975)*, $2 * \text{Re}(C)$ represents a proxy for the penetration depth at a given period.

$$z_p = 2 * \text{Re} \left(\frac{-\bar{Z}_{SSQ}^{1D}}{i\omega \mu_0} \right), \quad (12)$$

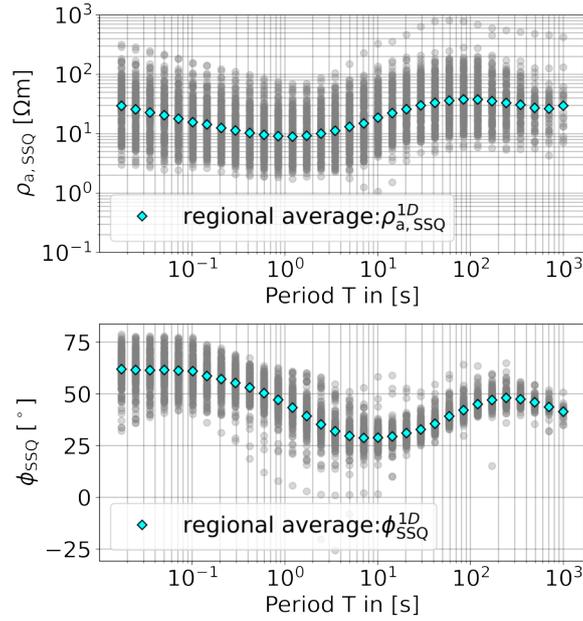


Figure S1: Apparent resistivity ($\rho_{a,SSQ}$) and phases (ϕ_{SSQ}) curves for all stations (gray) and the regional mean values (i.e., $\rho_{a,SSQ}^{1D}$ and $\phi_{a,SSQ}^{1D}$) (blue diamonds).

Additional information about the penetration depth comes from the skin depth z_s , defined as

$$z_s = \sqrt{\frac{2\rho_{a,SSQ}^{1D}}{\mu_0\omega}}. \quad (13)$$

For the periods in our dataset and for the regional mean resistivity, the penetration depth z_p is estimated to be 0.49 km for the shortest and 92.5 km for the longest sounding period (Fig. S2). For the denser station spacing at Aluto ($d_{st} = 0.7$ km), the sounding volume overlaps between neighboring sites is given at all periods, whereas outside Aluto area where site spacing is larger ($d_{st} \approx 5.9$ km), overlapping sounding volume is given at periods longer than 4.97 s.

Text S2.3. Figure S3 shows roseplot histograms of the geoelectric strike ($\alpha - \beta$) inferred from the phase tensor (Eq. 5) in the western and eastern rift part and at Aluto for different period ranges, along with the orientation from border and Wonji (WFB) faults. As can be seen, the geoelectric strike is in overall good agreement with the geological strike of the local fault systems.

The dominating geoelectric strike over all periods of the entire dataset of this study is about 0° (Fig. S4), hence we did not rotate the data prior to the inversion.

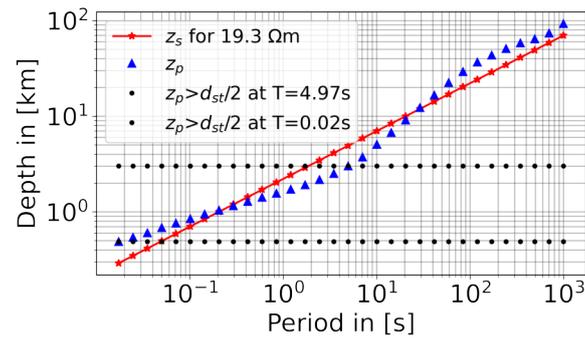


Figure S2: Period-dependent penetration depth z_p (Eq. 12) obtained from Z_{SSQ}^{1D} (Eq. 7) together with the skin depth z_s (Eq. 13) within a homogeneous halfspace of $\bar{\rho}_{a,SSQ}^{1D} = 19.25 \Omega m$. Horizontal black dotted lines in Fig. S2 mark the minimum period from which z_p exceeds the average site spacing ($d_{st}/2$, Tab S1) at Aluto (0.7 km) and in the profile arms (5.9 km). For this condition ($z_p > d_{st}/2$), sounding volumes of neighbouring stations overlap.

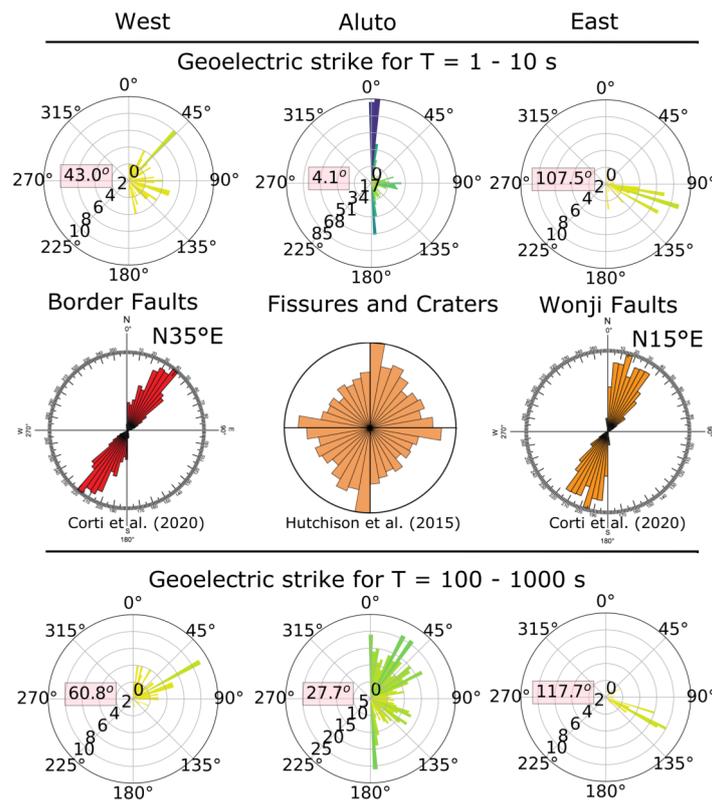


Figure S3: Roseplot histograms of the electric strike direction grouped by different areas within the survey region. Note, the geoelectric strike has a 90° ambiguity (Caldwell et al., 2004). The given angular direction of geoelectric strike corresponds to the direction with the maximum number of counts. Labelled concentric rings indicate the number of data. The geological strike directions of border faults and the WFB are from Corti et al. (Fig.7a in 2020), fissure directions and crater alignments at Aluto are from Hutchison et al. (Fig.8 in 2015).

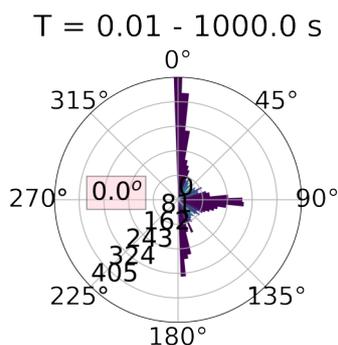


Figure S4: Roseplot histogram of the geoelectric strike ($\alpha - \beta$) inferred from the phase tensor (Eq. 5) for all stations at all frequencies. The given angular direction corresponds to the direction with the maximum number of counts. Ring lines indicate the number of data as given.

Text S3. The MT-dataset of this study clearly demands a 3-D modelling due to 3-D effects observed in the data (Fig. S5). Furthermore, the MT site distribution of our study (see main paper: Fig. 1) requires a multi-scale mesh that would account for the local and the regional site distribution as well as for the varying data resolution.

The mesh we designed for the inversion is shown in Fig. S6. The minimum cell diameters encountered in the mesh are 0.1 km around the site locations at the surface. The cell size increases away from MT stations and with depth to account for the loss of resolution.

Digital Elevation Model given by the NASA SRTM was incorporated into the mesh. This is essential in order to accurately model topography-related galvanic and inductive effects in the data (Käuffel et al., 2018).

After topography projection, we assigned a homogeneous resistivity value of $\bar{\rho}_{a,SSQ}^{1D} = 19.25 \Omega\text{m}$ (Eq. 11) to the subsurface. A data-informed starting model based on the average SSQ impedance (Eq. 10) was shown to be a good choice for data sets with galvanic distortions (Rung-Arunwan et al., 2022).

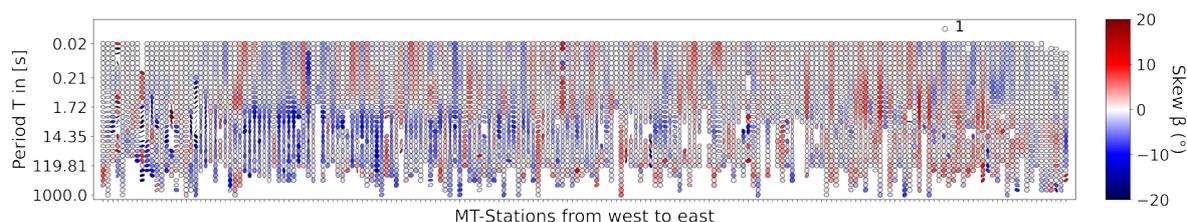


Figure S5: Phase Tensor pseudosection for all stations plotted onto a single line, across the survey area. Phase tensor ellipses were calculated from Eq.5 and are normalized by Φ_{max} . High ellipticities, rapid changes in ellipse main axis directions and high skew values (β) indicate that 3-D effects of the subsurface are present throughout the dataset.

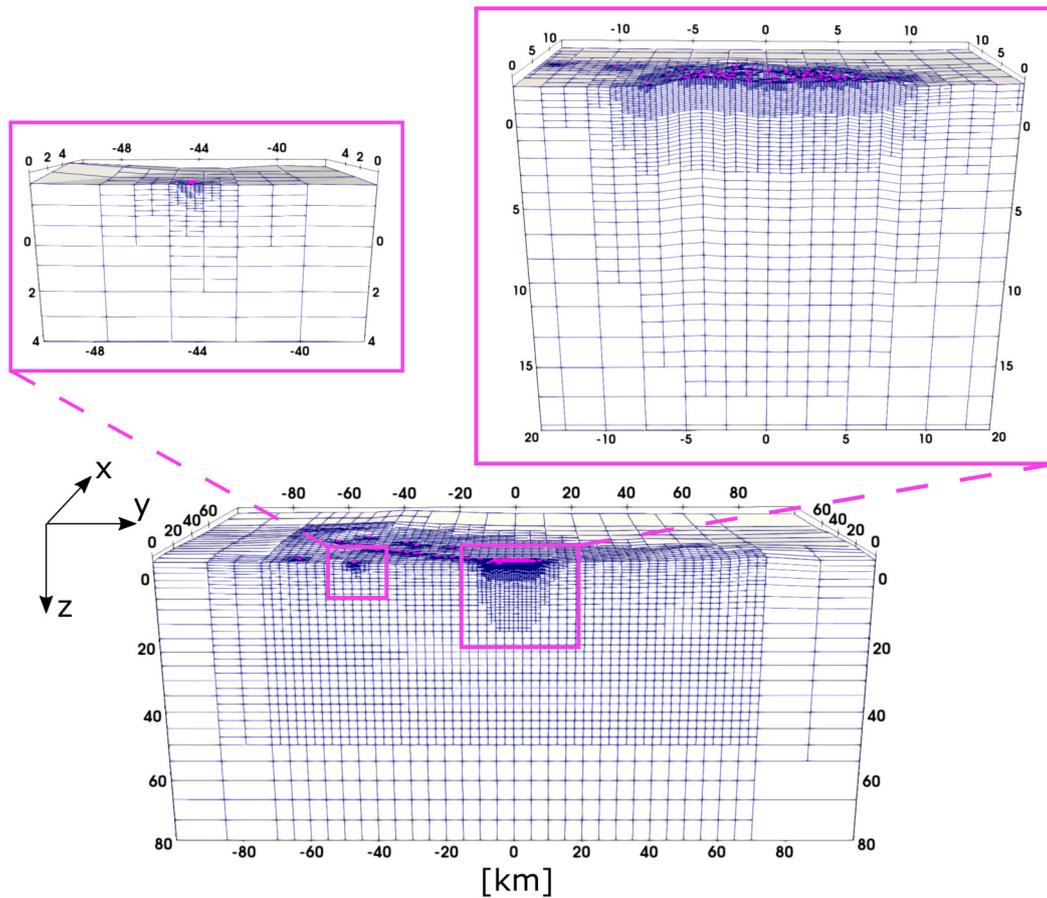


Figure S6: Mesh used in the inversions. The bottom plot shows an EW-slice through the model. The plot on the top left a zoom into a MT site at one of the profile arms, and the plot on the top right a zoom into the mesh at Aluto where a total of 165 MT stations are located. As it is standard in MT the x-axis points to the north, the y-axis to the east and the z-axis is positive downwards.

Text S4. The final model presented in the main paper (Fig. 3) was obtained using a 3-D phase tensor inversion followed by an impedance tensor inversion, whereby the phase tensor model was used as a starting model for the impedance tensor inversion. In the following we present both the phase tensor and impedance tensor models, and provide an in-depth analysis of the data fit for both models.

Text S4.1. Fig. S7 shows the final phase tensor model (corresponding impedance tensor model is shown in Fig. 3 in the main text). We see no major difference between the model in terms of the major large-scale structure. The main features we identified in the impedance tensor model appear equally clear in the phase tensor model: (C1) Aquifer unit, (C2) magma ascent channel, (R1), solidified igneous rock and (C3) lower crustal melt ponding zone.

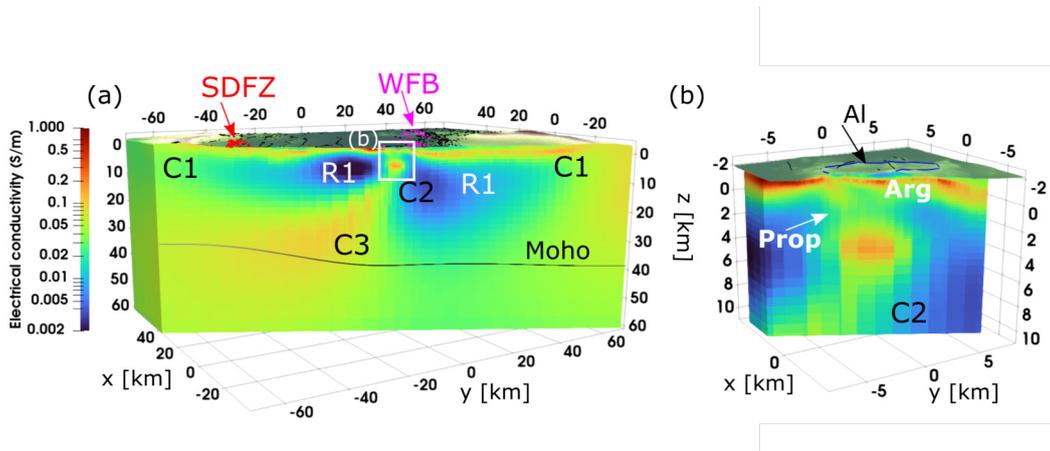


Figure S7: Model obtained from phase tensor inversion. (a) NW-SE oriented profile section, through the obtained model across the entire width of the central MER. The depth of the Moho is taken from (Stuart et al., 2006). Pink and red triangles depict WFB and SDFZ vents respectively. The white box marks the area of the Aluto-Langano geothermal system (b). (b) Close-up of the NW-SE oriented profile section beneath Aluto volcano (Al). Increased conductivities in the shallow subsurface can be attributed to the clay cap formed by argillic alteration (Arg) and higher temperature propylitic alteration (Prop).

Text S4.2. Pseudosections of the SSQ-averaged apparent resistivities (Fig. S8) and phases (Fig. S9) for the observed and the predicted data of the impedance and the phase tensor model give a qualitative impression of the data fit. Apparent resistivities are generally fitted well by both inversion models, however, absolute values of the impedance tensor model (Fig. S8b) fit the observed data (Fig. S8a) slightly better, compared to apparent resistivity values obtained from the phase tensor model (Fig. S8c). The observed phases are also well fitted by the impedance and the phase tensor model (Fig. S9).

A quantitative measure of the data fit is given by the residuals r and the root-mean-square RMS of observed F^{obs} and predicted transfer functions F^{pred} , where transfer function is either the impedance or phase tensor, depending on the data type that was inverted. The residuals r are defined as follows (see also Grayver et al., 2013):

$$r_i = \frac{F_i^{\text{obs}} - F_i^{\text{pred}}}{\delta F_i} \quad \text{with } F \in [Z, \Phi], \quad i = 1, \dots, N, \quad (14)$$

for N data. δF are the propagated data variances of the observed data with an assigned row-wise error-floor of 5% assigned to the impedance tensor as defined in (Käufel et al., 2020). Data

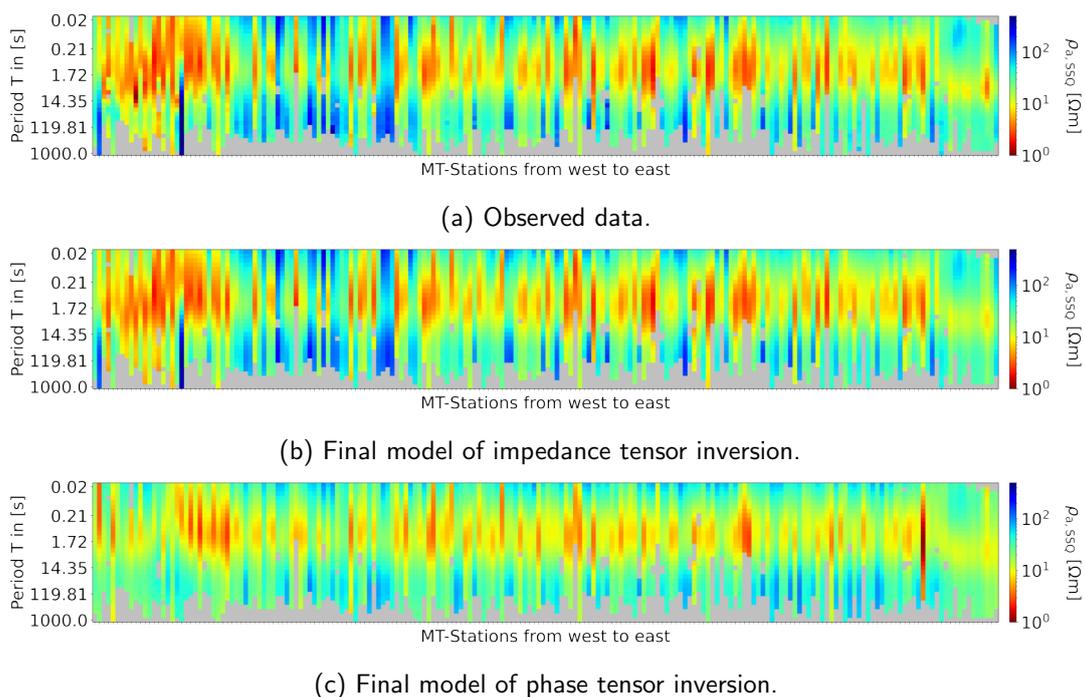


Figure S8: Observed and predicted apparent resistivities calculated from Z_{SSQ} (Eq. 6, Eq. 9) sorted from west to east and projected on the shown "pseudo-profile".

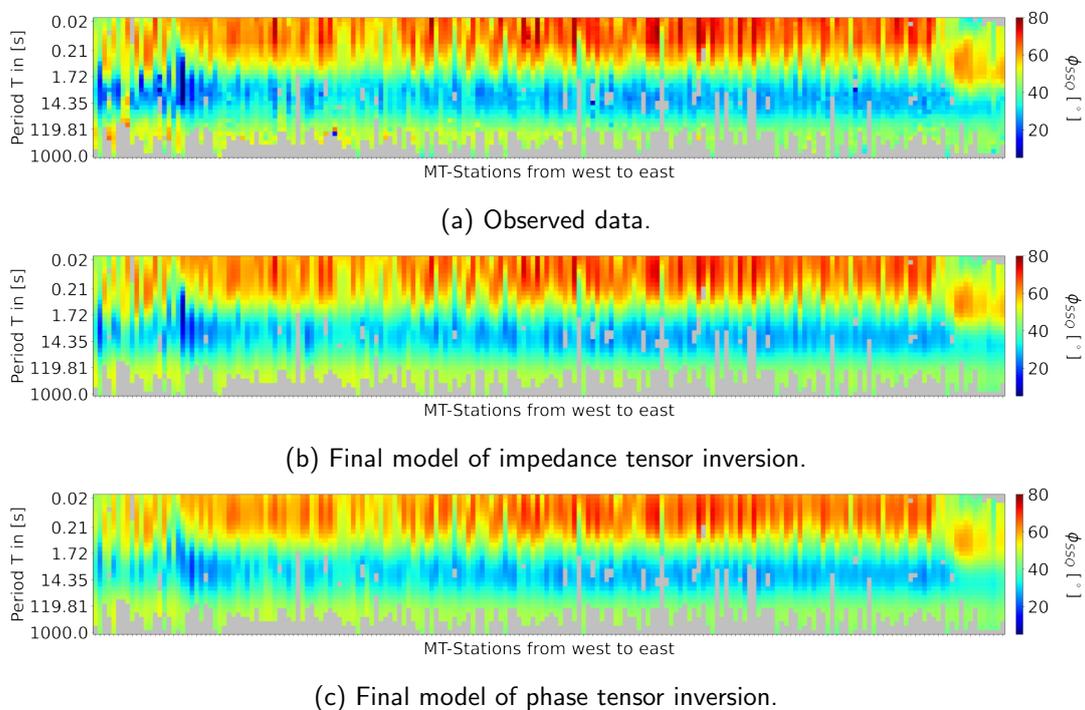
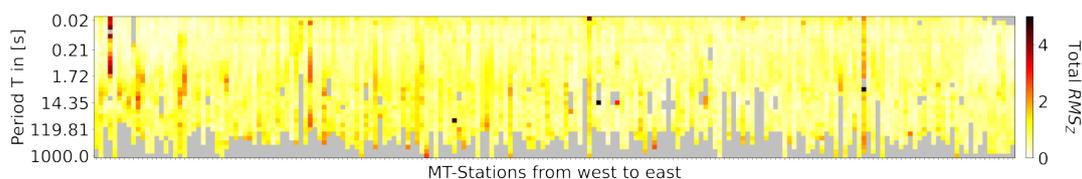


Figure S9: Observed and predicted phases calculated from Z_{SSQ} (Eq. 6, Eq. 9) sorted from west to east and projected on the shown "pseudo-profile".

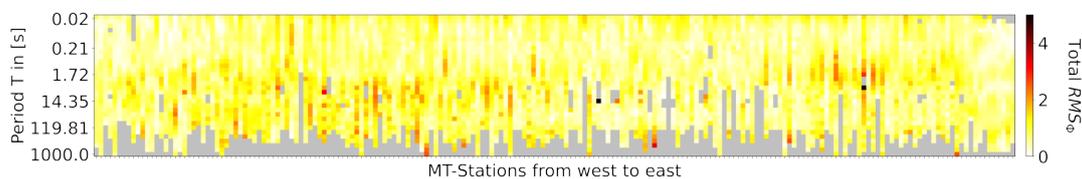
uncertainties of the phase tensors were obtained by error propagation from the impedance tensor. The RMS is defined as follows:

$$\text{RMS} = \sqrt{\frac{1}{N} \sum_{i=1}^N r_i^2} \quad (15)$$

Pseudosections of the RMS-value calculated for all modelled frequencies at all MT-sites are presented for the impedance (Fig. S10a) and the phase tensor (Fig. S10b) models. Both models achieve a good data fit with ($\text{RMS} \leq 1$) meaning that all data are fitted within the error bounds at nearly all stations and at all periods.



(a) RMS of the impedance tensor model.



(b) RMS of the phase tensor model.

Figure S10: Achieved RMS of impedance tensor model (a) and phase tensor model (b) presented as pseudosections per MT site and period. Note, that the RMS is always calculated for the respective transfer function used for the inversion (Eq. 14).

Another approach to assess the quality of the fit are crossplots of observed and predicted data (Fig. S11). These crossplots would show a systematic mismatch between observed and predicted data, if a systematic bias exists. Both, apparent resistivities and phase tensor elements, are actually better fitted by the final impedance tensor model (Fig. S11a, Fig. S11b) than by the phase tensor model (Fig. S11c, Fig. S11d). Apparent resistivities calculated from the phase tensor model (Fig. S11c) are less well fitted, reflecting galvanic distortions that are not accounted for in the phase tensor model (see Text S4.3.). It can also be seen that diagonal components of the phase tensor $\Phi_{xx,yy}$ with small magnitudes are generally underestimated (see Fig. S11d).

We conclude that the final impedance tensor model shows an overall good fit of both observed impedance and phase tensors and no systematic mismatch or bias in the data.

Text S4.3. The observed difference in impedance data fit between the final impedance tensor model and the phase tensor model (Fig. S11) is anticipated because: (1) absolute electrical conductivity values are less well constrained in phase tensor inversions compared to impedance tensor inversion (e.g. *Rung-Arunwan et al., 2022; Tietze et al., 2015*) and (2) the impedance tensors are affected by galvanic distortion, hence the inversion process introduces strong near surface heterogeneities in order to fit distorted responses. This leads to a wider distribution of electrical conductivities recovered by the final impedance tensor model compared to the phase tensor model as illustrated in Fig. S12.

Plane view plots of the surface from both models show that the final impedance tensor model shows a more scattered shallow conductivity structure compared to the phase tensor model (Fig. S13). However, the median of recovered conductivities in both models is identical (Fig. S12). This indicates

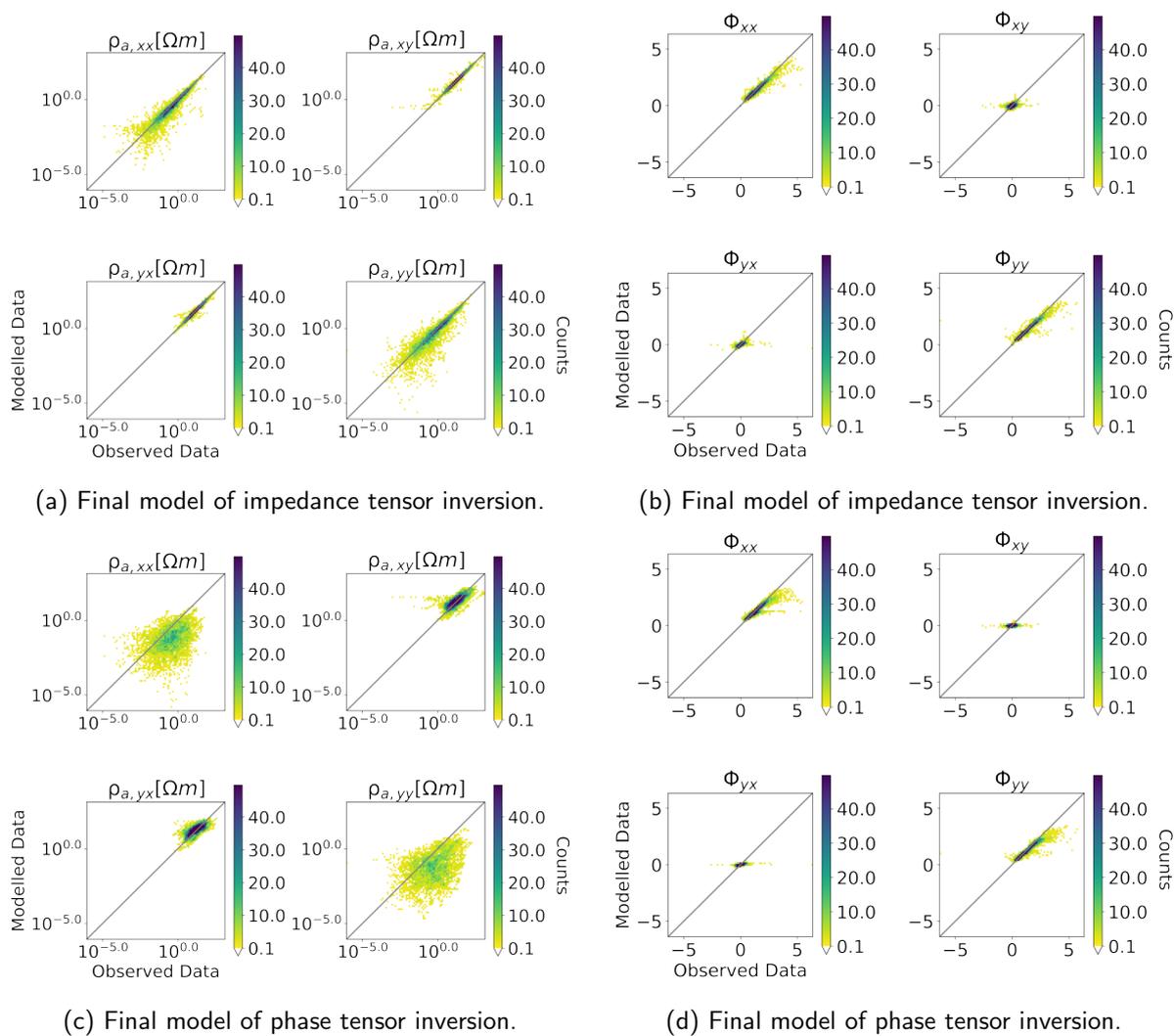


Figure S11: Data count crossplots comparing the observed with the predicted apparent resistivity and phase tensors. The gray diagonal line indicates the theoretical distribution for a perfect fit.

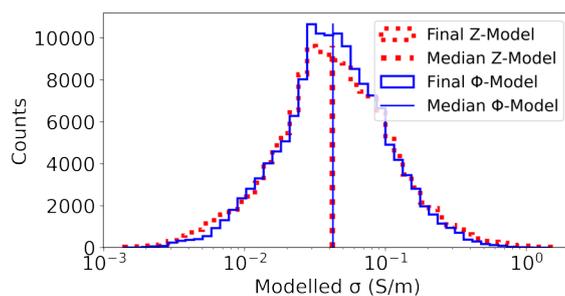


Figure S12: Histogram of predicted conductivities in the final impedance and phase tensor inversion models. Counts refer to the numbers of cells in the mesh with the respective conductivity.

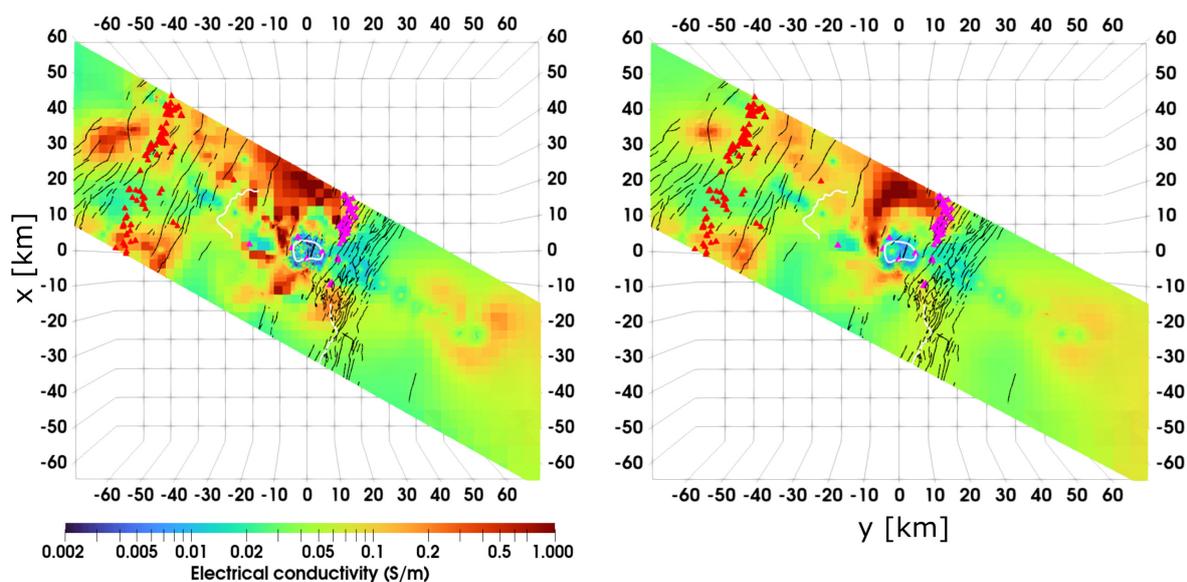


Figure S13: Birdview of the surface from the final model obtained from (a) impedance tensor inversion and from (b) phase tensor inversion. Black lines are fault systems and white lines caldera rims. Triangles are vents in the WFB (magenta) and SDFZ (red).

two important findings: (1) recovered conductivities by the phase tensor inversion are generally in the correct range and (2) impedance tensor inversion only introduces longer tails in the distribution of recovered electrical conductivities, which is due to a need to fit galvanically distorted impedances.

Text S5. The interpretation of recovered electrical conductivities σ_{bulk} in terms of fractions of individual phases present in the considered bulk volume requires knowledge of their electrical conductivities and their degree of connectedness. Magmatic reservoirs and fluid saturated rock are typically described as two-phase systems consisting of a homogeneous rock matrix with conductivity σ_2 and a conducting phase with conductivity σ_1 , which is e.g. fluid or magma. For a fully saturated rock, the fraction of the conducting phase χ_1 will be equal to the porosity $\chi_1 = 1 - \chi_2$.

These considerations are summarized in the modified Archie's law by (Glover et al., 2000):

$$\sigma_{bulk} = \sigma_1(1 - \chi_2)^p + \sigma_2\chi_2^m \quad \text{with} \quad p = \frac{\log(1 - \chi_2^m)}{\log(1 - \chi_2)}. \quad (16)$$

The degree to which the conducting phase with σ_1 contributes to the bulk electrical conductivity σ_{bulk} depends on its degree of connectedness. A geometrical description of the degrees of connectedness is contained in the cementation component m , which generally increases with the degree of connectedness (Glover, 2009). Examples for cementation exponent estimates of end-member geometries are $m = 1$ for a matrix with pores as parallel tubes, $m = 1.5$ for pores in a matrix of closely packed perfect spheres (Sen et al., 1981; Mendelson and Cohen, 1982), or $m = 1.15$, which approximates the upper Hashin-Shtrikman bound (Hashin and Shtrikman, 1962) and corresponds to the brick-layer model (e.g. Glover, 2015).

Text S5.1. In order to relate σ_{bulk} within C3 with basaltic magmatic melt fractions the electrical conductivity of the melt needs to be known under the prevailing conditions. Parameters that predominantly control the electrical conductivity of melt are melt composition, pressure, temperature and the amount of dissolved water within the melt. Estimations of these properties as they are expected to prevail within the lower magmatic ponding zone C3 are summarized in Table S2.

Ni et al. (2011) provides an empirical model that describes the electrical conductivity of basaltic melt for a varying temperature range of $\mathcal{T} = 1200 - 1650^\circ\text{C}$ and water content of $c_{H_2O}^{melt} = 0.02 - 6.3 \text{ wt}\%$, at a fixed pressure of $P=2 \text{ GPa}$ (Eq. 17).

$$\log(\sigma) = 2.172 - \frac{860.82 - 204.46\sqrt{c_{H_2O}^{melt}}}{\mathcal{T} - 1146.8} \quad (17)$$

$$\text{for } \mathcal{T} = 1200 - 1650^\circ\text{C}, \quad c_{H_2O}^{melt} = 0.02 - 6.3 \text{ wt}\%, \quad P = 2 \text{ GPa}$$

Note, we extrapolated Eq. 17 to lower pressures of $P=1 \text{ GPa}$ at $\mathcal{T} > 1300^\circ\text{C}$. This is justified according to a study from Tyburczy and Waff (1983), who have shown that the influence of pressure on the electrical conductivity can be neglected in this $P - \mathcal{T}$ -range. A pressure of 1 GPa is equivalent to an estimated lithostatic depth of 36.6 km (Fig. S14) which corresponds to depths of C3 (see e.g. Fig. S7). In accordance with reported conditions from previous studies (Tab. S2) we estimate melt electrical conductivity for a temperatures of $\mathcal{T} = 1300 - 1400^\circ\text{C}$ and water contents of $c_{H_2O}^{melt} = 0.5 - 1 \text{ wt}\%$. Reported water solubility for parental basaltic melt is $c_{H_2O}^{melt} \leq 1 \text{ wt}\%$ (Field et al., 2013), which is well in the range of maximum water solubility calculated using MagmaSat (max: $c_{H_2O}^{melt} = 6.7 \text{ wt}\%$) (Ghiorso and Gualda, 2015) for a quaternary basalt collected from a scoria cone NE of Aluto (sample 17-01-05 from Gleeson et al., 2017). Under these conditions electrical conductivities of basaltic melt will lie within $\sigma_2 = 2.86 - 8.41 \text{ S/m}$ (Fig. S15a).

Using modified Archie's law (Eq. 16) we estimated melt fractions for two different cementation exponents ($m = 1.15, 1.5$) and the minimum and maximum electrical conductivity of basaltic melt $\sigma_2 = 2.86 - 8.41 \text{ S/m}$ (see Fig. S15a). The observed bulk electrical conductivity for the conductor C3 is $\sigma_{bulk} = 0.1 - 0.18 \text{ S/m}$ and the electrical conductivity of the surrounding matrix is assumed to be $\sigma_1 = 0.02 \text{ S/m}$. This results in melt fraction of 1.8 - 7.1 vol.% and 4.5 - 14.7 vol.% for maximum and minimum basaltic melt conductivities respectively (Fig. S15b).

Property	Value	Method	Region	Study
Temperature [°C]	1125-1200	Basaltic melt composition related to T and P	MER	<i>Ayalew et al. (2016)</i>
	1400-1460	PRIMELT-2: obtain primary melt composition and temperature	MER	<i>Rooney et al. (2012)</i>
Pressure [GPa]	1.01-1.24	Basaltic melt composition related to T and P	MER	<i>Ayalew et al. (2016)</i>
	1.5-2.5	Back-correct major element compositions of basalt to Mg#72	MER: Debre Zeyit	<i>Rooney et al. (2005)</i>
Water content [wt%]	0.5 at 0.15 GPa	Thermodynamic modelling with MELTS	MER: Aluto	<i>Gleeson et al. (2017)</i>
	1.0 at 0.1 GPa	Thermodynamic modelling with MELTS	MER: Boseti, Gedemsa	<i>Peccerillo et al. (2003), Ronga et al. (2010)</i>
	0.4-1.0 at 430 MPa	SiO ₂ Harker diagrams of experimental vs. measured major elements	NMER: Dabahu volcano, Afar	<i>Field et al. (2013)</i>
Partial melt [vol.%]	2-7	Numerical modelling for seismic wave velocities	MER uppermost mantle	<i>Hammond and Kendall (2016)</i>
	3-5	P-wave velocity equivalent to study by <i>Mechie et al. (1994)</i>	MER low mantle	<i>Mackenzie et al. (2005)</i>
	2	Relation of shear wave velocity reduction to melt fraction from <i>Hammond and Humphreys (2000)</i>	MER low mantle	<i>Chambers et al. (2019)</i>
	≤ 0.6	Relation of shear wave velocity reduction to melt fraction from <i>Hammond and Humphreys (2000)</i>	MER mantle	<i>Gallacher et al. (2016)</i>
	13	MT study, melt estimation using SIGMELTS	Afar region	<i>Desissa et al. (2013)</i>
	≤ 7	Back-correlated FeO* and SiO ₂ contents	MER (DZBJ) Parental mantle melt	<i>Rooney et al. (2005)</i>

Table S2: Summary of the results from past studies that constrained prevailing conditions for parental magma generation in the MER. Please note that this list is not comprehensive.

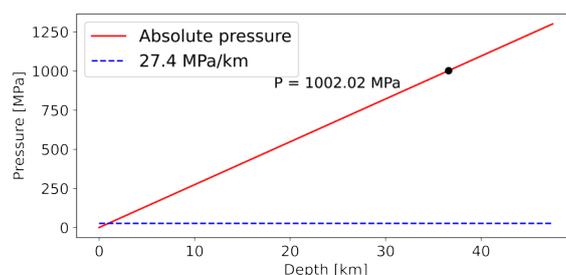


Figure S14: Pressure calculated for a continental crust with 2625 kg/m³ in a depth of 0-2.5 km and 2800 kg/m³ for greater depth. These assumptions were reported by *Gleeson et al. (2017)*.

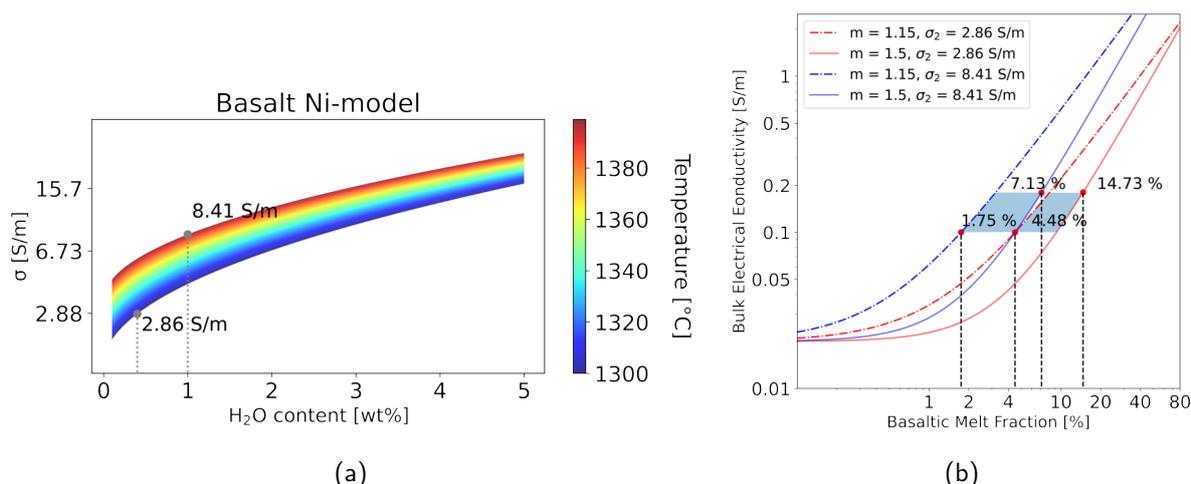


Figure S15: (a) Estimation of σ of basaltic melt after *Ni et al. (2011)* for the given temperature and water content range. (b) Estimation of melt fractions based on the observed bulk electrical conductivities in the lower crustal magma ponding zone using modified Archie's law (Eq. 16). The coloured patches mark the area of observed $\sigma_{bulk} = 0.1 - 0.18$ S/m in the conductor (C3).

Text S5.2. C1 is a prominent electrical conductor that extends at shallow depth over the entire width of the rift (see e.g. Fig. S7). In agreement with the conceptual hydrogeological model of the area by (Ghiglieri et al., 2020) C1 can be interpreted as a fully saturated aquifer system within pyroclastics (ignimbrites) and basalts, where water from the rift shoulders flows into the rift valley.

To verify the interpretation of C1 as an aquifer system with dominating observed bulk conductivities $\sigma_{bulk} = 0.1 - 0.2 \text{ S/m}$ we use modified Archies law (Eq. 16) to estimate the required water fraction within C1. The estimated regional mean electrical conductivity of groundwater is $\sigma_2 = 0.3 \text{ S/m}$ (Fig. S16a).

For the host rock conductivity we assigned $\sigma_1 = 0.05 \text{ S/m}$, which is equivalent to the surrounding rock matrix. The cementation exponent was chosen to be $m = 2.0$, which is in the range of values for sedimentary rocks in upper crustal basins (Glover et al., 2000). Similarly to the estimation of the melt fraction, calculation for estimating the water fraction were performed using Eq. 16. Figure S16b shows that a water fraction of 45–79 vol.% would be necessary to explain the observed bulk electrical conductivity of $\sigma_{bulk} = 0.1 - 0.2 \text{ S/m}$. However, such high porosities are unrealistic for a compacted pyroclastic rock (Fig. 6 in Colombier et al., 2017; Sruoga et al., 2004).

Hence, the predicted electrical conductivities cannot be solely explained by ionic conduction in fluid-saturated volcanic rock and suggest that the electrical conductivity of the rock matrix is higher than the assumed $\sigma_2 = 0.05 \text{ S/m}$, possibly due to the presence of electrically conductive clays that form through weathering of ignimbrites.

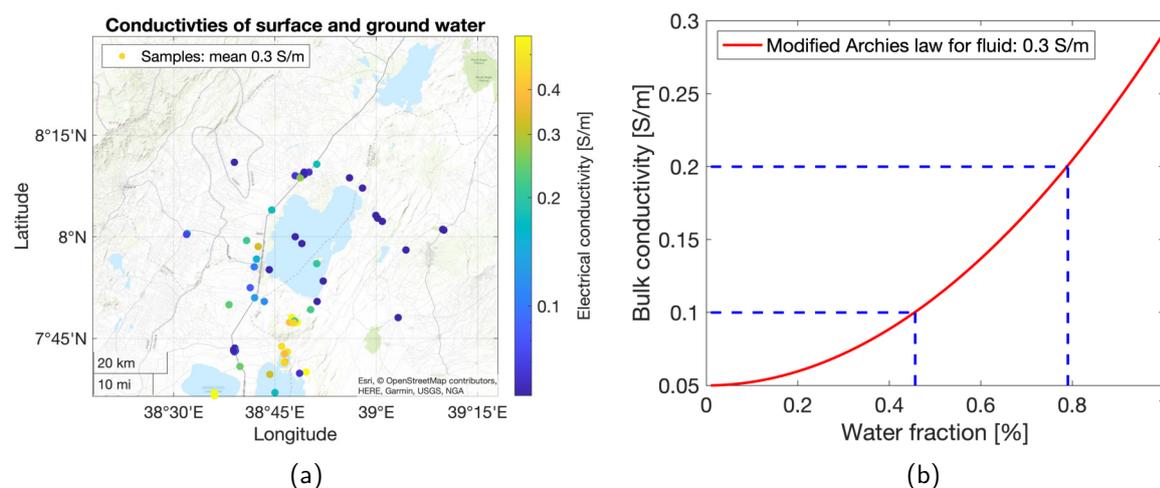


Figure S16: (a) A selection of measured electrical conductivities in the field of surface and groundwaters in the study area, taken from the database of (Burnside et al., 2021). (b) Water fraction present in C1 calculated from the modified Archie's law.

Movie S1. Animation showing a moving profile slice through the final impedance tensor model along with a 0.1 S/m isosurface, that delineates the lower crustal magma ponding zone (C3) and the magma ascent channel (C2), which terminates beneath Aluto volcano. The animation blends into the conceptual model of the central MER also shown in Fig. 6 of the main paper (video file uploaded separately).

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